

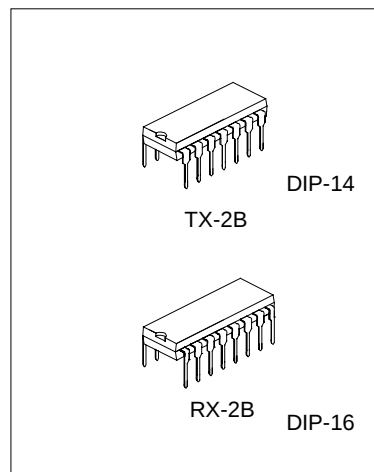
REMOTE CONTROLLER WITH FIVE FUNCTIONS

DESCRIPTION

The TX-2B/RX-2B is a pair of CMOS LSIs designed for remote controlled car applications. The TX-2B/RX-2B has five control keys for controlling the motions (i.e. forward, backward, rightward, leftward and the turbo function) of the remote controlled car.

FEATURES

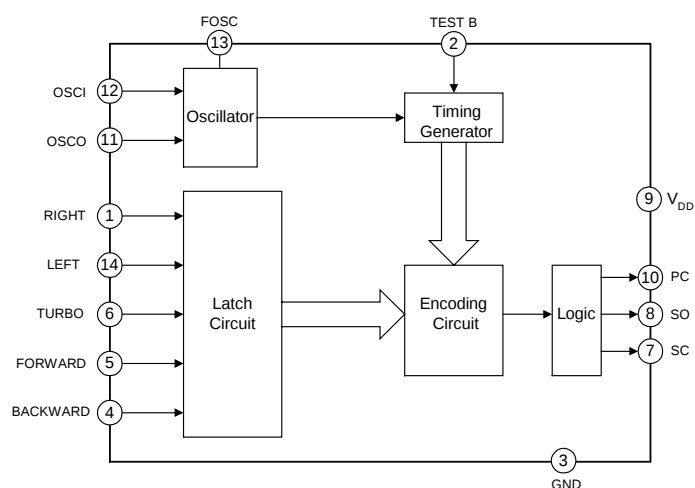
- * Wide operating voltage range ($V_{CC}=1.5\sim 5.0V$)
- * Low stand-by current
- * Auto-power-off function for TX-2B
- * Few external components are needed



ORDERING INFORMATION

Part No.	Package
TX-2B	DIP-14-300-2.54
RX-2B	DIP-16-300-2.54

BLOCK DIAGRAM



TRANSMITTER TX-2B Block Diagram

The block diagram illustrates the control system for a four-wheeled mobile robot. It features a power supply section with pins 13 (V_{DD}), 2 (GND), 1 (VO2), 16 (VI2), 8 (RDB), 9 (LDB), 14 (VI1), and 15 (VO1). The control logic section includes an Oscillator (pins 4 OSCI, 5 OSCO), Timing Generator, Decoding Circuit, Computer, PLA, and Latch Circuit. The Latch Circuit outputs to pins 6 (RIGHT), 7 (LEFT), 12 (TURBO), 10 (BACKWARD), and 11 (FORWARD).

RECEIVER RX-2B Block Diagram

The image contains two pinout diagrams for the TX-2B and RX-2B modules. The TX-2B diagram shows a 14-pin connector with pins 1-7 on the left and 8-14 on the right. The RX-2B diagram shows a 16-pin connector with pins 1-8 on the left and 9-16 on the right. Both diagrams include a central ground pin (pin 3 for TX-2B, pin 2 for RX-2B) and a power pin (pin 9 for TX-2B, pin 13 for RX-2B).

Pin	TX-2B Function	Pin	RX-2B Function
1	RIGHT	1	VO2
2	TEST	2	GND
3	GND	3	SI
4	ACKWARD	4	OSCI
5	FORWARD	5	OSCO
6	TURBO	6	RIGHT
7	SC	7	LEFT
8	SO	8	ROB
9	VDD	9	LDB
10	PC	10	BACKWARD
11	OSCO	11	FORWARD
12	OSCI	12	TURBO
13	FOSC	13	VDD
14	LEFT	14	VI1
		15	VO1
		16	VI2

ABSOLUTE MAXIMUM RATINGS

Characteristic	Symbol	Value	Unit
Supply Voltage	VDD	0.3~5.0	V
Input / Output Voltage	VIN, VOUT	GND-0.3~VDD+0.3	V
Operating Temperature	TOPR	-10~65	°C
Storage Temperature	Tstg	-25~125	°C

ELECTRICAL CHARACTERISTICS

1. TX-2B (VDD=4.0V, Fosc=128KHz, Tamb=25°C, unless otherwise specified.)

Characteristic	Symbol	Min	Typ	Max	Unit
Operating Voltage	VDD	1.5	4.0	5.0	V
Operating Current	IDD	--	--	2.0	mA
Stand-By Current	ISTB	--	--	10	μA
DC O/P Driving Current	Idrive	5	--	--	mA
AC O/P Driving Current	Idrive	5	--	--	mA
AC O/P Frequency	Faudio	0.5	--	1.0	kHz

2. RX-2B (VDD=4.0V, Fosc=128KHz, Tamb=25°C, unless otherwise specified.)

characteristic	Symbol	Min	Typ	Max	Unit
Operating Voltage	VDD	1.5	4.0	5.0	V
Operating Current	IDD	--	--	3.0	mA
O/P Driving Current	Idrive	1	--	--	mA
O/P Sinking Current	Isink	1	--	--	mA
Effect Decoding Frequency Variation	Ftolerance	-20	--	20	%

PIN DESCRIPTION

1. TX-2B

Pin No.	Symbol	Description
1	RIGHT	The rightward function will be selected, if this pin is connected to GND
2	TEST	This pin is used for testing mode
3	GND	Negative power supply
4	BACKWARD	The backward function will be selected, if this pin is connected to GND
5	FORWARD	The forward function will be selected, if this pin is connected to GND

(To be continued)

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Rev: 1.0 2002.03.29

(Continued)

Pin No.	Symbol	Description
6	TURBO	The turbo function will be selected if this pin is connected to GND
7	SC	Output pin of the encoding signal with carrier frequency
8	SO	Output pin of the encoding signal without carrier frequency
9	VDD	Positive power supply
10	PC	Power control output pin
11	OSCO	Oscillator output pin
12	OSCI	Oscillator input pin
13	FOSC	This pin is used for testing mode
14	LEFT	The leftward function will be selected, if this pin is connected to GND

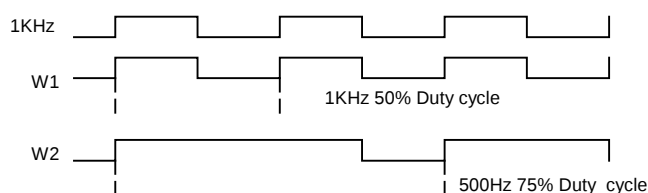
2. RX-2B

Pin No.	Symbol	Description
1	VO2	Inverter 2 output pin for power amplify
2	GND	Negative power supply
3	SI	Input pin of the encoding signal
4	OSCI	Oscillator input pin
5	OSCO	Oscillator output pin
6	RIGHT	Rightward output pin
7	LEFT	Leftward output pin
8	ROB	Rightward function disable, if this pin is connected to GND
9	LDB	Leftward function disable, if this pin is connected to GND
10	BACKWARD	Backward output pin
11	FORWARD	Forward output pin
12	TURBO	TURBO output pin
13	VDD	Positive power supply
14	VI1	Inverter 1 input pin for power amplify
15	VO1	Inverter 1 output pin for power amplify
16	VI2	Inverter 2 input pin for power amplify

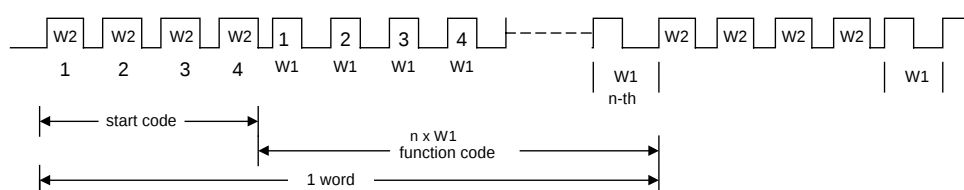
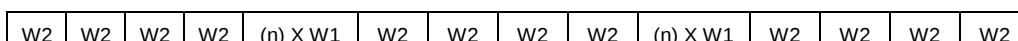
CODE FORMAT

1. ENCODE RULE

(A).Bit Format (W1 is used for function codes,W2 for start codes)

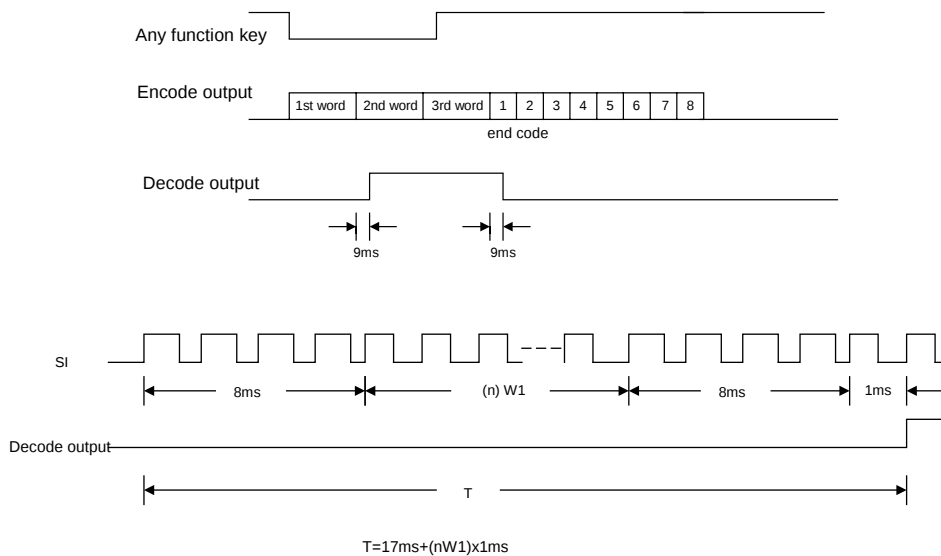


(B).Data Format



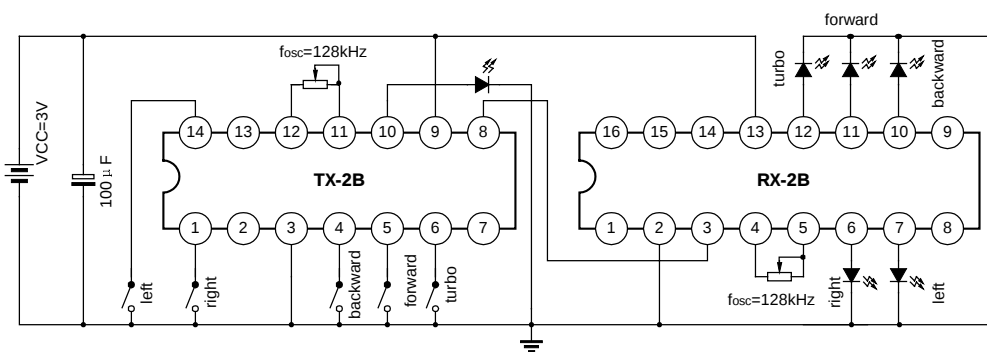
Number Of Function Code (N) W1	Function Key	Decode Result
4		End Code
10	Forward	Forward
16	Forward & Turbo	Forward
22	Turbo	Turbo
28	Turbo & Forward & Left	Forward & Left
34	Turbo & Forward & Right	Forward & Right
40	Backward	Backward
46	Backward & Right	Backward & Right
52	Backward & Left	Backward & Left
58	Left	Left
64	Right	Right

2. ENCODE/DECODE TIMING



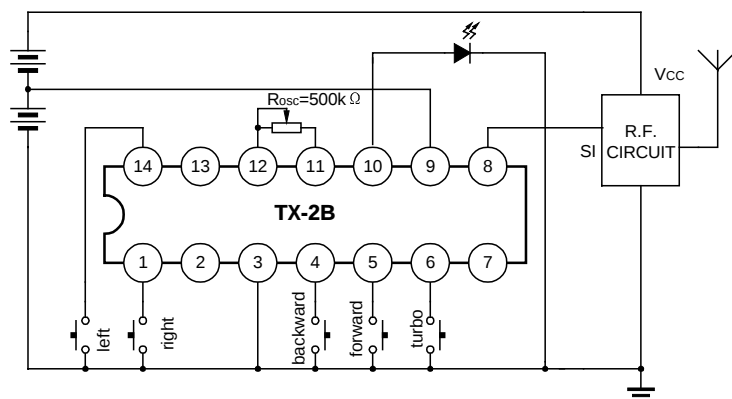
TESTING CIRCUIT

(The oscillator frequency of TX-2B, RX-2B is 128KHz, the oscillator resistor is 160KΩ and 250KΩ respectively)

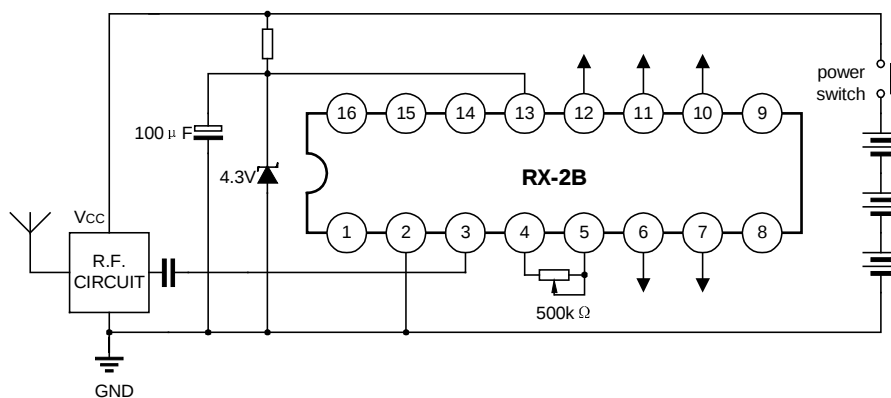


TYPICAL APPLICATION CIRCUIT

TRANSMITTER

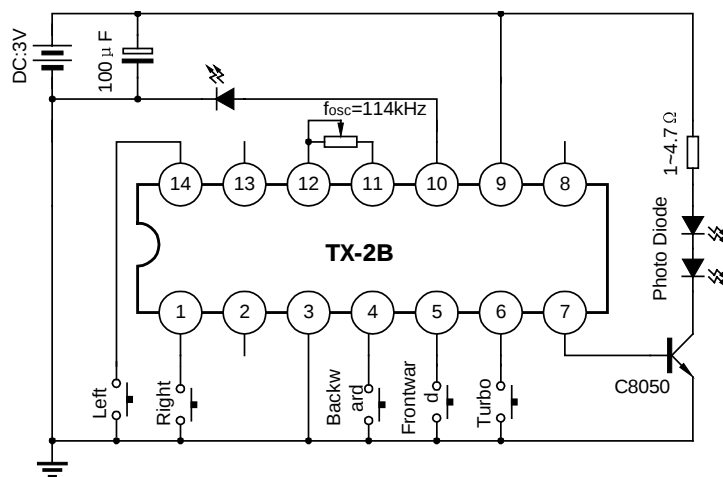


RECEIVER

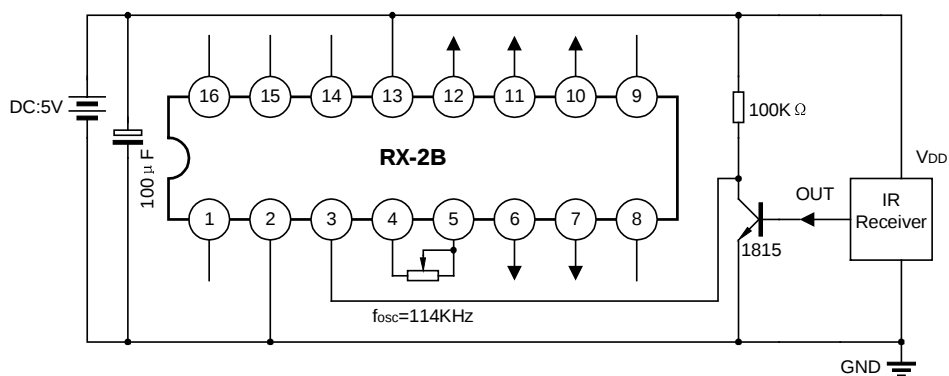


INFRARED APPLICATION CIRCUIT

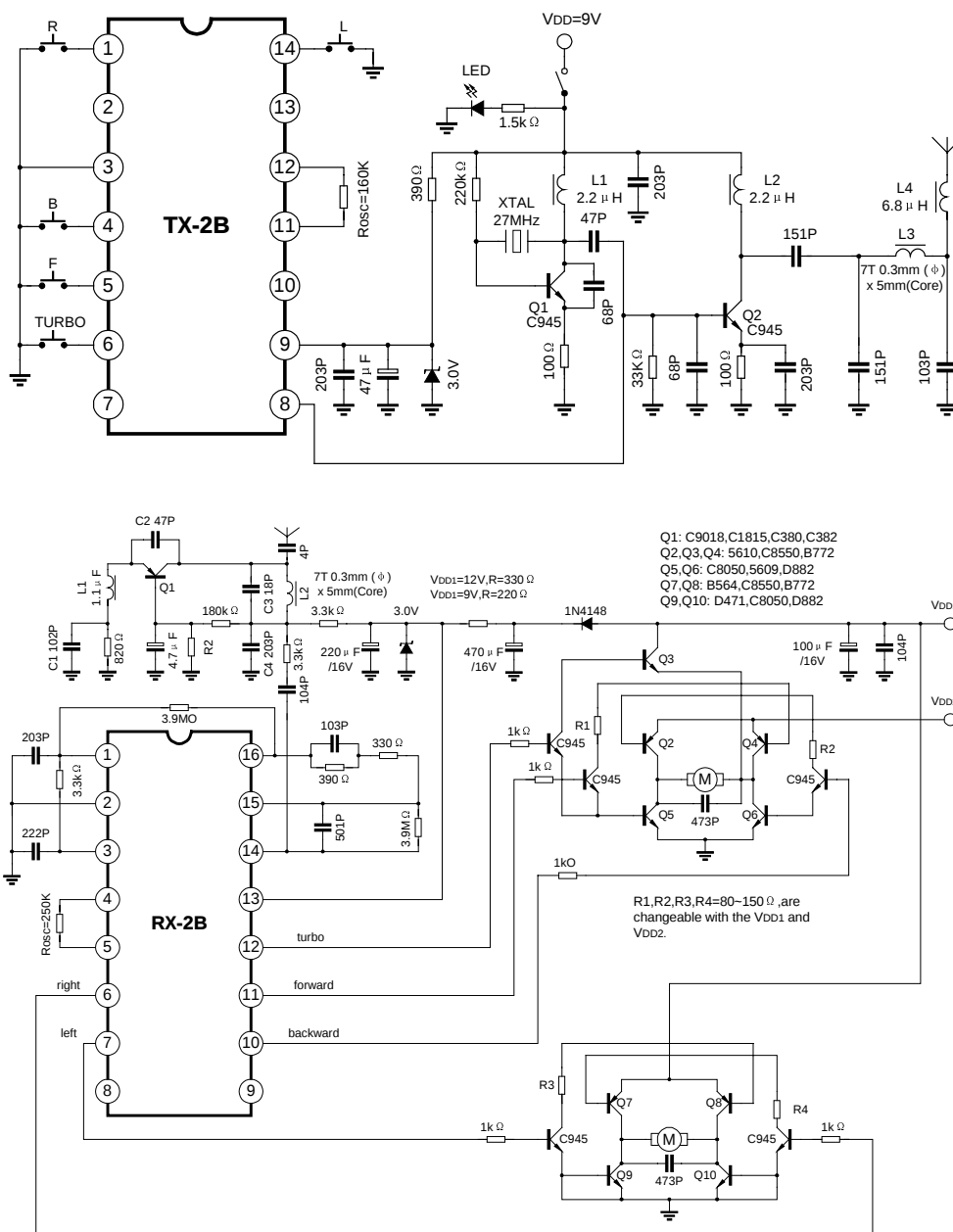
TRANSMITTER



RECEIVER



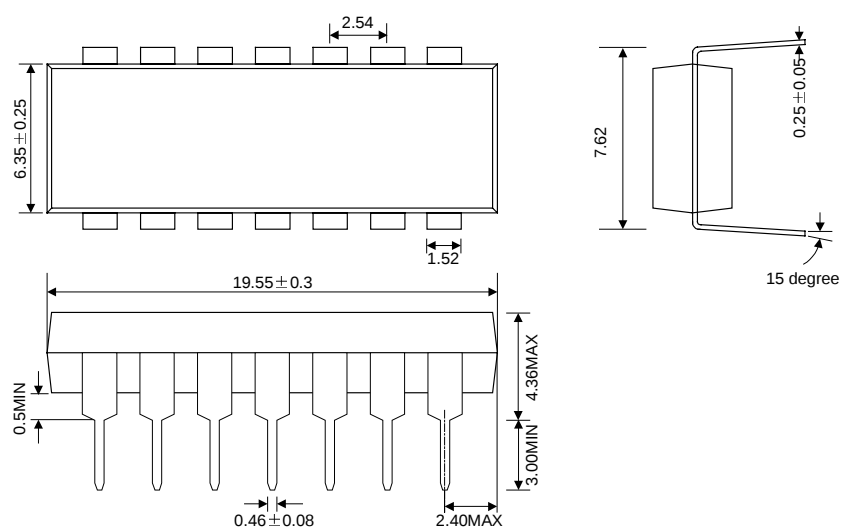
RECOMMENDED APPLICATION CIRCUIT



PACKAGE OUTLINE

DIP-14-300-2.54

UNIT: mm



DIP-16-300-2.54

UNIT: mm

