

AN220

Watt-Hour Meter using PIC16C923 and CS5460

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OVERVIEW

This application note shows how to use a PIC16C923 microcontroller to control operation of the CS5460 power measurement integrated circuit from Cirrus Logic®/Crystal Power Measurement, to drive a liquid crystal panel ("glass"), and to store and retrieve data using the 24C01 Serial EEPROM.

Energy transferred between the line and load is measured by the CS5460. The PIC16C923 initializes the CS5460 with calibration data stored in the 24C01 Serial EEPROM, records the total energy measured in the 24C01, and displays results on the LCD panel.

INTRODUCTION

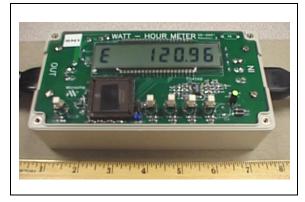
Most forms of AC power measurement have already been patented by various companies, so measuring AC power in a product intended for sale often involves paying licensing fees to another company. The CS5460 offers an integrated solution that provides a power and energy measurement sub-system, requiring only voltage and current sense inputs. In addition, calibration is accurate for any current waveform or power factor that may be encountered.

By using the CS5460, a PIC16C923 microcontroller, a 24C01 Serial EEPROM, and an LCD panel, a simple and compact device is constructed that displays RMS voltage, RMS current, and the energy consumed by a load. These features are extended by including computation and display of apparent power, true power, and power factor.

The PIC16C923 LCD controller can drive an LCD panel with up to 4 common planes and up to 32 segments. 4K words of program memory, and 176 bytes of RAM are provided. A Synchronous Serial Peripheral (SSP) provides SPI^{TM} communications with the CS5460. Inter-Integrated CircuitTM (I^2C) communications with the 24C01 Serial EEPROM are provided by firmware.

The CS5460 power/energy measurement IC measures instantaneous voltage and current four thousand times a second and uses these measurements to compute VRMS, IRMS, instantaneous power, and accumulated energy results for read out. In addition, a pulse is generated whenever a user specified amount of energy transfers between the line and the load.

FIGURE 1: WATT-HOUR METER



HARDWARE

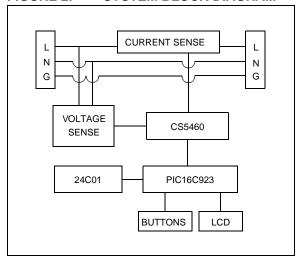
On power-up, the PIC16C923 microcontroller reads the calibration data, device serial number, and total energy from the 24C01, writes the calibration data to the CS5460, initializes the CS5460, and reads the state of the control buttons.

If the control button state matches one of three patterns at RESET, a control mode is entered that allows setting the real time clock (RTC), clearing the total WHr and restoring default calibration values, or adjusting calibration constants.

During normal operation, the PIC16C923 counts pulses from the CS5460, reads CS5460 data registers, drives the LCD panel to display the requested data, and monitors the control buttons. The pulses are used to update the total energy count and are periodically written to the 24C01.

The CS5460 measures line voltage and line current to compute power and energy transferred on the line. When a unit of energy has transferred between the line and the load, a pulse with direction indication is generated.

FIGURE 2: SYSTEM BLOCK DIAGRAM



CS5460 Power/Energy Measurement Circuit

The CS5460 measures the instantaneous line voltage and line current, four thousand times a second. These measurements are used to compute instantaneous power, energy transferred since the last measurement, RMS voltage, RMS current, and accumulated energy transferred. All measurements and results can be read by an external controller, via the SPI interface. A transfer of energy is also indicated by a pulse output at the EOUT pin. The direction of transfer is indicated by the EDIR pin.

Communication with the CS5460 takes place over a 4-wire SPI link with the PIC16C923. The CS5460 is configured and controlled over this link. Calculation results are also read by the controller over this link.

The line voltage may be sampled using a transformer or resistor divider. The differential input is limited to 150mVRMs. In this application, line voltage is detected from the secondary winding of the power supply transformer, T2 (see Figure 3B and Figure 5). When operating from 120V, there is about an 8V peak at VIN+ or VIN-. When operating from 220V, there is about a 14.7V peak. This voltage is further reduced by a resistor network before being applied to the CS5460 (see Figure 4A).

The line current may be sampled using a current transformer or shunt resistor. Depending on the gain of the input channel, the differential input is limited to either 30 mVRMs (gain = 50), or 150 mVRMs (gain = 10). In this application, the current channel gain is 10, for a maximum input voltage of 150 mVRMs. This voltage is provided by the current sense transformer T1 and resistor R21, and is reduced by a resistor network similar to the line voltage channel (see Figure 3A and Figure 4B).

There is no switching provided, or required for operation from either 120V or 220V, 50Hz or 60Hz. However, accuracy will decrease when operating from a line voltage different than the calibration conditions.

By using the instantaneous voltage and current, the CS5460 computes the RMS voltage, RMS current, and instantaneous power. The instantaneous power is integrated at the sampling rate (4000Hz) to compute the energy transferred. A new RMS value is available every 4000 samples. Samples are taken 4000 times per second, or about 67 times per 60Hz cycle.

When the integrated energy exceeds 10 WSec, a fixed width pulse is generated at the $\overline{\text{EOUT}}$ pin and the integrated energy is reduced by 10 WSec. These pulses are counted to record energy consumption. The $\overline{\text{EDIR}}$ pin indicates the direction that the energy flows (reactive loads can return energy to the line). Depending on the state of the $\overline{\text{EDIR}}$ pin, the pulse at the $\overline{\text{EOUT}}$ pin causes the PIC16C923 to either increment, or decrement the total energy count.

FIGURE 3: CIRCUITS THAT MONITOR
LINE CURRENT (A) AND LINE
VOLTAGE (B)

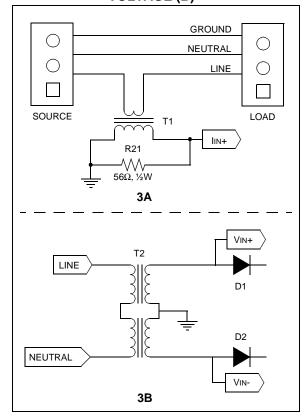
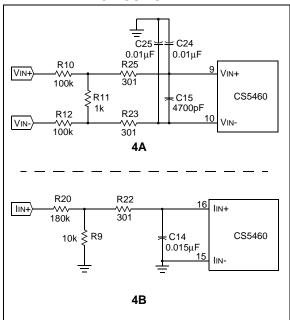


FIGURE 4: CS5460 INPUT ATTENUATION CIRCUITS

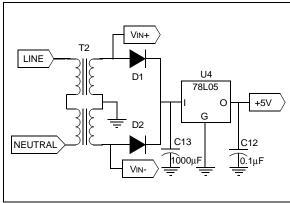


Power Supply

A transformer isolated power supply provides power for the Watt-Hour Meter. The transformer primary is connected to the line between the power source and the current sense transformer. The AC voltage from the transformer secondary is used to detect the line voltage and is coupled to the CS5460 through a resistor network (see Figure 4A).

The AC from the center tapped secondary is full wave rectified, filtered, and provided to the 5V regulator. The 5V loads are the "power-on" LED, the CS5460, and the PIC16C923. The majority of the current is drawn by the LED, about 7.5mA. The rest of the circuit draws less than 5mA.

FIGURE 5: POWER SUPPLY CIRCUIT

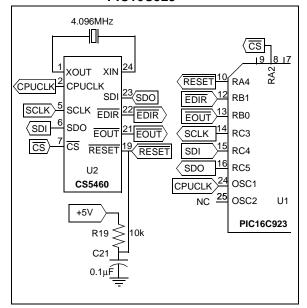


PIC16C923 Microcontroller

The PIC16C923 microcontroller provides a Liquid Crystal Display (LCD) driver module that drives the LCD panel directly. It also communicates with the CS5460 using the 4-wire SPI link (SDI, SDO, SCL, and $\overline{\text{CS}}$) to issue commands, write calibration data, and read measurement and calculation results. The microcontroller also controls the CS5460 $\overline{\text{RESET}}$ line (see Figure 6).

The controller system oscillator is driven by the CPUCLK output of the CS5460 and operates at 4.096MHz. The system oscillator is configured for XT mode, but any crystal mode will work. A 32.768kHz crystal has been provided for use with the Timer1 oscillator. Since the CS5460 provides a 4.096MHz clock source to the PIC16C923, either source can be used for the real time clock source. The demonstration units have been configured to use the CS5460 clock source for the real time clock.

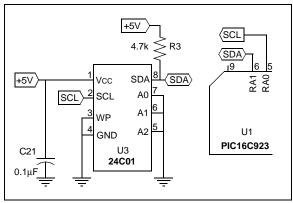
FIGURE 6: CONNECTIONS BETWEEN
THE CS5460 AND THE
PIC16C923



Interface to 24C01 Serial EEPROM

The Serial EEPROM stores the calibration constants required by the CS5460 for accurate measurements, and the total accumulated energy transferred. The controller communicates with the 24C01 via an I²C interface. Since the SSP module is already in use supporting SPI communications with the CS5460, the PIC16C923 must perform I²C communications in firmware, using RA0 (SCL) and RA1 (SDA) (see Figure 7). Either the 24C01, or the PIC16C923, may pull the SDA line low, depending on the direction of the data flow. Since the PIC16C923 always drives the SCL line, no pull-up resistor was included. A memory map of the Serial EEPROM is included in Appendix A.

FIGURE 7: CONNECTION BETWEEN THE 24C01 AND THE PIC16C923



User Interface

The user interface consists of the LCD display, four control push buttons, one reset push button, and the "power-on" LED.

The PIC16C923 LCD module directly drives the LCD panel. The panel can display eight, 7-segment digits (numbers only), seven decimal points and three colons.

When pushed, each of the four push buttons pull the respective port pin low. The buttons are connected to PORTB and are numbered from 1 to 4, left to right.

FIRMWARE

The CS5460 transfers data in 4 byte groups (32-bits). The first byte contains the register address and a bit specifying a read or write operation. The remaining 3 bytes are transferred to or from one of the internal registers. The CS5460 also accepts single byte commands. Such commands are followed by 3 SYNC bytes that are treated as NOP bytes.

A write command is followed by 3 bytes of data to the CS5460, to be written to the selected register. A read command causes the 3 bytes of the selected register to be output by the CS5460.

If the command byte specifies an operation to be performed, or a read operation, the remaining 3 bytes transmitted by the PIC16C923 should be SYNC0 bytes (0xFE).

Power-up and RESET

A Power-on Reset initializes the CS5460 and clears the real time clock.

Initialize On-Chip Peripherals

Timer1, Timer2, the SSP, and Ports A, B, and C are configured for operation. Interrupts are also enabled. The LCD module is then configured.

Clear the LCD Display

All segment data registers are cleared to blank the display. This routine is called frequently during normal operation.

Initialize Variables

If this was a cold start (power has just been applied), the memory contents are cleared and the calibration constants are copied from the 24C01 to the CS5460. The device serial number and the current total WHr are retrieved from the 24C01. If a warm start has occurred, only the serial number is retrieved.

Initialize the CS5460

The CS5460 is configured to generate a pulse at the EOUT pin for each 10 WSec measured (360 pulses per WHr). For 100W loads, this causes 10 pulses per second to be generated.

Check Button Status

The status of the four push buttons is checked. If all four buttons are pressed, the total WHr value in the 24C01 is cleared and calibration values are copied from the EEPROM to the CS5460. If the center two buttons are pressed, the real time clock is set. If the outer two buttons are pressed, the Watt-Hour meter enters Calibration mode (see Table 1). If no buttons are pressed, the CS5460 begins continuous measurements. Execution proceeds to the scrolling start-up message.

TABLE 1: BUTTON STATES CHECKED DURING RESET

	Butt	tons		Control Mode
1	2	3	4	Gonti or mode
Х	Х	Х	Х	Clear WHr, restore calibration values
	Х	Х		Set Clock
Х			Х	Calibration

Display the Start-up Message

A start-up message is displayed on the LCD. This message scrolls across the display until any of the four buttons is pressed. This message displays the device name and serial number.

Normal Operation

Results of the various calculations are displayed on the LCD. Each result is displayed for two seconds with an update after one second. If no buttons are pressed, the next mode is displayed. Holding any button keeps the display in the present mode, for as long as the button is held. New results will be displayed each second (see Table 2).

TABLE 2: DISPLAY MODES

Display	Value Displayed
HH:MM:SS	Time
E	RMS Voltage
С	RMS Current
AP	Apparent Power
TP	True Power
PF	Power Factor
Hr	Total WHr

Time

The first result displayed is the time of day in the form HH:MM:SS. If the time of day was not set at RESET, this indicates the time since power-up (days are not recorded).

RMS Voltage

The RMS voltage is computed by reading the RMS voltage value from the CS5460. This is a 24-bit value with a range of 0.000 to 1.000, representing a fraction of the full scale voltage. The 16 most significant bits are multiplied by the full scale voltage (as 16-bits) to produce the actual RMS voltage on the line, as a 16-bit binary number. This is converted to a 5 digit packed BCD number. The LCD display is blanked and "E" and the appropriate decimal point are displayed. The packed BCD number is then displayed, after determining which digits (leading zeros) should remain blank

After one second, the value is updated and displayed again. After another second, execution proceeds to the next mode if no buttons were pressed. If a button was pressed, the two-second counter that controls when the next subroutine should be executed is cleared, extending the time that the value is displayed. This code is repeated in all display subroutines.

RMS Current

The RMS current is computed and displayed similar to the RMS voltage. The only differences are the full scale current is used, a "C" is displayed and a different decimal point is turned on. The button state is again checked to see if execution should remain in this subroutine.

Apparent Power

The apparent power is computed in a subroutine (CalcAP), called by both the apparent power loop (APLoop) and the power factor loop (PFLoop). The apparent power is computed by reading the RMS voltage and RMS current from the CS5460, as before. The 16 most significant bits of each are multiplied together, giving a 32-bit result. The 16 most significant bits of the result are multiplied with the full scale apparent power (16-bits) to get the actual apparent power in volt • amps in binary. The 16 most significant bits are returned for use by the calling subroutines.

APLoop then converts the apparent power in binary (16-bits) to a 5-digit packed BCD number for display. The LCD display is blanked, "AP" is displayed and after determining which digits should remain blanked (leading zeros), the apparent power is displayed. The buttons are again checked, as before, to determine if execution should remain in this subroutine.

True Power

The CS5460 was programmed to generate a pulse whenever 10 WSec of energy has been transferred. For a 250W load, 25 pulses each second will be generated. These pulses have been processed in an Interrupt Service Routine. When 360 pulses have been accumulated, 3600 WSec or 1 WHr has been transferred. The total WHr is then incremented. The pulse count is also recorded for each second.

The apparent power is computed in a subroutine (CalcTP), called by both the true power loop (TPLoop) and the power factor loop (PFLoop). CalcTP multiplies the number of pulses received during the last second by 10 to compute the true power consumed by the load. The result is returned as the true power in watts as a 16-bit binary number.

TPLoop converts and displays the true power in the same way as APLoop displays apparent power. The only difference is that "TP" is displayed instead of "AP". The buttons are again checked as before to determine if execution should remain in this subroutine

Power Factor (PF)

The power factor is computed by calling the CalcAP subroutine to get apparent power in volt • amps and the CalcTP subroutine to get true power in watts. The true power is divided by the apparent power to get the power factor as a binary result, in the range of 0.000 to 1.000. The binary power factor is multiplied by 1000 and converted to a BCD number for display. The appropriate decimal point is turned on.

The buttons are checked as before to determine if execution should remain in the power factor subroutine.

If apparent power is equal to 0, there is no load (IRMS = 0). This can result in a division by zero condition. If a division by zero is detected, a PF of 1.000 is reported.

The calculated power factor can also greatly exceed 1.0. When this occurs, the power factor is reported as being 1.000. This occurs when the load characteristics are rapidly changing (as when a motor is starting). All the measurements are not taken at exactly the same time and the RMS values are calculated over a one second period. When the load reaches a steady state condition, the power factor will again be correct.

Energy (Watt-Hours)

The WHLOOP simply displays the WHr counter value. The binary count is converted to BCD. The BCD number is then displayed with leading zeros blanked, using the same subroutine used by the apparent power and true power displays. The WHr counter is 16-bits long, allowing a maximum of 65,535 WHr to be displayed. When this count is exceeded, the count rolls over to 0.

Control Modes

If any of the three control modes was selected during RESET, execution branches to one of these modules to control how the Watt-Hour meter functions.

When the control mode is terminated, a warm start RESET is executed.

Calibrating the Watt-Hour Meter

The user is given the opportunity to adjust the calibration constants. These constants will not be stored to the 24C01. When reset, using the reset button, the calibration values entered in the Calibrate mode will be used for making measurements and operation will resume as normal, except that the new calibration values are used. If reset by removing power, or reset while pressing all four buttons (clear total WHr), the constants stored in the 24C01 will be used for operation.

Enter Calibration mode by holding the two outer buttons while pressing the reset button. The first three digits display "CAL", and the remaining digits indicate which constant is being adjusted. "CAL EOFF" will be displayed first. This indicates that the value displayed the next time button 2 is pressed, will be the calibration constant for the voltage offset. Pressing button 2 again displays the constant's value.

The decimal point is next to the digit to be modified. Pressing button 3 will move the decimal point to the next digit to the right. Pressing button 4 will increment that digit. Each digit will cycle from 0 to F, then back to 0. Only that digit will be affected. Pressing button 1 at any time will cause the value for that constant to be sent to the CS5460 and display the next constant name. See Table 3 for button functions.

TABLE 3: CALIBRATION MODE BUTTON FUNCTIONS

	But	ton		Function
1	2	3	4	i unonon
Х				Writes constant to CS5460 and displays next constant name
	Х			Displays each constant name and its value in turn
		Х		Selects next digit and moves decimal point
			Х	Increments selected digit

Table 4 shows the constant names and typical values. It is essential that the offsets be minimized before setting the gains.

To set the offsets, remove AC power from the Watt-Hour meter and apply DC power of 8 to 12 VDC to C13. Adjust the offset constants for minimum RMS results (there is a null in both the current and voltage channels). Record the offsets.

Apply AC power to the Watt-Hour meter and remove the DC power from C13. Applying power in this order prevents a loss of power to the CS5460. If power is lost, reenter the offset values before adjusting the gain values. Apply a known resistive load to the Watt-Hour meter output. Adjust the voltage and current gain constants so the indicated RMS voltage and current match the actual load voltage and current. Adjust the pulse rate gain so the indicated true power matches the actual load power. Record the gain constants.

Resetting the device now uses the constants just found. If the total Watt-Hours is cleared, the original constants will be restored.

The software was designed for demonstration purposes; therefore, the calibration constants cannot be written to the serial EEPROM. If desired, the user can modify the code to write the new calibration constants to the EEPROM.

TABLE 4: CALIBRATION MODE INDICATIONS, CONSTANT AND TYPICAL VALUES

Indication	Constant	Calibration Value (120V, 10A)	CS5460 Default
EOFF	Voltage Offset	0x00CCBB = +0.00624	0x000000 = 0.00000
COFF	Current Offset	0xFEB320 = -0.01015	0x000000 = 0.00000
E GA	Voltage Gain	0x2C2F62 = 0.69039	0x400000 = 1.00000
C GA	Current Gain	0x298610 = 0.64917	0x400000 = 1.00000
P GA	Pulse Rate Gain	0x01FEF2 = 510.95	0x0FA000 = 4000.000

Clear Total Watt-Hours

This option causes the total WHr to be cleared from the 24C01 and RAM, and copies calibration data stored in the 24C01 back to the CS5460. The word "CLEAR" is displayed until the buttons are released.

Setting the Real Time Clock

"CL" is displayed in the two digits at the left edge of the display. The current time is displayed in the remaining six digits.

If buttons 2 and 4 are pressed together, the hours are incremented. If buttons 3 and 4 are pressed, the minutes are incremented. If the minutes roll over from 59 to 0, the hours will not be affected. If button 1 is pressed, "CL" is cleared from the display and execution proceeds to the main loop. Pressing Button 2, 3, or 4 alone has no effect (see Table 5).

TABLE 5: CLOCK SET MODE BUTTON FUNCTIONS

	But	ton		Function									
1	2	3	4	Tunction									
Х				Done setting clock									
	Х		Х	Increment hours									
		Χ	Χ	Increment minutes									

POSSIBLE ENHANCEMENTS

An idea to simplify the calibration process is presented, along with ideas for adding a battery backup and event logging.

Power Factor

As reactive loads draw current out of phase with the line voltage, there is an associated phase angle. The cosine of this angle provides the power factor.

The power factor will never exceed 1.000. Resistive loads will show a very high power factor, while reactive loads, such as motors, will show lower power factors. Loads with great harmonic content (such as most power supplies) will also indicate a low power factor. Power Factor Correcting (PFC) loads will indicate very high power factors.

Calibration

The calibration process assumes the user has the time and understanding to determine the calibration constants. This process can be greatly simplified. The CS5460 has the capability of determining offsets and gains. By commanding the CS5460 to perform an offset calibration, the offset constants can be found very quickly. The calibration program would indicate the measured value being calibrated and allow the user to adjust the constant, without actually having to know what the constant was. When a satisfactory measurement is achieved, the constant would then be written to the 24C01.

The code presented in this application note almost completely fills the first code page of the PIC16C923. The second code page could be dedicated to a calibration program.

Battery Backup

Some users may wish to have the real time clock continue to run, even during a loss of power. This becomes possible by adding a backup battery to power the PIC16C923 and allow the Timer1 oscillator to operate. This would be the time base for the real time clock. The code to use Timer1 and its oscillator has been included. To extend the life of the battery, it would power only the PIC16C923.

Event Logging

The 24C01 provides 128 bytes of non-volatile EEPROM memory. Currently, only 17 bytes are used for storing calibration data, total energy, and a device serial number. The remaining memory could be used to record power line events, such as black-outs, brown-outs, surges and load peaks. With a real time clock, the times of these events could also be recorded. Recording black-outs and brown-outs would require that the backup battery also power the 24C01.

APPENDIX A: EEPROM DATA MAP

Address	Description
0x00	Device Serial Number
0x01	Voltage Offset MSB
0x02	Voltage Offset
0x03	Voltage Offset LSB
0x04	Current Offset MSB
0x05	Current Offset
0x06	Current Offset LSB
0x07	Voltage Gain MSB
0x08	Voltage Gain
0x09	Voltage Gain LSB
0x0A	Current Gain MSB
0x0B	Current Gain
0x0C	Current Gain LSB
0x0D	Watt-Hour MSB
0x0E	Watt-Hour LSB
0x0F	Pulse Rate Gain MSB
0x10	Pulse Rate Gain
0x11	Pulse Rate Gain LSB

APPENDIX B: SOURCES

The LCD routines came from PICDEM-3™. Adjustments may have been made to the segment and common definitions to account for the use of a different LCD panel than was used in PICDEM-3.

The BIN2BCD routine is loosely based on the B2_BCD_Looped routine in BCD.ASM of application note AN544. This function was originally written for the PIC17CXXX family, but it has been modified for the PIC16CXXX family.

The multiply and divide math routines were copied from application note AN617.

The data sheet for the PIC16C923 can be found at http://www.microchip.com. Search for "DS30444E" or "PIC16C923".

The data sheet for the 24C01 can be found at http://www.microchip.com. Search for "DS20071J" or "24C01".

The data sheet for the CS5460 can be found at http://www.crystal.com. Search for "DS279PP3" or "CS5460".

APPENDIX C: SCHEMATICS

FIGURE C-1: PIC16C923 CONNECTIONS

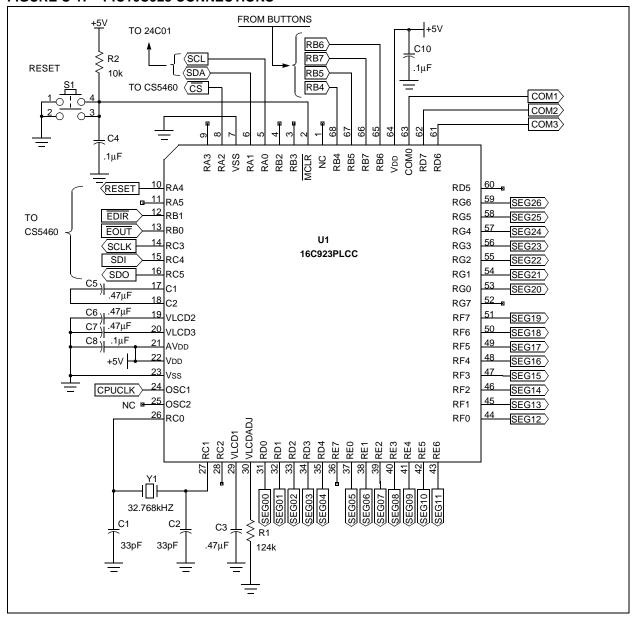
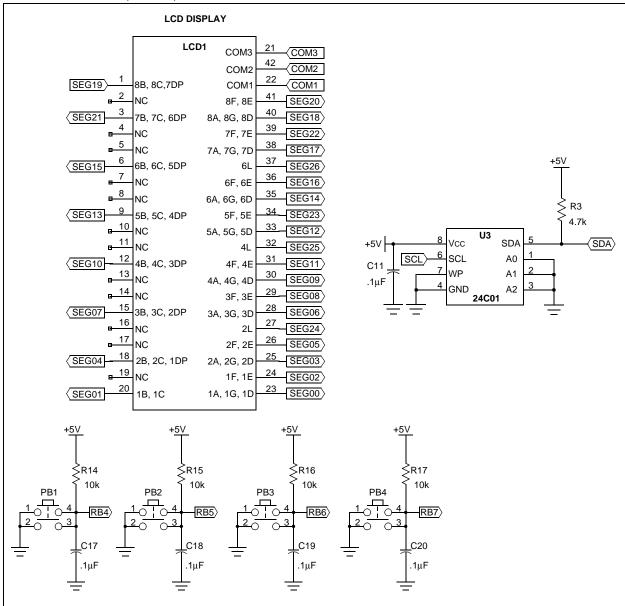


FIGURE C-2: LCD, 24C01, PUSH BUTTONS



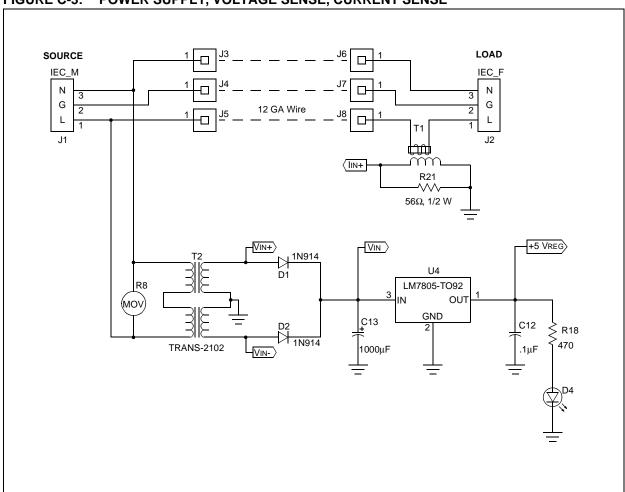
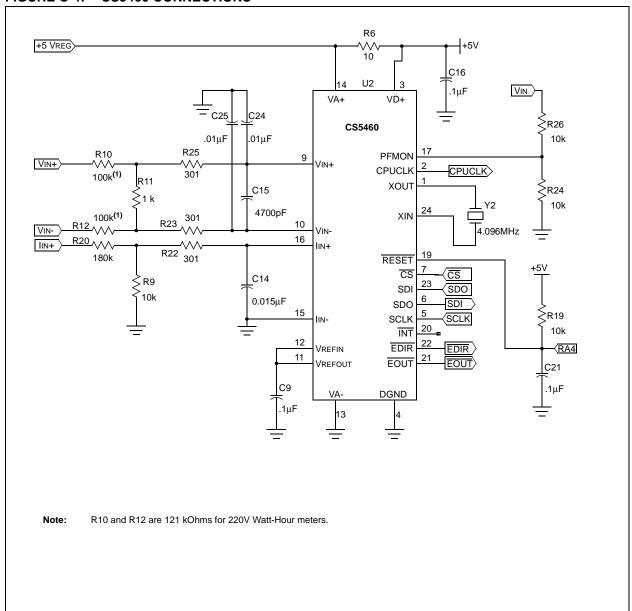


FIGURE C-3: POWER SUPPLY, VOLTAGE SENSE, CURRENT SENSE

FIGURE C-4: CS5460 CONNECTIONS



APPENDIX D: BILL OF MATERIALS

Cnt	Component Name	RefDes	Description	Digikey
2	1N4001	D1-2	IN4001DICT-ND	
1	16C923PLCC	U1	PIC16C924 (Microchip)	
1	SOCKET	U1	A2144-ND	
1	24C01_TSOP	U3	24CO1-BC (Microchip)	
2	CAP150	C1-2	33pF Capacitor	P4843-ND
12	CAP0805	C4, C8-12, C16-21	.1μF Capacitor	PCC1864CT-ND
2	CAP1206	C24-25	.01μF Capacitor	PCC103BCT-ND
4	CAP1206	C3, C5-7	.47μF Capacitor	PCC1891CT-ND
1	CAP1206	C15	4700pF Capacitor	PCC472BCT-ND
1	CAP1206	C14	15000pF Capacitor	PCC153BCT-ND
1	CAP-RAD400D	C13	1000μF Capacitor	P5142-ND
1	CRYSTAL	Y2	4.096MHz Crystal	X082-ND
1	CRYSTAL_32KHZ	Y1	32kHz Crystal	SE3201-ND
1	CS5460	U2	CS4560 (Crystal Semiconductor)	
1	CSE187-L	T1	Current Transformer	10515-ND
1	IEC_F	J2	Socket	509-1271 (Allied)
1	IEC_M	J1	Plug	509-1269 (Allied)
1	LCD_VIM-808-DP	LCD1	VIM-808-DP-RC-S-HV	153-1057-ND
1	LED_SMT	D4	LED, Green	LT1120CT-ND
1	LM7805-TO92	U4	Voltage Regulator	NJM78L05A-ND
1	MOV	R8	MOV	P7259-ND
1	RES600	R21	56Ω 1/2W Resistor	56H-ND
1	RES1206	R11	1kΩ Resistor	P1.0KECT-ND
1	RES1206	R3	4.7kΩ Resistor	P4.7KECT-ND
1	RES1206	R6	10Ω Resistor	P10ECT-ND
9	RES1206	R2, R9, R14-17, R19, R24, R26	10kΩ Resistor	P10KECT-ND
1	RES1206	R1	124kΩ Resistor	P124KFCT-ND
1	RES1206	R20	121kΩ Resistor	P121KFCT-ND
3	RES1206	R22-23, R25	301Ω Resistor	P300ECT-ND
1	RES1206	R18	470Ω Resistor	P470ECT-ND
2	RES1206	R10, R12	100kΩ Resistor	P100KECT-ND
5	SW-B3F1000	S1, PB1-4		SW404-ND
5	KEY CAP	S1, PB1-4		SW450-ND
1	TRANS-2102	T2	Transformer 12 Vac/0.09 A	MT2113-ND
1	Plastic case			141840 (Jameco)
1	Printed Circuit Board			
Misc	ı	<u>I</u>		1

Misc:

4 4-40 X 3/8 machine screw for J1, J2

4 4-40 hex nut

2 ft 12 ga stranded copper wire

20-pin machined pin IC socket to cut up for pin extensions for S1-S5

Software License Agreement

The software supplied herewith by Microchip Technology Incorporated (the "Company") for its PICmicro® Microcontroller is intended and supplied to you, the Company's customer, for use solely and exclusively on Microchip PICmicro Microcontroller prod-

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APPENDIX E: SOURCE CODE

PAGE 1		; suppress list file symbol table	; suppress list file page breaks		***************************************	00005 ; Configuration switches. These control what code is assembled.		Select the desired operating voltage by commenting out all but		; 120V nominal full scale range	; 220V nominal full scale range		cy source,	; defined if using 32kHz T10SC, comment out if another RTC source		0.001********************************			The software supplied herewith by Microchip Technology Incorporated (the	OOO19 · "Company") for its DTCmishow Mishocontroller is intended and short
13:31:13		st=off	n=0		*********	hese control		ating voltag	ge	VOLT120	VOLT220		lock frequen	TMR10SC		********	τ		ewith by Mic	ro® Microcon
.ASM 5-25-2000 13:31:13		list	list		************	ration switches. T		t the desired oper	the desired voltage range	#define	#define		Selects the real time clock frequency source,	#define		************	Software License Agreement		tware supplied her	v") for its PICmic
rmediate WAIT_MTR	LINE SOURCE TEXT	00001	00002	00003	00004 .*****	00005; Configu	90000	00007 ; Select	00008; the de	60000	, 00000	00011	00012 ; Select	00013 ;	00014	.******* 000TE	00016; Software	, 71000	00018 ; The soft	00019; "Company
MPASM 02.30.11 Intermediate WATT_MTR.ASM	LOC OBJECT CODE VALUE																			

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by the PIC16C923 to measure and display total energy transferred in WattHours
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 Standard Microchip include file for PIC16C923/924
                                                                                                                                                                                                                                                                                                                                                                                                                                                  FOR SPECIAL, INCIDENTAL OR CONSEQUENTIAL DAMAGES, FOR ANY REASON WHATSOEVER
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 RMS voltage and RMS current are displayed and used to calculate aparent
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           reactive, enegry flows from the load to the line). These pulses are counted
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             measurements and calculation results are avalible to the PIC16C923 via SPI.
                                                                                                      The software is owned by the Company and/or its supplier, and is protected
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       energy has been transferred between the line and the load. Another output
                                                                                                                                                                                                                                                                                                             THIS SOFTWARE IS PROVIDED IN AN "AS IS" CONDITION. NO WARRANTIES, WHETHER
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       A pulse output (EOUT) on the CS5460 indicates when a programable amout of
you, the Company's customer, for use solely and exclusively on Microchip
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            measurements are used to compute (within the CS5460) instantanious power,
                                                                                                                                                                    violation of the foregoing restrictions may subject the user to criminal
                                                                                                                                                                                                                                                                                                                                                                                 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE APPLY
                                                                                                                                                                                                                                                                                                                                                                                                                 TO THIS SOFTWARE. THE COMPANY SHALL NOT, IN ANY CIRCUMSTANCES, BE LIABLE
                                                                                                                                                                                                       sanctions under applicable laws, as well as to civil liability for the
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              the line (source) and the load. The instantanious voltage and current
                                                                                                                                                                                                                                                                                                                                              EXPRESS, IMPLIED OR STATUTORY, INCLUDING, BUT NOT LIMITED TO, IMPLIED
                                                                                                                                      under applicable copyright laws. All rights are reserved. Any use in
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          (EDIR) indicates the direction of that transfer (if a load is highly
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           CS5460 measures line voltage and current transfered between
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    This program controls and reads data from The Crystal CS4560
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              ********************
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     and displays it on a eight digit LCD using the LCD drive
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   LCD segment definitions
                                                                                                                                                                                                                                          breach of the terms and conditions of this license.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                calibration constants
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               ; Assembled using MPLAB 4.99.07, MPASM 2.30.11
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     Single Phase Bi-Directional Power/Energy IC
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        ; Author: Stephen Humberd, Brett Duane
                                     ; PICmicro Microcontroller products.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         Company: Microchip Technology Inc.
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cleared from the 24C01. The code to read the constants from cal.inc and write them to
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      On reset, the PIC16C923 checks the 4 control buttons for 3 specific states. One state
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        serial EEPROM. This saves the total energy during times when the AC power is removed.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       and written back to the CSS460 when power is reapplied, and when the total enegy is
                                                                                                                                                                                                                                                                                                                                                                        source with CCP1 in compare/interrupt only/special event mode, or using the Timer1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               These are read from the 24C01
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                allows the user to set the time of the real time clock. Another state clears the
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          total WHr for the 24C01 and rewrites the calibration constants to the CS5460. A
                                                                                                                                                                                                                                                                                                                                 clock. This code offers the option of using this source as the real time clock
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              third state allows the user to adjust the calibration constants in the CS5460.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 Every 8 minutes, the current accumulated energy (WHr) is written to the 24C01
                                                                                                                                                                                                                                                                                                                                                                                                               oscillator with a 32.768KHz crystal. The hardware provided on the demo units
True power is measured by counting pulses for 1 second. The CS5460 has been
                                       programmed to generate a pulse for each 10WattSeconds of energy tranferred.
                                                                                                                                                                                                                                                                                       The CS4560 outputs a 4.096MHz clock for use by the PIC16C923 as the system
                                                                                                                                                               Aparent power and true power are displayed, and are used to calculate the
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               CCPRIH: CCPRIL will need to be adjusted to make CCP1 generate an interrupt
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    can be used (as is) for the real time clock reference instead of
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               Modified Calibrate routine to include Pulse Rate "Gain" function
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                Optional Real Time Clock sources (T10SC or CS5460 CPUCLK output)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           Timerl Oscillator. If the CPUCLK output is some other frequency,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       If the CPUCLK output of the CS5460 is 4.096MHz, the CCP1 module
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        to 1 pulse/10Wsec (100W load generates 10 pulses per second)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 Added Apparent Power, True Power, and Power Factor Functions.
                                                                              The pulse count is multiplied by 10 to calculate true power.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            Written by Stephen Humberd, Microchip Technology 10/08/1999
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         *********************
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 Change Pulse Rate from 128 pulses/KWHr (1 pulse/28,125Wsec)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     the 24C01 has been included, but has been commented out.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               Calibration constants are also stored in the 24C01.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         General code size reduction. (Fits in PIC16C923.)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  Use 16-bits of CS5460 data rather than 24-bits
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          (CS5460 settings are still 24-bits long)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        Moved Pulse Rate register value to EEPROM.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          Monitor CS5460 !EDIR output.
                                                                                                                                                                                                         power factor of the load.
                                                                                                                                                                                                                                                                                                                                                                                                                                                         supports both options.
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DS00220A-page 16

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; suppress assembler warning message "Crossing page boundary"
                                                                                                                                                                                                                                    ; suppress assembler warning message "Operand not in bank 0"
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       ; Variable in shared RAM. CCP1 interrupt counter,
                                                                                                                                                                                                                                                                                                                                                                                                                                       ; Sync bytes sent as dummy data during reads
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        ; Load variables into RAM starting at 0x20
                                                                                                                                                                                                                                                                                                                                                                                                                                                    No more than 3 SYNC1 bytes at a time.
                                                                                                                                                                   Microchip Technology, Inc.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       ; not used with Timer1 oscillator.
If the Timer1 oscillator is to be used as the Real Time Clock base,
                                                                                                                                                                                                                                                                                                  *********************
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        ********************
               ; uncomment line 46 ("#define TMR10SC"). This causes CCP1 code to
                                                                            *****************
                                                                                                                                                                                                   CONFIG _CP_OFF&_WDT_OFF&_XT_OSC&_PWRTE_ON
                                                                 ; Modified by Brett Duane, Microchip Technology 5/25/2000
                                                                                                                                                                  Standard Header File, Version 1.01
                               be disabled and T10SC code to be enabled.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         energy pulse counter LSB
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             energy pulse counter MSB
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      TMR10SC
                                                                                                                                  #include <p16c924.inc>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           Accumulated WHr MSB
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                                                                                                                                                                                                                                                                                                                                                                                                                      ; CS5460 variables (string equates)
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                                                                                                                list p=16c924
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                                                                                                                                                                  ; P16C924.INC
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; Accumulated WHr LSB	; "Pulses per second" counter MSB	; "Pulses per second" counter LSB	during previous second"	; "Pulses during previous second" LSB		; Apparent Power MSB (16 bit) (VoltAmps in binary)	; Apparent Power LSB		; True Power MSB (16 bit) (Watts in binary)	; True Power LSB		; Power Factor MSB (16 bit) (unitless in binary)	; Power Factor LSB		variables	; Points to the characters in initial	; scrolling message	; unit serial number	; Calibration Mode being displayed	; Calibration digit being incremented	; When to write accumulated Watt HOURs to the EEPROM (every 8 minutes)		es (SPI mode) Receive buffer from CS5460		; RXDATA buffer	; RXDATA buffer LSB		er (SPI mode) Transmit buffer to CS5460	; command byte to send to the CS4560	; TXDATA buffer MSB	; TXDATA buffer	; TXDATA buffer LSB		ATH library AN617	; 4 byte argument and result. BO is always MSB						; 2 byte argument. B0 is always MSB	,	
00155 WATTHRL	00156 00157 PULSECH	00158 PULSECL		00161 PULDISPL	00162	00163 APH	00164 APL	00165	00166 TPH	00167 TPL	00168	00169 PFH	00170 PFL	00171	00172 ; More general	00173 POINTER	00174 PTRTMP	00175 SERNUM	00176 CALMODE	00177 CALDIG	00178 UPDATEWH	00179	00180 ; SSP variables	RX.	00182 RXDATA1	00183 RXDATA2	00184	00185 ; TXDATA buffer	00186 TXDATA	00187 TXDATA0	00188 TXDATA1	00189 TXDATA2	00190	00191 ; Microchip MATH	00192 AARGB0	00193 AARGB1	00194 AARGB2	00195 AARGB3	,	00197	00198 BARGB0	נסיים מסיים	
00000028	00000029	0000002A	0000002B	0000002C		0000002D	0000002E		0000002F	00000000		00000031	00000032			00000033	00000034	00000035	96000000	00000037	00000038			68000000	0000003A	0000003B			0000003C	0000003D	0000003E	0000003F			00000040	00000041	00000042	00000043	00000044		00000045	00000046	

00201 REMBO ; 2 byte remaider (from division) 00202 REMB1 ; B0 is always MSB 00203 00204 TEMP ; internal variables 00205 TEMPB1 00207 TEMPB2 00208 LOOPCOUNT 00209	0 1 2 8 4 5	TEMPH COUNT ; interna BYTECOUNT ; EEPROM FRAND · FEDROM	1 EEADDR ; 2 EEDATA ; 3 EETEMP 4 5 ; powerup variable 6 PWRUP55 ; 7 PWRUPAA ;	00229 LASTRAM ; dummy marker (unused) 00230 00231 endc 00232 00233 cblock 0x70 ; Load variables into RAM starting at 0x70 00234 ; "SHARED" variables in memory locations 70h-7Fh are avaliable in all banks 00235 00235 LCDTEMP1 ; used by LCD routines 00237 LCDTEMP2	00238 00239 MODEINC ; incremented each second, 00240 ; bit 7 set whever Bit 0 is set (every odd second) 00241 00242 UPDATE ; Bit 0 set each second 00243 00244 BUTTON ; indicates button press. Bit0=1 = a button is pressed 00245 BUTTONTMP ; used only in ISR. Bits<1:4>= buttons 1-4 are pressed 00246
00000047 00000048 0000004A 0000004B 0000004C	0000004E 0000004F 00000050	00000052	00000055 00000057 00000058 00000058	0000005A 00000070 00000071	00000072 00000073 00000074 00000075

upt, restore after interrupt gister during ISR register during ISR ster during ISR register during ISR	<pre><cal.inc> ; calibration definitions</cal.inc></pre>		h by Microchip Technology Incorporated (the Microcontroller is intended and supplied to	se solely and exclusively on Microck	· vi	and/or its supplier,	are rese	restrictions may subject the user to criminal	this license.		"AS IS" CONDITION. NO WARRANTIES, WHETHER		S FOR A PARTICULAR PURPOSE	IN ANY CIRCUM	CONSEQUENTIAL DAMAGES, FOR ANY REASON WHATSOEVER.		WRITE TO EEPROM ****************	n determined for	into these "#defines" and	Calibration instruction document)		. ; Serial Number		; voltage	• •	, voltage gain LSB		current gain MSB	; current gain	; current		; voltage	; voltage offset	; voltage offset LSB	
interru FSR rec PCLATH W regis		greement	ed herewit	customer, for	Microcontroller products.			toregoing restri	and con		PROVIDED IN AN	OR STATUTORY, II		THE COMPANY SH	ENTAL OR CONSE				be lo	(see		MBER 0x01			VINM 0x66	AINL 0x6F		AINH 0x2A	AINM 0x2E	AINL 0×0A				FL 0xB6	
text	endc #include	are License Agreement	The software suppli "Company") for its	the Company's	Cro Microconci	software is own		of the	of the te		SOFTWARE IS PR	IMPLIED	ES OF MERC	THIS SOFTWARE. T	SPECIAL, INCIDENTAL OR		*	calibrat	se values	en to the EEPROM		SERNUMBER		VOLTGAINH	VOLTGAINM	VOLTGAINL		CURRGAINH	CURRGAINM	CURRGAINL				VOLTOFFL	
; Save TEMPFSR TEMPPCI TEMPW		; Software ;	; The		; Ficmicro	; The	٠.	; violation			; THIS	; EXPRESS,	•-	L OL ;	; FOR		٠.	; After	; unit	; written		#define			#define	#define		#define	#define	#define				#define	
00247 00248 00249 00250 00251	00252 00253 00254	00001	00003	00005	00000	00008	60000	000010	00012	00013	00014	00015	00016	00017	00018	00019	000020	00021	00022	00023	00024	00025	00026	00027	00028	00029	00030	00031	00032	00033	00034	00035	00036	00037	00038
00000076 00000077 00000078																																			

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ω O		ROVIDED IN AN "AS IS" CC R STATUTORY, INCLUDING, HANTABILITY AND FITNESS THE COMPANY SHALL NOT, I	I2C communications	PORTA, 0	PORTA, 1	TRISA, 1	*****	PORTA, 2		**********	register	LCDD02,2	LCDD02,3	LCDD06,3	LCDD10,2	LCDD06,4	LCDD02,4	LCDD06,2		LCDD02,1	LCDD02,5	LCDD06,5	LCDD10,1	LCDD06,6	LCDD02,6	LCDD06,1		LCDD01,6	LCDD01,7	LCDD05,7	гсрров, е
Company's Microcontr	are i licab of t unde the	SOFTWARE IS PROVIDED ISS, IMPLIED OR STATUTIVIES OF MERCHANTABILIS SOFTWARE. THE COMPECTAL, INCIDENTAL OF	****** EEPROM	SCL	SDA	SDATRIS	QUU *****	CS		***** ICD	ne what bit in what	D1A	D1B	DIC	D1D	DIE	D1F	D1G		D2A	D2B	D2C	DZD	DZE	D2F	D2G		D3A	D3B	D3C	рзр
00006; you, the 00007; PICmicro 00008;	00009; The softwe 00010; under app. 00011; violation 00012; sanctions 00013; breach of	; THIS ; EXPR ; WARR ; TO I ; FOR	**************************************	00022 #define		00024 #define	************		00028		000030; We define	00032 #define		00034 #define	00035 #define	00036 #define	00037 #define	00038 #define	00039	00040 #define	00041 #define	00042 #define	00043 #define	00044 #define	00045 #define	00046 #define	00047	00048 #define	00049 #define	00050 #define	00051 #define

		DIGIT 4								DIGIT 5								DIGIT 6								DIGIT 7								DIGIT 8 (RIGHT SIDE)								COLONS	
LCDD06,0 LCDD02,0 LCDD05,6		LCDD01,4	LCDD01,5	LCDD05,5	LCDD09,4	LCDD06,7	LCDD02,7	LCDD05,4		LCDD01,1	LCDD01,2	LCDD05,2	LCDD09,1	LCDD05,3	LCDD01,3	LCDD05,1		LCDD00,6	LCDD00,7	LCDD04,7	LCDD08,6	LCDD05,0	LCDD01,0	LCDD04,6		LCDD00,3	LCDD00,4	LCDD04,4	LCDD08,3	LCDD04,5	LCDD00,5	LCDD04,3		rcpp00,0	LCDD00,1	LCDD04,1	LCDD08,0	LCDD04,2	LCDD00,2	LCDD04,0		LCDD11,2	LCDD11,1
D3E D3F D3G		D4A	D4B	D4C	D4D	D4E	D4F	D4G		D5A	D5B	DSC	DSD	DSE	DSF	D5G		D6A	D6B	Dec	рбр	D6E	DGF	D6G		D7A	D7B	D7C	D7D	D7E	D7F	D7G		D8A	D8B	D8C	D8D	D8E	D8F	D8G		COLON1	COLON2
00052 #define 00053 #define 00054 #define	00055	00056 #define	00057 #define	00058 #define	00059 #define	00060 #define	00061 #define	00062 #define	00063	00064 #define	00065 #define	00066 #define	00067 #define	00068 #define	00069 #define	00070 #define	00071	00072 #define	00073 #define	00074 #define	00075 #define	00076 #define	00077 #define	00078 #define	00079	00080 #define	00081 #define	00082 #define	00083 #define	00084 #define	00085 #define	00086 #define	00087		00089 #define	00090 #define	00091 #define	00092 #define	00093 #define	00094 #define	00095		00097 #define

; DECIMAL POINTS	**************************************	; Reset vector	; Interrupt vector	<pre>; save context before executing ; ISR (Interrupt Service Routine)</pre>			; Prog page 0 ; SFR bank 0 ; SFR bank 0	then branch to apropriate subroutine ; RBO/INT flag	Pulse fr	; Check CCP1 interrupt flag, not used with Timer1	<pre>; Timer1 overflowed (One second timer) ; Check PORTB flag</pre>
LCDD11,0 LCDD10,3 LCDD10,5 LCDD09,7 LCDD09,2 LCDD08,7 LCDD08,7 LCDD08,4	**************************************	0x0000 Start	0x0004	TEMPW STATUS, W	TEMPSTAT FSR,W TEMPFSR	РСГАТН, W ТЕМРРС <u>ГА</u> ТН	PCLATH STATUS,RP0 STATUS,RP1	d the interrupt, INTE	RBOISR PIR1, TWR11F	PIR1, CCP11F	TMR11SR INTCON,RBIF
COLON3 DEC1 DEC2 DEC3 DEC4 DEC5 DEC5 DEC5	**************************************	org goto	org	movwf	movwf movf movwf	movf movwf	clrf bcf bcf	Find out which flag caused btfsc		btfsc	goto
000998 #define 000099 #define 00100 #define 00102 #define 00103 #define 00104 #define 00105 #define 00105 #define 00105 #define 00105 #define 00105 #define	00257; ************************************	00261 00262 00263	00264 00265	00266 00267	00268 00269 00270	00271 00272 00273	00274 00275 00276	•-	# =	00285 #ELSE 00286 00287 #ENDIF	00288 00289 00290
		28B2 (2 3			080A 00F7 (018A 1283 (1303	1888 888		U	2818 (
		0000	0004			0009 000A	0000 000C	000年			0011

ButtonISR ; A BUTION was pressed		RZIF ; Check Tin	TMR2ISR ; debounce time for BUTTONs		t a real interrupt, c	INICON,TOIE ; disable timero interrupts	DOD . reators contact return from intervient	י דפארסדם רסוורפאר, דפרעדון דדסווו				the second counter for the Real Time Clock	is stopped, a new value is reloaded, and the timer			nterrupt is generated, but interrupts occur twice	The interrupt rate is dived by 2 to get a 1 second interrupt	red.		s of the 1 second timer tick that regulates the various	il time clock.	PULSEC <h:l> variables is moved to PULDISP<h:l>, and PULSEC<h:l> is cleared.</h:l></h:l></h:l>		, MINUTE,	UPDATE, PULSECL, PULSECH, WATTHRL, WATTHRH, UPDATEWH			code if 32kHz Timer10SC is used		N,TMRION ; turn off timer	0x7f ; reload Timerl registers	TMR1H	Oxff	TWR1L	TICON, TMRION ; turn on timer		PIR1, TMR11F ; Clear TMR1 interrupt flag		; use this code if the system clock is used		PIR1, CCP1IF ; Clear CCP1 interrupt flag		CCPCOUNT, r ; count interrupt core ccPCOUNT, 0 ; divide interrupt rate by 2	
goto		btfsc	goto		; if you get	bar	, + ()))	*****************		mer1 overflow interrupt	This is the interrupt for	used, the timer	restarted.		CCP1 is used, only an interrupt is	often as needed.	te. No reloading is required		is interrupt is the basis	splay modules, and the	count in the			tput variables:	!		#IFDEF TMR10SC ; use this co		bcf	movlw	movwf	movlw	movwf	lsd		bcf		ы		bcf	4	inci btfsc	
00291	00292	00293	00294	00295	00296	00297	00298	00800	+	· ·	•-	00303 ; Th	00304 ; If	00305 ; is	00306;	00307 ; If	00308; as	; ra	00310 ;	00311 ; Th	; di	 00314 ; The	•-	i In	, Ou	ļ			00321	00322	00323	00324	00325	00326	00327	00328	00329	00330	00331 #ELSE	00332	00333	# L	00336	
2847		188C	2853		0	128B	0 6	6407																																	110C	[[6	187F	
0013		0014	0015		7	9T00	7.100	H 000																		4	0018														0018	0	0018	

; not yet time for 1 second interrupt (1/2 second)	; Set to update display	; set to change MODE every 2 seconds	; COUNT the pulses each second from the ; CS4560 EOUT pin. Every second move . the count from the counter variable (pursect)		; increment seconds ; see if we have counted 60 seconds	; if we have then increment minutes ; clear SECONDs counter every minute	watt HOURs to EE of the update Wa mlated Watt HOURs the data in EEDATA	; call EEWrite to write it	; increment MINUTEs ; if we have counted 60 minutes
P009	UPDATE,0 MODEINC,F change display MODEs ;, etc)	MODEINC, 1 MODEINC, 7	PULSECL, W PULDISPL PITTER W	PULDISPH PULSECL PULSECH	SECOND, F SECOND, W .60 STATUS, Z	IncMINUTE POP SECOND	UPDATEWH, F UPDATEWH, 3 IncMINUTE2 WATTHRL, W EEDATA 0x0D EEADDR	EEWrite WATTHRH,W EEDATA EEADDR,F EEWrite UPDATEWH	MINUTE, F MINUTE, W .60 STATUS, Z
goto	we	btfsc bsf	movf movwf	movwf clrf clrf	incf movf sublw btfsc	goto goto clrf	incf btfss goto movf movwf movwf movwwf	call movf movwf incf call clrf	incf movf sublw btfsc
00337 00338 00339 #ENDIF 00340	00342 bsf 00342 incf 00343 00344; This is how often 00345; (time, volts, cur	00347	00350000351	00354 00354 00355 00355	00357 00357 00359 00359	00361 00362 00363 IncMINUTE 00364	00365 00366 00367 00368 00370 00371	00372 00373 00374 00375 00377 00378	
28A9	1473 0AF2	18F2 17F2	082A 00AC	00AB 01AA 01A9	0AA2 0822 3C3C 1903	282C 28A9 01A2	0AB8 1DB8 283A 0828 00D6 300D	241A 0827 00D6 0AD5 241A 01B8	0AA3 0823 3C3C 1903
001B	001C 001D	001E 001F	0020	00023	0026 0027 0028 0029	002B 002B 002C 002C	002D 002E 002E 0031 0031 0033	0034 0035 0036 0037 0038 0039	003A 003B 003C 003D

; then increment the HOURs	; increment HOURs	; if we have counted 24 hours then	* * * * * * * * * * * * * * * * * * *	., save BUTTON state in BUTTONIMP, start Timer2 for debounce	; Read the Port : clear lower nibble (BITTTONs are on RB4-7)	save nibble	; clear flag (already read PORTB)	; disable PORTB interrupt	<pre>; clear Timer2 count ; clear timer2 interrupt flag</pre>	; Bank 1	turn	; Bank 0	; start timer2		****************************		(RB4-7) again	interrint on change is disabled the	rape on change is disabled,		the timer, and checks to see if the		ess is written to BUTTON, otherwise		
IncHOUR POP	MINUTE HOUR, F HOUR, W	.24 STATUS, Z HOTTE	**************************************	button was pressed,	PORTB, W	BUTTONTMP	INTCON, RBIF	INTCON, RBIE	TMR2 PIR1, TMR2IF	STATUS, RPO	PIE1, TMR2IE	STATUS, RPO	T2CON, TMR2ON	РОР	************		the BUTTONs	Aetected DORTH in	1 1 1	TIMET TE	this ISR disables		ed, the button press	Ψ	
goto goto	clrf incf mowf	sublw btfsc	GOTO GOTO ***********************************	; ISR - A bu	movf	movwf	bcf	bcf	clrf bcf	bsf	bsf	bcf	bsf	goto		for BUTT	mer2 timeout read	1 + 1 + 1 + 1 + 1 + 1 + 1 + 1 + 1		ישטאממדי	overflows,	state has changed	langes are detected,	1 S S S S S S S S S S S S S S S S S S S	
	00385 INCHOUR 00386 00387	00389 00390	00392 00393 00393	00395 ButtonISR 00396	00397	00399	00401 00402	00403	00405 00406 00407	00408	00409	00410 00411	00412 00413	00414 00415	******** 91700	; Debounce	; After Ti	00419 ; 00420 : When a h	, wilell a	, Daccoii	00423 ; When Timer2	00424 ; button s	00426; If no changes	••	00428 ;
000				00	00	000	00	00	0 0 0		0.0	00	00	00	00	00	00	000		000	00	000	00	00	00
2840 28A9	01A3 0AA4 0824	3C18 1903	28A9		39F0	00F5	100B	118B	0191 108C	1683	148C	1283	1512	28A9											
003E	0040	0043	0046	0047	0047	0049	004A	004B	004C 004D	004臣	004F	0020	0051	0052											

upt on change is then re-enabled. ************************************				ON ; turn off timer2		; bank 1	E ; disable timer2 interrupt	; bank 0		F ; clear timer2 interrupt flag		; clear button status		; read PORTB	F ; clear PORTB interrupt flag	E ; enable PORTB interrupt on change		; clear lower nibble	W ; compare with last button state	; did previous and present button states match?	; debounce good		; debounce failed ignore			ON press status	ed	(bit1 set = BUTTON 1 pressed etc)				; ignore button release			; a button was pressed		4 ; test button 1	; button 1 was pressed		5 ; test button 2	; button2 was pressed		6 ; test button 3	
. PORTB interrupt on change is then re-enabled	THE PROPERTY OF THE PROPERTY O			T2CON, TMR2ON		STATUS, RPO		STATUS, RPO		PIR1, TMR2IF		f BUTTON		f PORTB, W	INTCON, RBIF	INTCON, RBIE		llw 0xf0	wf BUTTONTMP, W	sc STATUS, Z	O ChkButtons		f BUTTONTMP	O POP		"BUTTON" returns the BUTTON press	t one BUTTON was pressed	that was pressed				sc STATUS, Z	O POP		BUTTON, 0		BUTTONIME,	BUTTON, 1		S BUTTONTMP, 5	BUTTON, 2		ss BUTTONTMP, 6	
00429 ; PORTB interrupt	Tabilta DOD	, inputs:	00434 TMR2ISR	00435 bcf	00436	00437 bsf	00438 bcf	00439 bcf	00440	00441 bcf	00442	00443 clrf	00444	00445 movf	00446 bcf	00447 bsf	00448	00449 andlw	00450 subwf	00451 btfsc	00452 goto	00453	00454 clrf	00455 goto	00456	00457 ; The variable "BI	00458 ; bit0 = at least	00459; $bit1-4 = BUTTON(s)$	00460	00461 ChkButtons		00463 btfsc	00464 goto	00465	00466 bsf	00467 Button1	00468 btfss	00469 bsf	00470 Button2	00471 btfss	00472 bsf	00473 Button3	00474 btfss	
			0053	0053 1112 (0054 1683 (108C	0056 1283 (0057 108C		0058 01F4 (0059 0806	100B	005B 158B		005C 39F0	005D 0275 (1903	005F 2862		01F5	0061 28A9 (0062	0875		0064 28A9 (0065 1474 (9900	0066 1E75 (0067 14F4 (0068	0068 1EF5		006A	006A 1F75 (

; button 3 was pressed		on 4	; button 4 was pressed				************	pulse (active low) whenever a programmed	line and the load. The !EDIR			Canaing an intermint This	deride if Wattimbehit.	2 C C C C C C C C C C C C C C C C C C C		(3600 MattGeograph) MammudyUtta is incremented	ם הם			E	the same time. This	t occur each second for true power		************	:L>, WATTHR <h:l></h:l>		**************								raw pulses per second from the CS4560	EDIR high?	increment counter			Decrement pulse count							
BUTTON, 3		BUTTONTMP, 7	BUTTON, 4		POP		******************	CS5460 outputs a pulse (actir	been transferred between the	direction of energy flow.		IROITT nin drives the INT nin of the DIC160923	examines the state of the UROIT on wis RR1 to		ייייי של הייי היייי וייייי	2	1 C C T	A MATTHE LATE AND A SECOND				unt the number of pulses that occur	lations.	***************************************	and RB1, PULSEC <h:l>, WATTTMP<h:l>,</h:l></h:l>	PULSEC <h:l>, WATTTMP<h:l>, WATTHR<h:l></h:l></h:l></h:l>	****************	JT pin (active low)	,	. I O		Watt*Sec = 1 Watt*Hr			INTCON, INTF ; raw]	PORTB, 1 ; Was	DirPlus ; yes,			PULSECL, F ; Decr	PULSECL, W	0×FF	STATUS, Z	DM1	PULSECH, F		PULSECL, 7
bsf	Button4	btfss	bsf	ButtonEnd	goto		*****************	; The !EOUT pin of the C	; amount of energy has b	the		· The IROIT nin drives t				. When the WatthMD/U: Needbea			WALLING AND LOSGO		<pre>!<h:l> count</h:l></pre>	; counter is used to count	; and power factor calculations	***************	; Inputs: Pins RB0 and		*******	; Pulse from CS4560 !EOUT pin (active low)	4 TO ST.	COLL	DT = parnd	; 360 pulses = 3600 Watt		RBOISR	bcf	btfss	goto		DirMinus	decf	novf	xorlw	btfss	goto	decf		btfss
Ŋ	ıo	00477	ω	00479 I	00480	00481	00482	00483	00484	00485	00486	78700	20400	0 0 0	00400	0 0 0	00492	10000	40400	# L	00495	00496	00497	00498	00499	00200	00501	00502	0000	20000	40000	00202	00206	7	00208	00200	00510	00511	00512 I	00513	00514	00515	00516	00517	00518	00519	00520
15F4		1FF5	1674		28A9																														108B	1086	897			03AA	082A	3AFF	1D03	287C	03A9		1 FAA
				006臣	006E 28																													006F	006F 10	0070 10	0071 28		0072	0072 03	0073 08	0074 37	0075 11	0076 28	0077 03		0078 11

				; decrement pulse count LSB	; get LSB	; test for underflow	; was there an underflow?	; no, continue		; decrement pulse count MSB	; get LSB	; test for underflow	; was there an underflow?	; no, continue		; reset counter					; decrement pulse count	; get LSB	; test for underflow	; was there an underflow?	; no, continue		; decrement pulse count	; get LSB	; test for underflow	; was there an underflow?	; no, continue		; yes, do not decrement below zero			; exit interrupt			; increment pulse count				; increment pulse count		; increment pulse count	
DM1	PULSECH	PULSECL		WATTTMPL, F	WATTTMPL, W	OXFF	STATUS, Z	POP		WATTTMPH, F	WATTTMPH, W	OXFF	STATUS, Z	POP		0x01	WATTTMPH	0x67	WATTTMPL		WATTHRL, F	WATTHRL, W	0xFF	STATUS, Z	POP		WATTHRH, F	WATTHRH, W	OXFF	STATUS, Z	POP		WATTHRL	WATTHRH		POP			PULSECL, F	DP2	PULSECH, F		WATTTMPL, F	DP1	WATTTMPH, F	
goto	clrf	clrf		decf	movf	xorlw	btfss	goto		decf	movf	xorlw	btfss	goto		movlw	movwf	movlw	movwf		decf	movf	xorlw	btfss	goto		decf	movf	xorlw	btfss	goto		clrf	clrf		goto			incfsz	goto	incf		incfsz	goto	incf	
00521	00522	00523	00524	00525 DM1	00526	00527	00528	00529	00530	00531	00532	00533	00534	00535	00536	00537	00538	00539	00540	00541	00542	00543	00544	00545	00546	00547	00548	00549	00550	00551	00552	00553	00554	00555	00556	00557	00558	00559 DirPlus	00560	00561	00562	00563	00564 DP2	00565	00566	
287C	01A9	01AA		03A6	0826	3AFF	1D03	28A9		03A5	0825	3AFF	1D03	28A9		3001	00A5	3067	0 0 A 6		03A8	0828	3AFF	1D03	28A9		03A7	0827	3AFF	1D03	28A9		01A8	01A7		28A9			OFAA	289A	0AA9		0FA6	289D	0AA5	
6400	007A	007B		007C	007D	007E	007F	0800		0081	0082	0083	0084	0085		9800	0087	0088	0089		008A	008B	0080	008D	008臣		008月	0600	0091	0092	0093		0094	0095		9600		0097	0097	0098	6600		009A	009B	0090	

	; not yet 360 pulses		; get pulse count MSB	; test for $360 \text{ pulses } (256 + 104 = 360) \text{ (1WHr)}$; was there a borrow?	; no, count raw pulse		; yes, clear counter	; yes, clear counter		; increment WattHOUR LSB		; increment WattHOUR MSB			, ************************************	STATUS, PCLATH, and FSR	called.		at the beginning of the												; return from interrupt		****************************	*	*************************		; initialize controller peripherals and some variables		; initialize the LCD module, setup registers		; and clear the LCD display
WATTTMPH,0	POP		WATTTMPL, W	0x67	STATUS, C	POP		WATTTMPL	WATTTMPH		WATTHRL, F	POP	WATTHRH, F		POP	***********	the values that were in the W, S'	interrupt was		saved in the routine a	; Interrupt vector"			TEMPPCLATH, W	PCLATH	TEMPFSR, W	FSR	TEMPSTAT, W	STATUS	TEMPW, F	TEMPM, W			************		***********		InitPeriph		InitLCD		ClrLCD
btfss	goto		movf	sublw	btfsc	goto		clrf	clrf		incfsz	goto	incf		goto	******	Restore the values tha	registers just after the		values were	program at "org 4 ; In			novf	movwf	movf	movwf	swapf	movwf	swapf	swapf	retfie		******	Program start	*******		call		call		call
00568 DP1	00569	00270	00571	00572	00573	00574	0.0575	00576	0.0577	00578	00579	00580	00581	00582	00583	***** 00282	٠.	00587 ; regi	00588;	00589 ; These	00590 ; prog	00591	00592 POP	00593	00594	00595	00596	00597	00598	00599	00900	00601	00602	****** 60900	00604 ; Prog	*	00607 Start	80900	60900	00610	00611	00612
1C25	28A9		0826	3067	1803	28A9		01A6	01A5		0FA8	28A9	0AA7		28A9									0877	008A	0876	0084	0E79	0083	0EF8	0E78	6000						2494		260B		2612
0600	3600		009月	00A0	00A1	00A2		00A3	00A4		00A5	00A6	00A7		00A8								00A9	00A9	00AA	00AB	OOAC	00AD	OOAE	00AF	00B0	00B1					00B2	00B2		00B3		00B4

**************************************	NC to the EEPROM.	a new	allow writing values to EEPROM memory.			·*************************************		the EEPROM,	; place them in variables and write to CS5460,	; initialize interrupts		; enable all interrupts		; get states of BUTTONs (normally high, active low))	; mask off low 4 bits	; are all four BUTTONs pressed?	; yes, clear the accumulated Watt HOURs from the EEPROM	; and rewrite calibration values to CS5460		; get states of buttons (normally high)	; mask off low 4 bits	; center two buttons	; are only center 2 buttons pressed	; yes, set the "Time of Day" clock			; get states of buttons (normally high)	; mask off low 4 bits	; outside two buttons	outer	; no, skip next few instructions			to calibrat	; set to digit 1 (left)	; Modify calibration registers in the CS4560		*******					; CS5460 "start continuous conversions" command	; Send the command
*****	n values in CAL.INC	ibration	instruction to allow w		WriteSer	************		InitValues				INTCON, GIE		PORTB, W	0xf0	STATUS, Z	ClearEEPROM			PORTB, W	0xf0	06×0	STATUS, Z	SetClock			PORTB, W	0xf0	09×0	STATUS, Z	Continue4		0×01	CALMODE	CALDIG	Calibrate		*******************	d at reset	here			b'11101000'	TXDATA
*******		s used	Uncomment the next instr		call	*************		call				fsd		movf	andlw	btfsc	call		Continue2	movf	andlw	sublw	btfsc	goto		Continue3	movf	andlw	sublw	btfss	goto		movlw	movwf	movlw	goto		******************	If no BUTTONs are pressed at	the real program starts		Continue4	movlw	movwf
00613			00617 ; Ur	00618;		***; 00900	00621	00622	00623	00624	00625	00626	00627	00628	00629	00630	00631	00632	00633 Cont	00634	00635	96900	00637	00638	00639		00641	00642	00643	00644	00645	00646	00647	00648	00649	00650	00651	***: 00652	00653 ; If	00654 ; th	00655		00657	00658
								222A				178B		9080	39F0	1903	21DD			9080	39F0	3C90	1903	2CB5			9080	39F0	3060	1D03	28C9		3001	00B6	3037	2B06							30E8	00BC
							_	00B5				00B6		00B7	00B8	00B9	OOBA		OOBB	00BB	OOBC	00BD	00BE	00BF		0000	0000	0001	00C2	0003	00C4		0005	9000	00C7	00C8						6000	6000	00CA

: send TXDATA only to CS5460		Display	; until a button is pressed	; Then start executing the main loop begining	with		*************		*************		*****************	E 0 4 4 5 5 5 5 5 6 5 6 6 6 6 6 6 6 6 6 6 6	tne lime interrupt routine.	acond while in this loop before execution	Oug wille in city toop belone execution		remains within this loop until 2 seconds	4	*****************				; displays current time on LCD			; 1 second passed?	; yes, displays current time on LCD.		; 2 seconds yet?	; no, skip over jump		; yes, clear MODE counter	; goto ELoop		; check buttons	; mask off unneeded bits	; compare with no pressed buttons state	; buttons pressed?	; no, wait some more		; yes, clear MODE counter
SPORG		Message		TimeLoop			************		***********		ן ר		are counted in	ים סמט אפון אפן אפן אפן אפן אפן אפן אפן אפן אפן אפ	חוכב מדרכד חוב אבר		execution	been released.	***********	, PORTB			UpdateDisplay			UPDATE, 0	UpdateDisplay		MODEINC, 7	TLoop2		MODEINC	ELOOD		PORTB, W	0xf0	0xf0	STATUS, Z	Troop		MODEINC
[e	H H H H H H	call		goto			************	; Program main loop	************) \$ '-E 4'0 [HIT AND THE STREET OF THE STRE	MINOTES, & SECONDS				If any button is pressed,		************	Inputs: UPDATE, MODEINC,	Ouputs: none		call			btfsc	call		btfss	goto		clrf	goto		movf	andlw	sublw	btfsc	goto		clrf
00659	00661	00662	00664	00665	99900	00667	****** 89900	00669 ; Progra	****	2,000			00674 ; HOUKS,	The Late of the Area of the Ar		00678		; after		•-	•	00685 TimeLoop	00686	00687	00688 TLoop	00689	06900	00691	00692	00693	00694	00695	96900	00697 TLoop2	86900	66900	00700	00701	00702	00703	00704
22FD	1	225D		28CE																			2295			1873	2295		1FF2	28D5		01F2	28DC		9080	39F0	3CF0	1903	28CF		01F2
0.00 B		0000		00CD																		OOCE	00CE		OOCF	OOCF	0000		0001	0002		0003	0004	0005	0005	0006	0007	0008	00D9		00DA

; wait forever	<pre>************************************</pre>		; read RMS Voltage from CS4560		<pre>; move received Vrms data to ; multiplicand</pre>		<pre>; load full scale voltage to ; multiplicand</pre>		, Math 16bit * 16bit multiply routine	, move result for Bin2BCD ; this is the actual voltage in binary	; Change 16 bit binary to 5 digit decimal	, clear display	; display "E" on LCD (for Volts)	; Select Bank 2
TLoop	age on LCD ********* ction of full scale, 0 ale voltage to get actu (3 byte) BCD (Binary D result is displayed, execution remains with are released.	ins data iion cootoo, ofbrib	b'00011000' TXDATA	SSPRead	RXDATAO,W AARGBO RXDATAI.W	AARGB1	MAXVOLTH BARGB0	MAXVOLTL BARGB1	FXM1616U	AARGB1,W TEMPH AARGB2,W TEMPL	Bin2BCD16	ClrLCD	0×0E	LOAGDI STATUS,RP1
goto	*************** Display Voltage on LCD; Reads RMS voltage (as fraction of fu; multiplies by the full scale voltage; converts binary to 5 digit (3 byte); The display is blanked, an "E" is wr; point is turned on. The BCD result i; 10's and 100's digits. If any button is pressed, execution; after all buttons have been released; ************************************	מ מ ד ה	movlw movwf	call	movf movwf movf	JWVOM TOVWE	movlw movwf	movlw movwf	call	movf movwf movf movwf	call	call	movlw	call bsf
00705	*	· · · I		00725	00727 00728 00729	00730	00732	00734 00735 00736	00737	00739 00740 00741 00742	00743 00744 00745	00746	00748	00750
28CF			3018 00BC	22BF	0839 0000 083A	0001	3000	30ED 00C6	25D1	0841 00D2 0842 00D1	24DC	2612	300E	261F
00DB		0000	00DC 00DD	000E	00DF 00E0	00EE	00E3 00E4	00E5 00E6	00E7	00E8 00E9 00EA	OOEC	00ED	00EE	0.400

; turn on the decimal point ; Select Bank 0	; if "Hundreds" digit is 0, leave blank	; Display 5 digits of data as decimal	; if "Tens" digit is zero, leave blank	Display 4 digits of data	Dispirary of digites of data as seconds vet?		; 1 second passed? ; yes, take new reading and display it.	; no, check buttons; mask off unneeded bits; compare with no pressed button state; button pressed?; no, wait some more	; yes, clear MODE counter; wait some more ***********************************	st digit, and the decimal
DEC6 STATUS, RP1	RO,W OxOF STATUS,Z E51.CD	WriteLCD4 WaitEl	R1,W 0x0F STATUS,Z E41,CD	WriteLCD5 WaitEl	UPDATE, 0 MODEINC, 7	MODEINC, / MODEINC ILOOP	UPDATE, 0 ELoop	PORTB,W 0xf0 0xf0 STATUS,Z WaitE	clrf MODEINC; yes, clear MODestrong controls white some more served with the first some more served on LCD ***********************************	The display is blanked, an "C" is written to the leftmost digit, and the decimal
bsf bcf	movf andlw btfsc	goto goto	swapf andlw btfsc	got110	bcf btfss	goto goto goto	btfsc goto	movf andlw sublw btfsc goto	clrf goto ****** Display Cur RMS current (as fr plies by the full s rts binary to 5 dig	isplay is blanked,
00751 00752 00753	00754 00755 00755 00757	00758	00761 ESLCD 00762 00763 00763	00765		000772 000773 000775 00777	00778 WaitE2 00779 00780 00781	0 0 0 7 8 2 0 0 0 0 8 4 0 0 0 7 8 5 0 0 7 8 6	*	00796 ; The d:
1798 1303	084E 390F 1903 2879	270C 2900	0 E 4 F 3 9 0 F 1 9 0 3	270F 2900 2712	2/12 1073 1FF2	1442 2905 01F2 290E	1873 28DC	0806 39F0 3CF0 1903 2901	01F2 2901	
00F1 00F2	00F3 00F5 00F5	0057	00F9 00FA 00FB	00FE	0100 0101 0101	0102 0102 0103 0104	0105 0105 0106	0107 0108 0109 010A 010B	010C 010D	

skipping the leading zero in the	in this loop until 2 seconds	; alter all ductons nave been released. ;************************************	UPDATE, MODEINC, PORTB				; read Irms from the CS4560				; move received data to	; multiplicand				; move full scale Current value	; to multiplicand				; Math 16bit * 16bit multiply routine		; move result for Bin2BCD	; this is actual current in binary				; Change 16 bit binary to 5 digit decimal (BCD)		; clear display		char "C" to	C	; Select Bank 2	; turn on the decimal point	; Select Bank 0		; if "tens" digit is 0, leave blank				; Display 5 digits of data as decimal
The BCD result is displayed,	1, execution remains within this)een released. :*************	Irms data from CS5460, UPD				b'00010110'	TXDATA	SSPRead		RXDATAO,W	AARGBO	RXDATA1,W	AARGB1		MAXCURRH	BARGBO	MAXCURRL	BARGB1		FXM1616U		AARGB1,W	TEMPH	AARGB2,W	TEMPL		Bin2BCD16		ClrLCD		0×00	LoadD1	STATUS, RP1	DECS	STATUS, RP1		RO,W	0×0F	STATUS, Z	CSLCD	WriteLCD4
point is turned on. The 10's digit.	If any button is pressed,	arrer all burrons nave been released. ************************************	Inputs: MAXCURR <h:l>, Ir</h:l>	Ouputs: none		đc	movlw	movwf	call		nowf	movwf	novf	movwf		movlw	movwf	movlw	movwf		call		movf	movwf	movf	movwf		call		call	1	wowlw	call	bsf	bsf	bcf		movf	andlw	btfsc	goto	call
00797 ; po 00798 ; 10 00799 ;	٠.	.**; 00800 .**;	00803 ; II	00804 ; 01	00802	00806 ILoop	00807	00808	60800	00810	00811	00812	00813	00814	00815	00816	00817	00818	00819	00820	00821	00822	00823	00824	00825	00826	00827	00828	00829	00830	0083I	00832	00833	00834	00835	00836	00837	00838	00839	00840	00841	00842
							3016	OOBC	22BF		0839	0000	083A	0001		3000	0005	30FA	9200		25D1		0841	0002	0842	0001		24DC		2612		300C	261F	1703	1519	1303		084臣	390F	1903	292B	270C
						010E	010E	010F	0110		0111	0112	0113	0114		0115	0116	0117	0118		0119		011A	011B	011C	011D		011E		011F		0120	0121	0122	0123	0124		0125	0126	0127	0128	0129

; Display 4 digits of data as decimal		; 2 seconds yet?	; no, skip over jump		yes, clear MODE counter	; go to the Apparent Power loop			; 1 second passed?	; yes, take new reading and display it.	; no, check buttons	; mask off unneeded bits	; compare with no pressed button state	; button pressed?	; no, wait some more		; yes, clear MODE counter	; wait some more			.********* Display Apparent Dower on I.CD *******************	converts the binary result to BCD. clears		(execution remains within this loop until 2 seconds		*****************************					; get Vrms, Irms, multiply, save as APH:APL(binary)		; get Apparent Power high byte			; get Apparent Power low byte			; convert binary to decimal		; clear the LCD display
WaitC1 WriteLCD5	UPDATE, 0	MODEINC, 7	WaitC2		MODEINC	APLoop			UPDATE, 0	ILoop	PORTB, W	0xf0	0xf0	STATUS, Z	WaitC		MODEINC	WaitC			parent Power on LCD	calculate apparent power.	and calls the s		1, execution remains	been released.	*******	PORTB				CalcAP		APH,W	TEMPH		APL,W	TEMPL		Bin2BCD16		ClrLCD
goto call	bcf	btfss	goto	r	clrf	goto			btfsc	goto	movf	andlw	sublw	btfsc	goto		clrf	goto			***** Display Apr	Calls routine to calcula			If any button is pressed,	aiter all buttons have been released.	*	Inputs: UPDATE, MODEINC,	Ouputs: none			call		movf	movwf		movf	movwf		call		call
00843 00844 C5LCD		00847 WaitC 00848	00849	00850	00851	00852	00853	00854 WaitC2	00855	00856	00857	00858	00859	00860	00861	00862	00863	00864	00865	00866	****** 19800			 -	•-			٠.	00875 ; Ouputs	00876	00877 APLoop	00878	00879	00880	00881	00882	00883	00884	00885	00886	00887	00888
292C 270F	1073	1FF2	2931		01F2	293A			1873	290臣	9080	39F0	3CF0	1903	292D		01F2	292D														24FF		082D	0002		082E	00D1		24DC		2612
012A 012B	0120	012D 012D	012E	[0	012F	0130		0131	0131	0132	0133	0134	0135	0136	0137		0138	0139													013A	013A		013B	013C		013D	013E		013F		0140

	; A		; P			; display power with lead zero blanking			; 2 seconds yet?	no		; yes, clear MODE counter	; goto True Power Loop		; 1 second passed?	; yes, display new Apparent Power.		; check buttons	; mask off unneeded bits	; compare with no pressed button state	; button pressed?	; no, wait some more		; yes, clear MODE counter	; wait some more		on LCD **************************	converts the binary result to BCD, clears	subroutine that displays the power result.		execution remains within this loop until 2 seconds		,*************************************					; calc True Power, Result in TPH:TPL in Watts as binary		; Pulse per second MSB	,	; Pulse per second LSB
	0×0A	LoadD1	0×10	LoadD2		DispPwr	UPDATE,0		MODEINC, 7	WaitAP2		MODEINC	TPLoop		UPDATE,0	APLOOD		PORTB, W	0×f0	0xf0	STATUS, Z	WaitAP		MODEINC	WaitAP		Power	true power,	ays "tP", and calls the s		l, execution remains	have been released.	***********	PORTB				CalcTP		TPH,W	TEMPH	TPL,W
	movlw	call	movlw	call		call	bcf		btfss	goto		clrf	goto		btfsc	goto		movf	andlw	sublw	btfsc	goto		clrf	goto		,********** Display True	Calls routine to calculate	displ		If any button is pressed,	after all buttons have b	************	Inputs: UPDATE, MODEINC, PORTB	: none			call		movf	movwf	movf
00889	00890	00891	00892	00893	00894	00895	00897 WaitAP1	00899 WaitAP	00600	00901	00902	00903	00904	00906 WaitAP2	70600	80600	60600	00910	00911	00912	00913	00914	00915	00916	00917	00918	******* 6T600	00920 ; Calls r	00921 ; the display,	•-	00923 ; If any		******* 00000	٠.	00927 ; Ouputs: none	00928	00929 TPLoop	00030	00931	00932	00933	00934
	300A	261F	3010	263A		271C	1073		1FF2	294B		01F2	2954		1873	293A		9080	39F0	3CF0	1903	2947		01F2	2947													2518		082F	00D2	0830
	0141	0142	0143	0144		0145	0146	0147	0147	0148		0149	014A	014B	014B	014C		014D	014臣	014F	0150	0151		0152	0153												0154	0154		0155	0156	0157

		; 16 bit binary to BCD routine				, t		, P			; display power with lead zero blanking				; 2 seconds yet?	; no, skip over jump		; yes, clear MODE counter	; goto Power Factor loop			; 1 second passed?			; check buttons	; mask off unneeded bits	; compare with no pressed button state	; button pressed?	; no, wait some more		; yes, clear MODE counter	; wait some more			Factor on LCD ****************************	and true power TPH:TPL.		dividing the true nower by the annarent nower		PF is displayed starting with the 1's digit.		this loop until 2 seconds	
TEMPL		Bin2BCD16		ClrLCD		0x13	LoadD1	0x10	LoadD2		DispPwr		UPDATE, 0		MODEINC, 7	WaitTP2		MODEINC	PFLOOP			UPDATE, 0	TPLOOP		PORTB, W	0xf0	0xf0	STATUS, Z	WaitTP		MODEINC	WaitTP			wer Factor on LCD *******	late apparent power APH:APL	is report	calculated by dividing the tru	converted to BCD.	display is blanked, "tP" is displayed, and the PF		d, execution remains within this loop until	oeen released.
movwf		call		call		movlw	call	movlw	call		call		bcf		btfss	goto		clrf	goto		Ol	btfsc	goto		movf	andlw	sublw	btfsc	goto		clrf	goto			******* Display Power	Calls routines to calculate	If APH:APL=0, then PF=1.000	nower factor is cald	result is	display is blanked,		any button is pressed,	1 buttons
00935	98600	00937	00938	00939	00940	00941	00942	00943	00944	00945	00946	00947	00948	00949 WaitTP	00000	00951	00952	00953	00954	00955	00956 WaitTP2	00957	00958	00959	09600	00961	00962	00963	00964	00965	99600	00967	89600	69600	********* 02600	00971 ; Calls	00972 ; If A	 	The	 00977 ; The	, 87600	00979 ; If ar	00980 ; after al
0001		24DC		2612		3013	261F	3010	263A		271C		1073		1FF2	2965		01F2	296臣			1873	2954		9080	39F0	3CF0	1903	2961		01F2	2961											
0158		0159		015A		015B	015C	015D	015E		015F		0160	0161	0161	0162		0163	0164		0165	0165	0166		0167	0168	0169	016A	016B		016C	016D											

*************************************		**************************************			exists, report back PF=1.000	zero		es compute to greater than 1.000. This		. P.F.	load charactoristics are rapdily changing.	*******			; calculate present Aparent Power		condition (APH:APL=0)	; test APH for non-zero value	; was APH zero?	; APH is non-zero, PF can be calculated		; APL may be very close to zero	; discard low 4 bits	; is APL>0x0F?	; APL is non-zero		; report PF=1.000					; jump directly to display routine	E	ulate present irue Power	, save results in TPH:TPL as Watts in binary		; load True Power						; load Apparent Power		
******	i, PORTB	*****	A D 0 / 一 D E / 一 1	,	zero condition	Vrms cannot be		in the CS5460, PF can sometimes compute to	In such cases, limit	.1 report	۵۱	****************			CalcAP		for divide by zero	APH, F	STATUS, Z	PFNZero		APL,W	0×F0	STATUS, Z	PFNZero		0×03	TEMPH	0×E8	TEMPL		PFZero	E	Calcip			TPH,W	AARGBO	TPL, W	AARGB1	AARGB2		APH,W	BARGBO	
****	UPDATE, MODEINC,	10ne ****	D &	1	then a divide by	a no load condition.		elays in the CS	is an incorrect result.	calculation will report	ally occurs only	*********			call		; checking	movf	btfss	goto		movf	andlw	btfss	goto		movlw	movwf	movlw	movwf		goto		Call			movf	movwf	movf	movwf	clrf		movf	movwf	
	; Inputs:	00983 ; Cupurs: I			00987 ; If AP=0,	; This is	: 68600	00990 ; Due to delays	00991 ; is an inc	00992 ; The next		*	00995	00996 PFLOOD		86600	66600	01000	01001	01002	01003	01004	01005	01006	01007	01008	01009 PFUnity	01010	01011	01012	01013	01014		UIUI6 FFNZero	01017	01018	01019	01020	01021	01022	01023	01024	01025	01026	
															24FF			08AD	1D03	297B		082臣	39F0	1D03	297B		3003	0002	30E8	0001		2996	Ĺ	Z518			082F	0000	0830	00C1	01C2		082D	0.005	
_														016E	016E			016F	0110	0171		0172	0173	0174	0175		0176	0177	0178	0179		017A	, 1	A/TO			017C	017D	017E	017F	0180		0181	0182	

	; divide True Power by Apparent Power	; Test AARGB1	; is AARGB1 non-zero?	; yes, report PF => 1.000		; move result for scaling					; 1000 decimal					; multiply result by 1000 decimal							and BCD is returned in R0:R1:R2	; 16 bit binary to BCD routine				ረ :		丘;				; turn on the decimal point			; Write the data as formatted decimal					
APL,W BARGB1	FXD2416U	AARGB1, F	STATUS, Z	PFUnity		AARGB1,W	AARGBO	AARGB2,W	AARGB1		0×03	BARGBO	0×E8	BARGB1		FXM1616U		AARGB1,W	TEMPH	AARGB2,W	TEMPL		HEX value in TEMPH:TEMPL (MSB:LSB)	Bin2BCD16		ClrLCD		0x10	LoadD1	0×0F	LoadD2		LCDD02	DECS	PORTA		WriteLCD5		UPDATE, 0		L CNIHHOOM	MODELNO,
movf movwf	call	movf	btfss	goto		movf	movwf	movf	movwf		movlw	movwf	movlw	movwf		call		movf	movwf	movf	movwf		; put HEX v	call		call		movlw	call	movlw	call		banksel	bsf	banksel		call		bcf		1 1 1 1 1	ט מ מ
01027 01028 01029	01030	01032	01033	01034	01035	01036	01037	01038	01039	01040	01041	01042	01043	01044	01045	01046	01047	01048	01049	01050	01051	01052	01053 PFZero	01054	01055	01056	01057	01058	01059	01060	01061	01062	3 01063	01064	3 01065	01066	01067	01068	01069	01070		7 / 0 7 0
082E 00C6	2525	08C1	1D03	2976		0841	0000	0842	0001		3003	0005	30E8	9200		25D1		0841	0002	0842	0001			24DC		2612		3010	261F	300F	263A		1283 1703	1519	1283 1303		270F		1073		1 1 1 1	7 4 4
0183	0185	0186	0187	0188		0189	018A	018B	018C		018D	018臣	018F	0190		0191		0192	0193	0194	0195		0196	0196		0197		0198	0199	019A	019B		019C	019臣	019万		01A1		01A2	, ,	0.145	0 T T O

; no, skip over jump	; yes, clear MODE counter	goto		ī	l second passed?	; go to top of Power Factor loop		; check BUTIONs	; mask off unneeded bits	; compare with no pressed BUTTONs state	; BUTTON pressed?	; no, wait some more		; yes, clear MODE counter	; wait some more	*****************	RBO/INT pin of the PIC16C923.	RB1 pin.	T T	circ parses and		energy in WAITHKH:WAITHKL, converts it to BCD, clears the display,	subroutine that displays power while blanking leading zeros.		execution remains within this loop until 2 seconds	1	***************************************	WATTHRL					; LSB of Watt hours		; MSB of Watt hours		; but HEX value in TEMPL (LSB) and TEMPH (MSB),	BCD is returned in R2 (LSB) R1 and R0 (: 16 bit binary to BCD routine			; blank display		two digits (left side)	н ′	
WaitPF2	MODEINC	WHLOOD		(E	UPDATE, 0	PFLoop		PORTB, W	0xf0	0xf0	STATUS, Z	WaitPF		MODEINC	WaitPF	Kw/Hr on LCD *****	o the	CS5460 goes to the	RROTSR AL	Catalie NEGISIN COM		total	calls the subroutine			been released.	***********	, PORTB, WATTHRH:WATTHRL				ClrLCD	WATTHRL, W	TEMPL	WATTHRH, W	TEMPH		Bin2BCD16			i i	ClrLCD		"Hr" to the first t	0x18	
goto	clrf	goto			DTISC	goto		movf	andlw	sublw	btfsc	goto		clrf	goto	**** Display			rrint			tine takes the	"Hr", and		If any button is pressed,	1 butt	*********	s: UPDATE, MODEINC,	s: none			call	movf	movwf	movf	movwf		call			ŗ	call		Write a "H	movlw	
01073	01074 01075	01076		01078 WaltPF2	67.010	01080	01081	01082	01083	01084	01085	01086	01087	01088	01089	******** T60T0	01092 ; The !!	The) + + + (٠.	٠.	01097 ; displays	01098 ;	01099 ; If an		*	٠.	01103 ; Ouputs:	01104	01105 WHLoop	01106	01107	01108	01109	01110	01111	01112	01113	01114	+ 	01115	01116	01117 ;	01118	
29A7	01F2	29B0		1	1873	296E		9080	39F0	3CF0	1903	29A3		01F2	29A3																	2612	0828	0001	0827	0002		24DC				2612			3018	
01A4	01A5	01A6	i f	01A7	01A7	01A8		01A9	01AA	01AB	OLAC	OIAD		OIAE	01AF																01B0	01B0	01B1	01B2	01B3	01B4		01B5			1	01B6			01B7	

٤.			; display result without leading zeros				; 2 seconds yet?	; no, skip over jump		; yes, clear MODE counter				; 1 second passed?	; yes, take new reading and display it		; no, check BUTTONs	; mask off unneeded bits	; compare with no pressed BUTTONs state	; BUTTON pressed?	; no, wait some more		; yes, clear MODE counter	; wait some more			**************************************		*********************************	cycle via the SPI code.	port is resynchronized by sending SYNC bytes.	****************				bit 7 which starts a reset cycle		; write to CS4560 Configuration Register	; command byte		; bits 23-16		; bits 15-8	S A	
LoadD1	LoadD2		$\mathtt{DispPwr}$		UPDATE, 0		MODEINC, 7	WaitWH2		MODEINC	TimeLoop			UPDATE, 0	WHLoop		PORTB, W	0×f0	0xf0	STATUS, Z	WaitWH		MODEINC	WaitWH			************	initialization routines	************		resets, the serial po	************				default values except	1	b'01000000'	TXDATA	p,00000000q	TXDATA0	p,00000000q	TXDATA1	b'10000001'd	
call mov/lw	call		call		bcf		btfss	goto		clrf	goto			btfsc	goto		movf	andlw	sublw	btfsc	goto		clrf	goto			******	initializa	********	the CS5460 to	CS5460 is res	*********	one	lone		; all defa		movlw	movwf	movlw	movwf	movlw	movwf	wlvom	:
01119	01121	01122	01123	01124	01125	01126 WaitWH	01127	01128	01129	01130	01131	01132	01133 WaitWH2	01134	01135	01136	01137	01138	01139	01140	01141	01142	01143	01144	01145	lo	01147 ; *******	01148 ;	01149;******	01150 ; Commands t		**********	01153 ; Inputs: none	01154 ; outputs: none	. 10	01156 ResetCS4560	_	01158	01159	01160	01161	01162	01163	01164	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
261F	263A		271C		1073		1FF2	29C1		01F2	28CE			1873	29B0		9080	39F0	3CF0	1903	29BD		01F2	29BD														3040	0.0BC	3000	0 0BD	3000	00BE	3081	
01B8	01BA		01BB		01BC	01BD	01BD	01BE		01BF	0100		0101	0101	01C2		01C3	01C4	0105	0106	01C7		01C8	0109												01CA		01CA	01CB	0100	01CD	01CE	01CF	0110)

; bits 7-0 ; send command to CS5460	*********************		3 times followed by	Port		; SYNC1 byte (0xFF)		; SYNC1 byte (0xFF)		; SYNC1 byte (0xFF)		; SYNCO byte (0xFE)		; send sync bytes to CS5460				*****************	Hours		s zeroed in the 24C01 EEPROM, and all	energy are cleared. The display			201 and written back to the CS5460.	*******************									; set data to 0	; EE address of Watt HOUR MSB			; clears WHr MSB		; clears WHr LSB		
TXDATA2 SSPWrite	******		to the CS4560 up to	alize the Serial		SYNC1	TXDATA	SYNC1	TXDATA0	SYNC1	TXDATA1	SYNCO	TXDATA2	SSPWrite				***********	accumulated Watt Hours		e total energy is	track accumlated	written to it.		read from the 240	************					ResetCS4560		M addresses		EEDATA	0×0D	EEADDR		EEWrite		EEADDR, F	EEWrite	
movwf call	**********	Initialize the CS5460 Se	Write SYNC1 (0xFF) to the	a SYNCO (0xFE) to initialize the Serial		movlw	movwf	movlw	movwf	movlw	movwf	movlw	movwf	call		return		****************	This routine clears the		The CS5460 is reset, the total energy is	internal variables that	blanked, and "CLEAr" is		Calibration values are read from the 24C01	****************	Inputs: none	outputs: none		ClearEEPROM	call		Write "00" to the EEPROM		clrf	movlw	movwf		call		incf	call	
01165	01167 01168 ;*	01169;	01170 ;	01171 ;	01172	01173	01174	01175	01176	01177	01178	01179	01180	01181	01182	01183	01184	01185 ;*	•-	01187 ;	01188 ;	01189 ;	01130 ;	01191 ;	01192 ;	*; 01103	01194 ;	01195 ;	01196	01197 Cl	01198	01199	01200 ;	01201	01202	01203	01204	01205	01206	01207	01208	01209	01210
00BF 22E1						30FF	0 OBC	30FF	0.0BD	30FF	00BE	30FE	00BF	22E1		8000															21CA				01D6	300D	0005		241A		0AD5	241A	
01D1 01D2						01D3	01D4	01D5	01D6	01D7	01D8	01D9	01DA	01DB		OIDC														01DD	01DD				01DE	OIDF	01E0		01E1		01E2	01E3	

; clear total energy		; clear pulse counter		; clear 8 minute timer		; Put the default Voltage and Current			; "C" ; Write CLEAr to the LCD		; "L"		"E" '		; "A"		; "r"			continue				; clear button state			**********	ues from the EEPROM and writes them to the	onsists of	Gain, Current Gain and Pulse Rate Gain		Rs from the EEPROM and writes it to the variables in RAM.			************						stores in WATTHRH:WATTHRL	; address of Watt HOUR MSB in EEPROM		; get byte from address in EEPROM	retrieve
WATTHRL	WATTHRH	WATTTMPH	WATTTMPL	UPDATEWH		GetDefaults		ClrLCD	0×0C	LoadD2	0x1D	LoadD3	0×0E	LoadD4	0×0A	LoadD5	0x14	LoadD6		BUTTON press to		BUTTON, 0	ClearWait	BUTTON			***********	calibration values	registers. The calibration data consists of	Offset, Voltage Gain,		accumulated Watt HOURs		at power-up.	**********						ata from EEPROM,	0x0D	EEADDR	EERead	EEDATA,W
clrf	clrf	clrf	clrf	clrf		call		call	movlw	call	movlw	call	movlw	call	movlw	call	movlw	call		; wait for		btfss	goto	clrf	return		*********	outine fetches the	gisters. The ca	e Offset, Current		fetches the accu		outine is called a	**********	: none	s: WATTHRH:WATTHRL			-	bytes of WATTHR data	movlw	movwf	call	movf
01211	01212	01213	01214	01215	01216	01217	01218	01219	01220	01221	01222	01223	01224	01225	01226	01227	01228	01229	01230	01231 ClearWait	01232	01233	01234	01235	01236	01237	01238 ,******	01239 ; This rout	01240 ; CS4560 re	01241 ; Voltage O	01242 ;	01243 ; It also f	٠.	01245 ; This rout	01246 ,*******	01247 ; Inputs: n	01248 ; outputs:	01249	01250	01251 GetDefaults	01252 ; gets 2 by	01253	01254	01255	01256
01A8	01A7	01A5	01A6	01B8		21F9		2612	3000	263A	301D	2655	300臣	2670	300A	268B	3014	26A6				1C74	29F5	01F4	8000																	300D	0005	242A	0856
01E4	01E5	01E6	01E7	01E8		01E9		01EA	01EB	01EC	01ED	01EE	01EF	01F0	01F1	01F2	01F3	01F4		01F5		01F5	01F6	01F7	01F8															01F9		01F9	Olfa	01FB	01FC

; store in RAM	<pre>; next higher EEPROM address ; get byte from address in EEPROM ; retrieve data ; store in RAM</pre>	; write to CS5460 Voltage Gain register	; address in EEPROM for Voltage Gain MSB ; get voltage gain constant from EEPROM, ; write to corresponding registers in CS5460	; write to CS5460 Current Gain register ; address in EEPROM for Current Gain MSB	<pre>; get current gain constant from EBPROM, ; write to corresponding registers in CS5460 ; write to CS5460 Voltage offset register ; store in TX buffer</pre>	; address of Voltage Offset MSB in EEPROM ; get voltage offset constant from EEPROM, ; write to corresponding registers in CS5460	; write to CS5460 Current offset register ; store in TX buffer	; address in EEPROM for Current Offset MSB	; get current offset constant from EEPROM, ; write to corresponding registers in CS5460
WATTHRL	EEADDR,F EERead EEDATA,W WATTHRH	UPDATEWH b'01001000' TXDATA	0x07 EEADDR Init5460	b'01000100' TXDATA 0x0A	EEADDR Init5460 b'01000110' TXDATA	0x01 EEADDR Init5460	b'01000010' TXDATA	0×04 EEADDR	Init5460
movwf	incf call movf movwf	clrf ge Gain movlw	movlw movwf call	Current Gain movlw movwf movwf movlw	Offse		nt Offset movlw movwf	movlw movwf	call Pulse Rate
01257	01259 01260 01261 01262	01264 01265 01266; Voltage 01267 01268		••	01280 01281 01282 01283 01284 ; Voltage 01285 01286		01293 ; Current 01294 01295	01297 01298 01299	01300 01301 01302 ; Pulse
0048	0AD5 242A 0856 00A7	01B8 3048 00BC	3007 00D5 221D	3044 00BC 300A	00D5 221D 3046 00BC	3001 00D5 221D	3042 00BC	3004 00D5	221D
01FD	01FE 01FF 0200 0201	0202 0203 0204	0205 0206 0207	0208 0209 020A	020B 020C 020D 020D	020F 0210 0211	0212	0214	0216

	; store in TX buffer		; address in EEPROM for Pulse Rate MSB			; get Pulse Rate constant from EEPROM,	write to c			*********************************	transmit buffer		* * * * * *					; get byte from address in EEPROM	; retreive data	; store in TX buffer			; get byte from address in EEPROM	; retreive data	; store in TX buffer		; point to next address	; get byte from address in EEPROM	; retreive data	; store in TX buffer		; send TX buffer to CS5460				**********	the start	the locations PWRUPAA and PWRUP55 contain 0xAA and 0x55, respectively	locations PWRUPAA and PWRUP55 contain random data.		the warm start data is written to PWRUPAA and PWRUP55, memory is cleared,	and calibration data is rewritten to it.
b'01001100'	TXDATA		0×0F	EEADDR		Init5460				************	OM, puts them into	transmi	************	CS5460 command	Address in EEPROM			EERead	EEDATA, W	TXDATA0		EEADDR, F	EERead	EEDATA, W	TXDATA1		EEADDR, F	EERead	EEDATA, W	TXDATA2		SSPWrite				************	start or a "cold"	when	when the		occurred, the warm st	calibration data
movlw	movwf		movlw	movwf		call		return		******	3 bytes from EEPROM,	60 comman	*******	: TXDATA CS546	EEADDR	s: none		call	movf	movwf		incf	call	movf	movwf		incf	call	movf	movwf		call		return			"warm"	m" start has occurred	d" start has occurred		start has	CS5460 is reset and
01303	01304	01305	01306	01307	01308	01309	01310	01311	01312			Sends			01318 ;	01319 ; Outputs:	01321 Init5460	01322	01323	01324	01325	01326	01327	01328	01329	01330	01331	01332	01333	01334	01335	01336	01337	01338	01339	**********		 01343 ; A "warm"	 01344 ; A "cold"	01345 ;	; If a	01347 ; the CS
304C	00BC		300F	0005		221D		0008										242A	0856	0 0BD		0AD5	242A	0856	0 OBE		0AD5	242A	0856	00BF		22E1		8000								
0217	0218		0219	021A		021B		021C									021D	021D	021圧	021F		0220	0221	0222	0223		0224	0225	0226	0227		0228		0229								

; if serial # = 0, no data		; if serial # = FF, no data			; get device seriai number	; store in temporary variable		; change to "display data"			o clear	; clear all pending peripheral interrupts	; clear all remaining interrupts and	; some interrupt enable flags		; select page 1		; Interrupt on RBO/INT falling edge					; enable Timer1 interrupt		; enable CCP1 interrupt		; select page 0		; enable RBO/INT pin interrupt	; enable change on PORTB interrupt	; enable peripheral interrupts				****************	*	*	***************************************				
STATUS,Z ConfigInt	SERNUM, W Oxff	STATUS, Z	ConfigInt		SEKNOM, W	LCDTEMP1	Get7SegDat	SERNUM		ınt	PORTB, W	PIR1	INTCON			STATUS, RPO		b'10111111'	OPTION_REG	I	PIE1		PIE1, TMR1IE		PIE1, CCP1IE	•	STATUS, RPO		INTCON, INTE	INTCON, RBIE	INTCON, PEIE				**********	scrolling message		*********	POINTER			
btfsc goto	movf	btfsc	goto		INONI	movwf	call	movwf	i	; contigure	MOVI	clrf	clrf			psf		movlw	movwf		clrf	TMR10SC	bsf		þsf		bcf		bsf	bsf	bsf		return		***********	the initial	23 WAtt Hour	******	Inputs: BUTTON, UPDATE,	Outputs: LCD display		
01394 01395	01396 01397 01398	01399	01400	01401	O T 4 O Z	01403	01404	01405		01407 Configint	01408	01409	01410	01411	01412	01413	01414	01415	01416	01417	01418	#IFDEF		01421 #ELSE		01423 #ENDIF	01424	01425	01426	01427	01428	01429	01430	01431	01432 ,*****			*		01437 ; Outputs:	01438	01439 Message
1903 2A50	0835 3CFF	1903	2A50	L (0835	0000	27B0	00B5			9080	018C	018B			1683		30BF	0081		018C				150C		1283		160B	158B	170B		8000									
0246 0247	0248	024A	024B		0.440	024D	024臣	024F		0250	0220	0251	0252			0253		0254	0255		0256				0257		0258		0259	025A	025B		025C									025D

; POINTER is the charactor in the string . We are doing to display	; we are going to arightar, ; save to temporary variable		; Call the table to get offset into Get7SegDat	; LCD position 1		; next character	; at end of message, start over				; LCD position 2							; LCD position 3							; LCD position 4							; LCD position 5							; LCD position 6					
POINTER, W	1111111		Msg	LoadD1	PTRTMP, F	Disp2	.31	PTRTMP		Msg	LoadD2	PTRTMP, F	Disp3	.31	PTRTMP		Msg	LoadD3	PTRTMP, F	Disp4	.31	PTRTMP		Msg	LoadD4	PTRTMP, F	Disp5	.31	PTRTMP		Msg	LoadD5	PTRTMP, F	Disp6	.31	PTRTMP		Msg	LoadD6	PTRTMP, F	Disp7	.31	PTRTMP	
movf	1 2		call	call	decfsz	goto	movlw	movwf		call	call	decfsz	goto	movlw	movwf		call	call	decfsz	goto	movlw	movwf		call	call	decfsz	goto	movlw	movwf		call	call	decfsz	goto	mov1w	movwf		call	call	decfsz	goto	movlw	movwf	
01440	01442	01443	01444	01445	01446	01447	01448		01450 Disp2	01451	01452	01453	01454	01455	01456	01457 Disp3	01458	01459	01460	01461	01462	01463	01464 Disp4	01465	01466	01467	01468	01469	01470	01471 Disp5	01472	01473	01474	01475	01476	01477	01478 Disp6	01479	01480	01481	01482	01483	01484	01485 Disp7
0833	#		27D6	261F	0BB4	2A65	301F	00B4		27D6	263A	0BB4	2A6B	301F	00B4		27D6	2655	0BB4	2A71	301F	00B4		27D6	2670	0BB4	2A77	301F	00B4		27D6	268B	0BB4	2A7D	301F	00B4		27D6	26A6	0BB4	2A83	301F	00B4	
025D	1		025F	0260	0261	0262	0263	0264	0265	0265	0266	0267	0268	0269	026A	026B	026B	026C	026D	026E	026F	0270	0271	0271	0272	0273	0274	0275	0276	0277	0277	0278	0279	027A	027B	027C	027D	027D	027E	027F	0280	0281	0282	0283

; LCD position 7	; LCD position 8 ; Wait a second before scrolling	scrolling ; any BUTTONs pressed? ; yes, continue with program ait ; wait for 1 second timer tick	clrf UPDATE ; 1 second passed, clear counter goto Message ; redisplay message, scrolled 1 char left ***********************************	; Clear the LCD display ; get the HEX value for seconds ; LSB ; MSB (SECONDs are never > 256) ; change to BCD ; write seconds to LCD digit 8
Msg LoadD7 PTRTMP,F Disp8 .31 PTRTMP	Msg LoadD8 POINTER,F MessageWait .31 POINTER	second before scro BUTTON, 0 UPDATE, 0 MessageWait	clrf UPDATE ; 1 segoto Message ; redigoto Message ; redigoto Message ; redigoto in the current time to the LCD display. The Current time to the LCD display. The Display, convert SECOND to BCD, write to the MINUTE to BCD, write the BCD result to the HOUR to BCD, write the BCD result to the the colons. The colons. SECOND, MINUTE, HOUR LCD display	ClrLCD ClrLCD SECOND,W TEMPL TEMPH Bin2BCD16 R2,W LCDTEMP2 0x0f LCDTEMP2 LCDTEMP2 LCDTEMP2
call call decfsz goto movlw movwf	call call decfsz goto movlw movwf	; Wait a btfsc return btfss goto	clrf U goto M *************** the current time to th the Display, convert SE MINUTE to BCD, write HOUR to BCD, write th 1 the colons. ***********************************	splay ; Writes Time call movf movwf clrf call movf movwf andlw call swapf
•	01492 D1sp8 01493 01494 01495 01496 01497	01499 01500 MessageWait 01501 01502 01504 01505		01521 UpdateDisplay 01522 01523 UpdDisp 01524 01525 01526 01527 01529 01530 01531
27D6 26C1 0BB4 2A89 301F	27D6 26DC 0BB3 2A8F 301F	1874 0008 1C73 2A8F	01F3 2A5D	2 612 0 822 0 102 0 400 0 850 0 850 0 871 2 600 0 671
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	H D C B B B B B B B B B B B B B B B B B B	0 2 8 F 0 2 8 F 0 2 9 1 0 2 9 1	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

<u>د</u> د د	\sim							; On LCD digit 6			; and 5	; Display HOURs							; On LCD digit 4			; and 3		; Turn on the colons					***************************************	* PORT	,*************************************	hich register to read)	.ved data buffer)		; CS4560 chip select pin7 low	; CS4560 register to read	; put it in SSPBUF the start read	; clear flag	; wait for SSP to be ready	•	י אפפרטי	י כוכמו וומק	
0x0f	MINCTE, W	TEMPL	TEMPH	Bin2BCD16	R2,W	LCDTEMP2	0x0f	LoadD6	LCDTEMP2, W	0x0f	LoadD5	HOUR, W	TEMPL	TEMPH	Bin2BCD16	R2,W	LCDTEMP2	0x0f	LoadD4	LCDTEMP2, W	0x0f	LoadD3	LCDD11	COLON2	COLON3	PORTA	UPDATE,0		***********) through the SSP	***********	nand specifying w	L, RXDATA2 (recei		CS	TXDATA, W	SSPBUF	PIR1, SSPIF	PIR1, SSPIF	- □	PTP1 CCDTF	FINT, COFIL	SSFBOF, W
andlw res	movf	movwf	clrf	call	movf	movwf	andlw	call	swapf	andlw	call	movf	movwf	clrf	call	movf	movwf	andlw	call	swapf	andlw	call	banksel	psf	þsf	banksel	bcf	return	************	data from the CS4560	******	Inputs: TXDATA (read command specifying which register to	Outputs: RXDATA0, RXDATA1, RXDATA2 (received data buffer)		bcf	movf	movwf	bcf	btfss	goto	7 7 7	, CL	MOVI
01532	01534	01535	01536	01537	01538	01539	01540	01541	01542	01543	01544	01545	01546	01547	01548	01549	01550	01551	01552	01553	01554	01555	01556	01557	01558	01559	01560	01561			******* 01265	٠.	01567 ; Outputs	01569 SSPRead	01570	01571	01572	01573	01574	01575	7740	11 00 00 11 0	77.510
390F	0823	0001	01D2	24DC	0820	00F1	390F	26A6	0E71	390F	268B	0824	0001	01D2	24DC	0820	00F1	390F	2670	0E71	390F	2655	1283 1703	149B	141B	1283 1303	1073	0008							1105	0830	0093	118C	1D8C	2AC3	Σα) r	UBIS
029月	02A1	02A2	02A3	02A4	02A5	02A6	02A7	02A8	02A9	02AA	02AB	02AC	02AD	02AE	02AF	02B0	02B1	02B2	02B3	02B4	02B5	02B6	02B7	02B9	02BA	02BB	02BD	02BE						02BF	02BF	02C0	02C1	02C2	02C3	02C4	よりつつ	0 0	9.7.0

				; dummy byte 1						; read the returned data and put in variable	; MSB		; dummy byte 2								; dummy byte 3							; LSB		; CS4560 chip select pin back high		***************************************		data will be in	*	**************************************	মুন্ত মুন্ত				; set CS4560 chip select pin 7 low	; clear the flag		; get command (or register)
		send "SYNC1"s		SYNCI	SSPBUF	PIR1, SSPIF	PIR1, SSPIF	- ₽ - 1	PIR1, SSPIF	SSPBUF, W	RXDATA0		SYNC1	SSPBUF	PIR1, SSPIF	PIR1, SSPIF	- 2	PIR1, SSPIF	SSPBUF, W	RXDATA1	SYNCI	SSPBUF	PIR1, SSPIF	PIR1, SSPIF	\$-1	PIR1, SSPIF	SSPBUF, W	RXDATA2		CS		************		TXDATA and the	, and TXDATA2 (LSB)	***********	A1, TXDATA2, TXDATA3				CS	PIR1, SSPIF		TXDATA,W
	send three dummy bytes	in this case we send "		movlw	movwf	bcf	btfss	goto	bcf	movf	movwf		movlw	movwf	bcf	btfss	goto	bcf	movf	movwf	movlw	movwf	bcf	btfss	goto	bcf	movf	movwf		bsf	return	****************	e data to	The commmand will be in TXDATA	TXDATA0 (MSB), TXDATA1,	***************	Inputs: TXDATA, TXDATA1, TXDATA2,			SSPWrite	bcf	bcf		novf
01578	•-	٠.	01581	01582	01583	01584	01585	01586	01587	01588	01589	01590	01591	01592	01593	01594	01595	01596	01597	01598	01599	01600	01601	01602	01603	01604	01605	01606	01607	01608	01609		•-	01613 ; '	01614 ; '	01615 ;*	01616 ;	01617 ; (01618	01619 SS	01620	01621	01622	01623
				30FF	0093	118C	1D8C	2ACA	118C	0813	00B9		30FF	0093	118C	1D8C	2AD2	118C	0813	00BA	30FF	0093	118C	1D8C	2ADA	118C	0813	00BB		1505	8000										1105	118C		083C
				02C7	02C8	0209	02CA	02CB	02CC	02CD	02CE		OZCF	02D0	02D1	02D2	02D3	02D4	02D5	02D6	02D7	02D8	02D9	02DA	02DB	02DC	02DD	02DE		OZDF	02E0									02E1	02E1	02E2		02E3

; put it in SSPBUF	; wait for SSP to be ready		; dummy read, discard byte	; command byte sent, clear flag		; get first data byte	; send data byte 0 (MSB)	; wait for SSP to be ready		; dummy read, discard byte	; first data byte sent, clear flag			; send data byte 1	; wait for SSP to be ready			; second data byte sent, clear flag			; send data byte 2 (LSB)	; wait for SSP to be ready		; dummy read, discard byte	; third data byte sent, clear flag		; set CS4560 chip select pin back high					*		, ************************************					; set CS4560 chip select pin 7 low		; get command		; clear interrupt flag	; loop waiting for command to be sent	
SSPBUF	PIR1, SSPIF	\$-1	SSPBUF, W	PIR1, SSPIF		TXDATA0,W	SSPBUF	PIR1, SSPIF	\$-1	SSPBUF, W	PIR1, SSPIF		TXDATA1,W	SSPBUF	PIR1, SSPIF	\$-1	SSPBUF, W	PIR1, SSPIF		TXDATA2,W	SSPBUF	PIR1, SSPIF	\$-1	SSPBUF, W	PIR1, SSPIF		CS			**************		to the CS4560	TXDATA	******					CS		TXDATA,W	SSPBUF	PIR1, SSPIF	PIR1, SSPIF	· 다 - 다
movwf	btfss	goto	movf	bcf		movf	movwf	btfss	goto	movf	bcf		movf	movwf	btfss	goto	movf	bcf		movf	movwf	btfss	goto	movf	bcf		bsf		return	******		e a 1 byte command	command will be in	*************	Inputs: TXDATA	Outputs: none		r	bcf		movf	movwf	bcf	btfss	goto
01624	01625	01626	01627	01628	01629	01630	01631	01632	01633	01634	01635	01636	01637	01638	01639	01640	01641	01642	01643	01644	01645	01646	01647	01648	01649	01650	01651	01652	01653	01654	n n	26 ;	57	01658 ;***	01659 ; Inp	01660 ; Out	01661	01662 SSPCmd	01663	01664	01665	01666	01667	01668	01669
0093	1D8C	2AE5	0813	118C		083D	0093	1D8C	2AEB	0813	118C		083臣	0093	1D8C	2AF1	0813	118C		083F	0093	1D8C	2AF7	0813	118C		1505		8000										1105		0830	0093	118C	1D8C	2B01
02E4	02E5	02E6	02E7	02E8		02E9	02EA	02EB	02EC	02ED	025万		02EF	02F0	02F1	02F2	02F3	02F4		02F5	02F6	02F7	02F8	02F9	02FA		02FB		OZFC									02FD	02FD		02FE	02FF	0300	0301	0302

		pin back high										MCLR.																to			r to								offset	***			
; command sent		; set CS4560 chip select pi			************	rily change the calibration		the EEPROM and will be lost when the	sthod is required to write			BUTTONs 1 and 4 and while pressing MCLR		and CALDIG are set to 0x01			0	Voltage Gain	Current Gain			displayed on the LCD.		S CS4560		V OFF, C GA, C OFF, P GA)		modify. The decimal point next			is reached the digit rolls over	ing the lower nibble does					calibration variable to adjust	4 = Pulse	1 = current offset 0 = voltage	***************************************			
SSPBUF, W		CS			Calibrate ********	the user to temporarily	50.	written to	lost. Some other method	EEPROM.		executed by holding BUT7		routine CALMODE	and Digit 1)		displayed on the LCD	Offset, CAL E GA = 1	Offset, CAL C GA = 0	e gain	1	from the CS4560 and c		current value to the		gh the Modes (V GA,		next hex digit to	s turned on.		the digit, when "F"	is changed (overflowing	nibble).		this routine.		1 0) selects	= don't care	= voltage gain	***************	BUTTON, CALDIG		
novf		bsf		דם במרחדו	T[8] ************************************	_	es used in the	These values are NOT	power to the unit is	these values to the		This routine is exec			(voltage offset MODE		CAL "MODE" is first	CAL EOFF = Voltage O	CAL COFF = Current O	CAL P GA = Pulse Rate		That value is read f		BUTTON 1 writes the		BUTTON 2 steps through		Button 3 selects the	the selected digit is		increments	0. Only one digit i	not increment upper		Reset (!MCLR) exits		CALMODE (7 6 5 4 3 2		3 = current gain 2	**************	CALMODE,	Outputs:	
01670	01671		01673	01674	1676	1677	01678;	01680 ;	01681 ;	01682 ;	01683 ;	01684 ;	01685 ;	01686 ;	01687	01688 ;	01689;	01690	01691 ;	01692 ;	01693 ;	01694 ;	01695	01696 ;	01697 ;	01698 ;	01699 ;	01700 ;	01701 ;	01702 ;	01703 ;	01704 ;	01705 ;	01706 ;	01707;	01708 ;	, 60110	01710 ;	1711	1712	01713 ;	01714 ;	71715
0813		1505		0																																							
0303		0304	L C	0000																																							

; clear button state	; read Voltage Offset command		; get voltage offset from CS5460		; blank the LCD display	; "C"		; "A"		; "L"					; test for voltage mode	; not voltage mode			; display "E"				; test for current mode	; not current mode		; assume Pulse Rate mode, "C"	; display "C"		; assume Pulse Rate mode, "P"	; display "E", "C", or "P"				; test for offset mode	; display "OFF"			; "G" ;		, "A" ;		
BUTTON	b'00000110'	TXDATA	SSPRead		ClrLCD	0×0C	LoadD1	0×0A	LoadD2	0x1D	LoadD3		CALMODE, W	B'00000101'	STATUS, Z	CalCur		0×0E	SendE5		CALMODE, W	B'00001010'	STATUS, Z	CalPul		0×0C	SendE5		0×10	LoadD5		CALMODE, W	B'00000011'	STATUS, Z	SendOff		"GA"	90×0	LoadD7	0×0A	LoadD8	Cal1
clrf	movlw	movwf	call		call	movlw	call	movlw	call	movlw	call		movf	andlw	btfsc	goto		movlw	goto		movf	andlw	btfsc	goto		movlw	goto		movlw	call		movf	andlw	btfss	goto		; display "	movlw	call	movlw	call	goto
01716 Calibrate 01717	01/10	01720	01721	01722	01723	01724	01725	01726	01727	01728	01729	01730	01731	01732	01733	01734	01735	01736	01737	01738	01739 CalCur	01740	01741	01742	01743	01744	01745	01746	01747 CalPul	O1/49 O1749 SendE5	01750	01751	01752	01753	01754	01755	01756	01757 SendGA	01758	01759	01760	01761
01F4	3006	OOBC	22BF		2612	300C	261F	300A	263A	301D	2655		0836	3905	1903	2B17		300m	2B1E		0836	390A	1903	2B1D		300C	2B1E		3010	268B		0836	3903	1D03	2B28			3006	26C1	300A	26DC	2B2E
0306	0307	0	0309		030A	030B	030C	030D	030臣	030F	0310		0311	0312	0313	0314		0315	0316		0317	0318	0319	031A		031B	031C		031D	031臣		031F	0320	0321	0322			0323	0324	0325	0326	0327

	"0" ;		; "F"		; "F"				; was BUTTON 2 pressed? (step through modes)	; no, wait some more			; clear button state			; digit 1 selected		0 command -	; test for Voltage Offset MODE	; read CS5460 register		; CS5460 command - Read Current Offset	; test for Current Offset MODE	; read CS5460 register		0 command -		; read CS5460 register		0 command - Read		; read CS5460 register		; CS5460 command - Read Pulse Rate Gain			; move data to TX command buffer	; get data from CS5460	; send HEX data to display		; bank 2	; turn on decimal point next to digit 1	; bank 0	
"OFF"	00×0	LoadD6	0×0F	LoadD7	0×0F	LoadD8			BUTTON, 2	Cal1			BUTTON		CALDIG	CALDIG, 0		b,00000110,	CALMODE, 0	GetCal		p,00000010,	CALMODE, 1	GetCal		p,00001000,	CALMODE, 2	GetCal		p,00000100,	CALMODE, 3	GetCal		p,00001100,		60 register	TXDATA	SSPRead	WriteLCD		STATUS, RP1	DEC1	STATUS, RP1	
play	movlw	call	movlw	call	movlw	call			btfss	goto			clrf		clrf	psf		movlw	btfsc	goto		movlw	btfsc	goto		movlw	btfsc	goto		movlw	btfsc	goto		movlw		; read CS5460	movwf	call	call		bsf	bsf	bcf	
01763 SendOff	01764	01765	01766	01767	01768	01769	01770	01771 Call	01772	01773	01774	01775 DispCal	01776	01777	01778	01779	01780	01781	01782	01783	01784	01785	01786	01787	01788	01789	01790	01791	01792	01793	01794	01795	01796	01797	01798	01799 GetCal	01800	01801	01802	01803	01804	01805	01806	01807
	3000	26A6	300F	26C1	300F	26DC			1D74	2B2E			01F4		01B7	1437		3006	1836	2B40		3002	18B6	2B40		3008	1936	2B40		3004	19B6	2B40		300C			OOBC	22BF	26F7		1703	159A	1303	
0328	0328	0329	032A	032B	032C	032D		032E	032臣	032F		0330	0330		0331	0332		\sim	0334	0335		0336	\sim	0338		0339	\sim	033B		033C	\sim	033臣		033万		0340	0340	0341	0342		0343	0344	0345	

; clear all BUTTON readings		; was a BUTTON pressed?	; no, wait some more		; was BUTTON 1 pressed? (write to CS5460)	; yes, copy RXDATA buffer to TXDATA buffer and send		; was BUTTON 2 pressed? (step through MODEs)	; check another BUTTON			; clear button states		; clear carry bit before rotate		; step to next calibrate MODE	; test for valid calibrate MODE	; back to top of calibrate MODE loop (start over)		; clear invalid MODE	; reset to Voltage Offset	; back to top of calibrate MODE loop (start over)			; was BUTTON 3 pressed? (select hex digit)	; yes	; was BUTTON 4 pressed? (increment digit)	; yes		ř	; wait for a BUTTON press		BUTTON	; clear carry bit before rotate instruction	; select next higher digit	; test for digit7 (invalid digit)	; valid digit selected		; invalid digit selected	; Reset CALDIG to digit 1 (MSB)		; clear BUTTON data		; is digit 1 selected?
BUTTON		BUTTON, 0	Cal2		BUTTON, 1	WriteCS4560		BUTTON, 2	ChkButton3			BUTTON		STATUS, C		CALMODE, F	CALMODE, 5	Calibrate		CALMODE, 5	CALMODE, 0	Calibrate			BUTTON, 3	NextDigit	BUTTON, 4	WhichDigit		BUTTON	Cal2		BUTTON	STATUS, C	CALDIG, F	CALDIG,6	WhichDec		0×01	CALDIG		BUTTON		CALDIG,0
clrf		btfss	goto		btfsc	goto		btfss	goto			clrf		bcf		rlf	btfss	goto		bcf	psf	goto			btfsc	goto	btfsc	goto		clrf	goto		clrf	bcf	rlf	btfss	goto		movlw	movwf		clrf	,	btfsc
01808	01809 Cal2	01810	01811	01812	01813	01814	01815	01816	01817	01818	01819 IncCal	01820	01821	01822	01823	01824	01825	01826	01827	01828	01829	01830	01831	01832 ChkButton3	01833	01834	01835	01836	01837	01838	01839	01841 NextDigit	01842	01843	01844	01845	01846	01847	01848	01849	01850 WhichDec	01851	01852	01853
01F4		1C74	2B47		18F4	2BC5		1D74	2B55			01F4		1003		0DB6	1EB6	2B06		12B6	1436	2B06			19F4	2B5B	1A74	2B8C		01F4	2B47		01F4	1003	0DB7	1F37	2B62		3001	00B7		01F4		1837
0346	0347	0347	0348		0349	034A		034B	034C		034D	034D		034臣		034F	0320	0351		0352	0353	0354		0355	0355	0356	0357	0358		0359	035A	035B	035B	0350	035D	Ω	035F		0360	0361	0362	0362		0363

; yes, modify digit 1	; is digit 2 selected?	; yes, modify digit 2		; is digit 3 selected?	; yes, modify digit 3		; is digit 4 selected?	; yes, modify digit 4		; is digit 5 selected?	; yes, modify digit 5		; modify digit 6		; select bank 2	; turn off decimal point 7	; turn on decimal point 1	; select bank 0	; wait for BUTTON press		; select bank 2	; turn off decimal point 1	; turn on decimal point 2	; select bank 0	; wait for BUTTON press		; select bank 2	; turn off decimal point 2	; turn on decimal point 3	; select bank 0	; wait for BUTTON press		; select bank 2	; turn off decimal point 3	; turn on decimal point 4	; select bank 0	; wait for BUTTON press		; select bank 2	; turn off decimal point 4	; turn on decimal point 6	; select bank 0	; wait for BUTTON press	
DigitOne	CALDIG, 1	DigitTwo		CALDIG, 2	DigitThree		CALDIG, 3	DigitFour		CALDIG, 4	DigitFive		DigitSix		STATUS, RP1	DEC7	DEC1	STATUS, RP1	Cal2		STATUS, 6	DEC1	DEC2	STATUS, RP1	Cal2		STATUS, 6	DEC2	DEC3	STATUS, RP1	Cal2		STATUS, 6	DEC3	DEC4	STATUS, RP1	Cal2		STATUS, 6	DEC4	DEC6	STATUS, RP1	Cal2	
goto	btfsc	goto		goto		bsf	bcf	bsf	bcf	goto		bsf	bcf	bsf	bcf	goto		bsf	bcf	bsf	bcf	goto		bsf	bcf	bsf	bcf	goto		bsf	bcf	bsf	bcf	goto	ı									
01854	01856	01857	01858	01859	01860	01861	01862	01863	01864	01865	01866	01867	01868	01869 DigitOne	01870	01871	01872	01873	01874	01875 DigitTwo	01876	01877	01878	01879	01880	01881 DigitThree	01882	01883	01884	01885	01886	01887 DigitFour	01888	01889	01890	01891	01892	01893 DigitFive	01894	01895	01896	01897	01898	01899 Digitsix
2B6E	18B7	2B73		1937	2B78		19B7	2B7D		1A37	2B82		2B87		1703	1218	159A	1303	2B47		1703	119A	169A	1303	2B47		1703	129A	1799	1303	2B47		1703	1399	1699	1303	2B47		1703	1299	1798	1303	2B47	
0364	0365	0366		0367	0368		0369	036A		036B	036C		036D	036臣	036臣	036F	0370	0371	0372	0373	0373	0374	0375	0376	0377	0378	0378	0379	037A	037B	037C	037D	037D	037臣	037F	0380	0381	0382	0382	0383	0384	0385	0386	0387

; select bank 2	point 7	st bank 0	; wait for BUTTON press		; clear BUTTON data		; is digit 1 selected?	; yes, increment digit 1		; is digit 2 selected?	; yes, increment digit 2		; is digit 3 selected?	; yes, increment digit 3		; is digit 4 selected?	; yes, increment digit 4		; is digit 5 selected?	; yes, increment digit 5		; increment digit 6		; get digit data	; increment digit	; store digit data	; update display	; turn on decimal point 1		; get digit data	β	; was there a digit overflow?	; no, display digit		; save result to buffer		; decrement upper digit		; save result	; update display	; turn on decimal point 2	; get digit data
STATUS,6	DEC7	STATUS, RP1	Ca12		BUTTON		CALDIG, 0	Incone		CALDIG,1	IncTwo		CALDIG,2	IncThree		CALDIG, 3	IncFour		CALDIG,4	IncFive		Incsix		RXDATAO,W	0x10	RXDATAO	WriteLCD	WhichDec		RXDATAO,W	0x01	STATUS, DC	IncTwo2		RXDATA0	0x10	RXDATAO, W		RXDATA0	WriteLCD	WhichDec	RXDATA1,W
bsf fr	bsf	bcf	goto		clrf		btfsc	goto		goto		movf	addlw	movwf	call	goto		movf	addlw	btfss	goto		movwf	movlw	subwf		movwf	call	goto	movf												
01900	01902	01903	01904	01906 WhichDigit	01907	01908	01909	01910	01911	01912	01913	01914	01915	01916	01917	01918	01919	01920	01921	01922	01923	01924	01925	01926 Incone	01927	01928	01929	01930	01931	01932 IncTwo	01933	01934	01935	01936	01937	01938	01939	01940	01941 IncTwo2	01942	01943	01945 IncThree
1703	1618		2B47		01F4		1837	2B98		18B7	2B9D		1937	2BA7		19B7	2BAC		1A37	2BB6		2BBB		0839	3E10	0 0 B 9	26F7	2B62		0839	3E01	1C83	2BA4		00B9	3010	0239		0 0B9	26F7	2B62	083A
0387	00	038A	ω	0386	∞		∞	038圧		038F	0390		0391	0392		0393	0394		0395	\circ		0397		D	0399	039A	039B	0390		039D	039圧	039F	03A0		03A1	03A2	03A3		03A4	03A5	03A6	03A7

	; increment digit	; update display	; turn on decimal point 3		; get digit data	; increment digit	; was there a digit overflow?	; no, display digit		; save result		; decrement upper digit		; save result	; update display	; turn on decimal point 4		; get digit data	; increment digit	; save result	; update display	; turn on decimal point 5		; get digit data	; increment digit	; was there a digit overflow?	; no, display digit		; save result		; decrement upper digit		; save result	; update display	; turn on decimal point 6		TXDATA buffer		; set to Write MODE	; copy RX buffer (modified) to TX buffer						
0×10	RXDATA1	WriteLCD	WhichDec		RXDATA1,W	0x01	STATUS, DC	IncFour2		RXDATA1	0x10	RXDATA1,W		RXDATA1	WriteLCD	WhichDec		RXDATA2,W	0x10	RXDATA2	WriteLCD	WhichDec		RXDATA2,W	0x01	STATUS, DC	IncSix2		RXDATA2	0×10	RXDATA2,W		RXDATA2	WriteLCD	WhichDec		RXDATA buffer to I	BUTTON	TXDATA, 6	RXDATA0,W	TXDATA0	RXDATA1, W	TXDATA1	RXDATA2.W	ATTWINE , W	7414741
addlw	movwf	call	goto		movf	addlw	btfss	goto		movwf	movlw	subwf		movwf	call	goto		movf	addlw	movwf	call	goto		movf	addlw	btfss	goto		movwf	movlw	subwf		movwf	call	goto		; copies F	clrf	psf	movf	movwf	movf	movwf	movf	mO3rwf	
01946	01947	01948	01949	01950	01951 IncFour	01952	01953	01954	01955	01956	01957	01958	01959	01960 IncFour2	01961	01962	01963	01964 IncFive	01965	01966	01967	01968	01969	01970 Incsix	01971	01972	01973	01974	01975	01976	01977	01978	01979 Incsix2	01980	01981	01982	01983 WriteCS4560	01984	01985	01986	01987	01988	01989	01990	0 0 0	O L Y Y L
3E10	00BA	26F7	2B62		083A	3E01	1083	2BB3		00BA	3010	023A		00BA	26F7	2B62		083B	3E10	0.0BB	26F7	2B62		083B	3E01	1C83	2BC2		00BB	3010	023B		00BB	26F7	2B62			01F4	173C	0839	0.0BD	083A	00BE	0838	000E	3 Q O O
03A8	03A9	03AA	03AB		03AC	03AD	03AE	03AF		03B0	03B1	03B2		03B3	03B4	03B5		03B6	03B7	03B8	03B9	03BA		03BB	03BC	03BD	03BE		03BF	03C0	03C1		03C2	03C3	03C4		03C5	03C5	03C6	03C7	0308	0309	03CA	03CB	ת כ ה ה)))

<pre>; transmit TX buffer ; select next calibration MODE</pre>																			Cines ************	e 24C01 EEPROM	not.	to be pulled high by pull-up resistor			**************************	high	*************************				goes low while clock is high		; PORTA, bit1	; bank 1	; set SDA as output	; bank 0	; PORTA, bit0		; data set low		; clock goes low
SSPWrite IncCal		routine	STATUS, RPO	STATUS, RP1	TEMPA	.5	TEMPB	Dly1	doo	\$+1	\$+1		TEMPA, F	Dly1	TEMPB, F	Dly1			I2C EEPROM routines	to and read from the 24C01	, but SCL does	than allowed t	*********		*********	- SDA falls while SCL is high	*********				data		SDA	STATUS, RPO	SDATRIS	STATUS, RPO	SCL		SDA		SCL
call goto	return	; 10ms delay		bcf	clrf	movlw	movwf	goto	; the delay loop	goto	goto	dou	decfsz	goto	decfsz	goto	return		***************	routines write to an	a pull-up resistor, but SCL does not.	is driven high rather	************		************	Start Bit - SDA fall	*************	none	: none		; start bit -		bsf	bsf	bcf	bcf	bsf		bcf		bcf
01992 01993	01994 01995	01996 Delay10mS 01997	01998	01999	02000	02001	02002	02003	02005 Dly1	02006	02007	02008	02009	02010	02011	02012	02013	02014	02015 ,******	02016 ; These ro	02017 ; SDA has a	02018 ; SCL is	*	02020	02021 ,*****	02022 ; Sends St	02023 ,******	02024 ; Inputs:	02025 ; Outputs:	02026	02027 SendStart	02028	02029	02030	02031	02032	02033	02034	02035	02036	02037
22E1 2B4D	8000		1283	1303	01A0	3005	00A1	2BD6		2BD7	2BD8	0000	0BA0	2BD6	0BA1	2BD6	8000																1485	1683	1085	1283	1405		1085		1005
03CD	03CF	03D0	03D0	03D1	03D2	03D3	03D4	03D5	03D6	03D6	03D7	03D8	03D9	03DA	03DB	03DC	03DD														03DE		03DE	03DF	03E0	03E1	03E2		03E3		03E4

		***************************************	high	*******************				while clock is high		; data goes low	; bank 1	; set SDA as output	; bank 0		; clock goes high		; data goes high	; bank 1	; set SDA as input	; bank 0				,*************************************	bits to send). For each bit in EETEMP starting	bit to send, sets SCL high then low.	When BYTECOUNT reaches zero, all bits		************************							; send eight bits			; bank 1	; SDA set to output	; bank 0			; EETEMP MSB
		***********	SDA rises while SCL is h	************				- data goes high while clock		SDA	STATUS, RPO	SDATRIS	STATUS, RPO		SCI		SDA	STATUS, RPO	SDATRIS	STATUS, RPO				************	8 (8	same state as	for each bit.		*************	o transmit)		counter)		s clock, reads SDA		0×08	BYTECOUNT		STATUS, RPO	SDATRIS	STATUS, RPO			EETEMP, 7
; ; ;	Tecatin	************	s Stop Bit - SDA ris	*******	ts: none			op ; stop bit		bcf	bsf	bcf	bcf		bsf		bsf	bsf	bsf	bcf		return		*************	BYTECOUNT is loaded with	with MSB, sets SDA to to	BYTECOUNT is decremented	have been sent.	**************	ts: EETEMP (data to	Outputs: none	: BYTECOUNT (bit		ta ; generates		movlw	movwf		bsf	bcf	bcf		taLoop	btfsc
		****	; Sends		; Inputs:	; Outp		SendStop																****	; BYTE	; with	; BYTE	; have	****	; Inputs:	; Outp	٠.		SendData									SendDataLoop	
02038	02020	02041	02042	02043	02044	02045	02046	02047	02048	02049	02050	02051	02052	02053	02054	02055	02056	02057	02058	02059	02060	02061	02062	02063	02064	02065	02066	02067	02068	02069	02070	02071	02072	02073	02074	02075	02076	02077	02078	02079	02080	02081	02082	02083
0000	0000									1085	1683	1085	1283		1405		1485	1683	1485	1283		8000														3008	0004		1683	1085	1283			1BD7
<u>Б</u>	0 4 0							03E6		03E6	03E7	03E8	03E9		03EA		03EB	03EC	03ED	03臣臣		03EF												03下0		03E0	03F1		03F2	03F3	03万4		03F5	03F5

	; SDA goes low	; SDA goes high	; clock pulse goes high	; clock pulses goes low	; rotate data to transmit ; count bit as sent	; not done yet, repeat loop ; done with loop, return	.*************************************	ed for each bit. The received ches zero, all bits have been .	,*************************************				, init bit counter $$; clock high	; read data						; clock low					
SDAHigh	SDA SCLPulse	SDA	SCL	SCL	EETEMP, F BYTECOUNT, F	SendDataLoop	**************************************	ount hen E	****	d data)	counter)	80×0	BYTECOUNT	SCL	SDA	RDHigh	EEDATA,0	DRCount		EEDATA,0	SCL	BYTECOUNT, F	NextBit			EEDATA,F
goto	bcf goto	bsf	dou	nop nop bcf	rlf decfsz	goto return	**************************************		*************	EEDATA (re	BYTECOUNT (bit	wlvom	movwf	bsf	btfsc	goto	bcf	goto		bsf	bcf	decfsz	goto	return		rlf
34	S6 SDALow	38 39 SDAHigh	90 91 SCLPulse 92	93 95)6)7 DecCntA)8	00					10 ; used:	.i 2 GetData		.5 ReadData .6	17	8	6.	5.0		22 RDHigh 23	4 DRCount	25	56	2.7		39 NextBit
02084	02086	02088	02090	02093 02094 02095	02096 02097 02098	02099 02100	02102	02104 02104 02105 02106	02107	02109	02110	02112	02113	02115	02117	02118	02119	02120	02121	02122 02123	02124	02125	02126	02127	02128	02129
2BF9	1085 2BFA	1485	0000	0000	0DD7 0BD4	2BF5 0008						3008	0004	1405	1885	2C0A	1056	2C0B		1456	1005	0BD4	2COF	8000		9000
03F6	03F7 03F8	03F9	03FA 03FB	03FC 03FD 03FE	03FF 0400	0401						0403	0404	0405	0406	0407	0408	0409		040A	040B	040C	040D	040臣		040F

		n send ACK bit. This bit is not		************************					; bank 1	; set SDA to input	; bank 0		; clock pulse for ACK									***********************			y address in EEPROM (EEADDR) and data		perform the write operation.	******************************			; Send Write Code to EEPROM memory			; send Start Bit	; send 8 bits of data	; get ACK bit from slave		; Send memory Address		; send 8 bits of data	; get ACK bit from slave		; Send memory Data
ReadData	***********	pulsse so slave can		******					STATUS, RPO	SDATRIS	STATUS, RPO		SCI					SCL				**********	ROM.		to EEPROM followed by		r the EEPROM to]	***********			b'10100000'	EETEMP		SendStart	SendData	GetACK		EEADDR,W	EETEMP	SendData	GetACK		EEDATA,W
goto	************	a 9th clock	ded.	***********	s: none	ts: none			psf	bsf	bcf		bsf	dou	dou	dou		bcf		return		************	Single byte write to EEPROM		nd	ite (EEDATA).	The delay allows time for the EEPROM to perform the write	************		.ts: none	movlw	movwf		call	call	call		movf	movwf	call	call		movf
		02133 ; Generates	-	02135 ,****	02136 ; Inputs:	02137 ; Outputs:	02138	02139 GetACK	02140	02141	02142	02143	02144	02145	02146	02147	02148	02149	02150	02151	02152	02153 ;*****	02154 ; Singl	٠.	٠.	•-	••	••	٠.	02161 ; Outputs: 02162	02163 EEWrite	02164	02165	02166	02167	02168	02169	02170	02171	02172	02173	02174	02175
2005									1683	1485	1283		1405	0000	0000	0000		1005		8000											30A0	0007		23DE	23F0	2411		0855	0007	23F0	2411		0856
0410								0411	0411	0412	0413		0414	0415	0416	0417		0418		0419											041A	041B		041C	041D	041E		041F	0420	0421	0422		0423

; address in the EEPROM. ;************************************	n constants)				; select address 0x00	; write serial number					; Voltage Offset MSB, select address 0x01						; Voltage Offset, select address 0x02						; Voltage Offset LSB, select address 0x03						; Current Offset MSB, select address 0x04						; Current Offset, select address 0x05						; Current Offset LSB, select address 0x06		
******	CAL.INC (calibration constants)			00x0	EEADDR	SERNUMBER	EEDATA	EEWrite		0x01	EEADDR	VOLTOFFH	EEDATA	EEWrite		0x02	EEADDR	VOLTOFFM	EEDATA	EEWrite		0x03	EEADDR	VOLTOFFL	EEDATA	EEWrite		0x04	EEADDR	CURROFFH	EEDATA	EEWrite		0x05	EEADDR	CURROFFM	EEDATA	EEWrite		90x0	EEADDR	CURROFFL	EEDATA
address in the EEPROM. ************	contents of CAL	: none		movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf
02222 ; address 02223 ;********	02224 ; Inputs:	02225 ; Outputs:	02227 WriteSer	02228	02229	02230	02231	02232	02233	02234	02235	02236	02237	02238	02239	02240	02241	02242	02243	02244	02245	02246	02247	02248	02249	02250	02251	02252	02253	02254	02255	02256	02257	02258	02259	02260	02261	02262	02263	02264	02265	02266	02267
				3000	0005	3001	9000	241A		3001	0005	3010	9000	241A		3002	0005	301A	9000	241A		3003	0005	30B6	9000	241A		3004	0005	30FE	9000	241A		3005	0005	30DC	9000	241A		3006	0005	3016	9000
			043B	043B	043C	043D	043E	043F		0440	0441	0442	0443	0444		0445	0446	0447	0448	0449		044A	044B	044C	044D	044臣		044F	0450	0451	0452	0453		0454	0455	0456	0457	0458		0459	045A	045B	045C

		; Voltage Gain MSB, select address 0x07						; Voltage Gain, select address 0x08						; Voltage Gain LSB, select address 0x09						; Current Gain MSB, select address 0x0A						; Current Gain, select address 0x0B						; Current Gain LSB, select address 0x0C						; Watt HOUR LSB, select address 0x0D					י אַראַר אַראַר.	
EEWrite	0×07	EEADDR	VOLTGAINH	EEDATA	EEWrite		0×08	EEADDR	VOLTGAINM	EEDATA	EEWrite		60×0	EEADDR	VOLTGAINL	EEDATA	EEWrite		0×0A	EEADDR	CURRGAINH	EEDATA	EEWrite		0×0B	EEADDR	CURRGAINM	EEDATA	EEWrite		0×0C	EEADDR	CURRGAINL	EEDATA	EEWrite		0×0D	EEADDR	EEDATA	EEWrite		0×0E	READUR	EEDATA
call	movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		movlw	movwf	clrf	call		movlw	mo vwf	clrf
02268	02270	02271	02272	02273	02274	02275	02276	02277	02278	02279	02280	02281	02282	02283	02284	02285	02286	02287	02288	02289	02290	02291	02292	02293	02294	02295	02296	\circ	02298	02299	02300	02301	02302	02303	02304	02305	02306	02307	02308	02309	02310	02311	02312	
241A	3007	0.005	3029	9000	241A		3008	0005	3066	00D6	241A		3009	0005	306F	0 0 D G	241A		300A	0005	302A	9000	241A		300B	0005	302E	9000	241A		300C	0.005	300A	9000	241A		300D	0005	01D6	241A		300E	2000	01D6
045D	045臣	045F	0460	0461	0462		0463	0464	0465	0466	0467		0468	0469	046A	046B	046C		046D	046圧	046F	0470	0471		0472	0473	0474	0475	0476		0477	0478	0479	047A	047B		047C	047D	047E	047F		0480	1840	0482

		; Pulse Rate gain MSB, select address 0x0F						; Pulse Rate gain, select address 0x10						; Pulse Rate gain LSB, select address 0x11						*************************	LCD) for operation.			depending on whether TMR10SC is defined.		the Timer1 Oscillator to generate	al 32.768 Hz crystal.		sed the system clock in	his ae	onfidired depending	1 1	ii ciiis	a by the csstou and is 4.096 MHz.	aajust corkii.	********************************							; Bank 1		
EEWrite	0x0F	EEADDR	PULSERATEH	EEDATA	EEWrite		0×10	EEADDR	PULSERATEM	EEDATA	EEWrite		0x11	EEADDR	PULSERATEL	EEDATA	EEWrite			***********	peripherals (except L			configured		is enabled, and uses the	e c		configured to	only, special ev	of by 2 in the TM	of Dy z In che in	1): IIIIB LCIICB O	crock is provide	ent irequency, a	***********	ion				PORTB, 3		STATUS, RPO		
call	movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		movlw	movwf	movlw	movwf	call		return	**************	ure internal	onfigures int)	second interrupt is		defined, Timer1 is er	nd interrupts	· · · · · · · · · · · · · · · · · · ·	not defined, CCP1 is	Ψ	intermint rate is divided by 2 in the	incerrupt rate is divided by a militude and are control on the TMD1000 defination). This welles on the avertem aloab	die improse der increi	acion, cne		***************	uts: TMR1OSC definition	puts: none		əriph	bcf		bsf		
02314	02316	02317	02318	02319	02320	02321	02322	02323	02324	02325	02326	02327	02328	02329	02330	02331	02332	02333	02334	****** 05338	7	02338 ; Also	02339 ;	02340 ; A 1	02341 ;	ŢŢ			02345 : If not				-	٠.		*		02353 ; Output	02354	02355 InitPeri	02356	02357	02358	02359	
241A	300F	0.005	3002	9000	241A		3010	0005	3014	9000	241A		3011	0005	30CB	9000	241A		8000																						1186		1683		
0483	0484	0485	0486	0487	0488		0489	048A	048B	048C	048D		048臣	048F	0490	0491	0492		0493																					0494	0494		0495		

	; set PORTA all digital		; RA0=EEPROM SCL, RA1=EEPROM SDA, RA2=CS5460 CS,	; RA3=NC, RA4=NC, RA5=NC		; RB0=!EOUT, RB4=!SW2	; RB1=!EDIR, RB5=!SW3	; RB2=NC, RB6=!SW4	; RB3=NC, RB7=!SW5		; RC0=T1OSC, RC3=SSP SCK	; RC1=T10SC, RC4=SSP SDI	; RC2=NC, RC5=SSP SDO		; setup SSP Module - input sampled at end of output,	; xmit on rising SCLK		; bank 0		and provides the Fosc for the controller.	Timer10SC is used	#DEFINE	4	; preload Timer1 to interrupt in 1 second					; setup Timer1 - 1 int/sec	; 1:1 prescale, osc enabled, ext clock, async		CCP1 in Special Event Trigger MODE.			; setup Timerl - reset by special event trigger	, int clock		; clear interrupt counter			; 0.5 second compare			
b'00000111'	ADCON1		b'11110010'	TRISA		b'11110001'	TRISB				B'00010110'	TRISC			b'11000000'	SSPSTAT		STATUS, RPO		is 4.096MHz	code if 32kHz	; (comment		0×7£	TMR1H	0×FF	TMR1L		b,00001111,	TICON		itialize Timer1 and	oscillator is used, these lines are		b,00110001,	TICON		CCPCOUNT		0xF9	CCPR1H	OXFF	CCPR1L	
movlw	movwf		movlw	movwf		movlw	movwf				movlw	movwf			movlw	movwf		bcf		The CS5460 CPUCLK output	DEF TMR10SC ; use this	•		movlw	movwf	movlw	movwf		movlw	movwf		The following lines initialize Timer1 and	If the Timer1 oscillat	statement.	movlw	movwf		clrf		movlw	movwf	movlw	movwf	
02360	02361	02362	02363	02364	02365	02366	02367	02368	02369	02370	02371	02372	02373	02374	02375	02376	02377	02378	02379	٠.	02382 #IFDEF		02384	02385	02386	02387	02388	02389	02390	02391	02392 #ELSE	02393 ; T	02394 ; I	02395 ; 8	02396	02397	02398	02399	02400	02401	02402	02403	02404	02405
3007	000万		30F2	0085		30F1	9800				3016	0087			30C0	0094		1283																	3031	0600		01FF		30F9	9600	30FF	0095	
0496	0497		0498	0499		049A	049B				049C	049D			049臣	049F		04A0																	04A1	04A2		04A3		04A4	04A5	04A6	04A7	

; set up CCP1 compare mode,				; setup Timer2 -	; 4:1 prescale, 8:1 postscale, TMR2 off		; SSP MODE, Fosc/16 -			; clear LCD update flag	clear pressed BUJ	; clear display MODE counter		; Set CS5460 !CS		; set message POINTER to start	; scrolling message				***************************************	and MINUTEs for the real time clock		**********************							, "C"		''				; update time display		; wait for BUTTONs to be pressed		; if BUTTON 1 then we are done			; and return start the main program	
b'00001011'	CCP1CON			b'00111001	T2CON		b'00100001'	SSPCON		UPDATE	BUTTON	MODEINC		CS		.31	POINTER				*************	user to set HOURs	ot be set).	*******		HOUR			UPDATE		0×0C	LoadD1	0x1D	LoadD2		UPDATE, 0	UpdDisp		BUTTON, 0	SetLoop	BUTTON, 1	Chk2C1k		Continue4	
movlw	movwf			movlw	movwf		movlw	movwf		clrf	clrf	clrf		lsd		movlw	movwf		return		************	outine allows the user	(Sec	***********	: BUTTON	s: SECOND, MINUTE,			clrf		movlw	call	movlw	call		btfsc	call		btfss	goto	btfss	goto	1	goto	
02406	02407	02408 #ENDIF	02409	02410	02411	02412	02413	02414	02415	02416	02417	02418	02419	02420	02421	02422	02423	02424	02425	02426	02427 ;*****	02428 ; This routine	02429 ; display.	02430 ,*****		02432 ; Outputs:	02433	02434 SetClock	02435	02436	02437	02438	02439	02440	02441	02442 SetLoop	02443	02444	02445	02446	02447	02448	02449	02450	02451 Chk2Clk
300B	2600			3039	0092		3021	0094		01F3	01F4	01F2		1505		301F	00B3		8000										01F3		300C	261F	301D	263A		1873	2296		1C74	2CBA	1CF4	2CC1		28C9	
04A8	04A9			04AA	04AB		04AC	04AD		04AE	04AF	04B0		04B1		04B2	04B3		04B4									04B5	04B5		04B6	04B7	04B8	04B9		04BA	04BB		04BC	04BD	04BE	04BF		04C0	04C1

04C1	1D74	02452	btfss	BUTTON, 2	is BUTTON 2 pressed?
04C2	2CC5	02453	goto	Chk3Clk	no, check BUTTON 3
04C3	1A74	02454	btfsc	BUTTON, 4	yes, is BUTTON 4 pressed?
04C4	2CD3	02455	goto	IncHr	; yes, adjust hours
04C5		02456 Chk3Clk			
04C5	1DF4	02457	btfss		; is BUTTON 3 pressed?
04C6	2CC9	02458	goto	EndButtonClk	no
04C7	1A74	02459	btfsc	BUTTON, 4	yes, is BUTTON 4 pressed?
04C8	2CCB	02460	goto	IncMin	; yes, adjust minutes
04C9		02461 EndButtonClk			
04C9	01F4	02462	clrf	BUTTON	
04CA	2CBA	02463	goto	SetLoop	; wait for BUTTON press
		02464			
04CB		02465 IncMin			
04CB	01F4	02466	clrf	BUTTON	
04CC	0AA3	02467	incf	MINUTE, F	; increment MINUTEs
04CD	303C	02468	movlw	.60	; if they roll over 60, reset to 0
04CE	0223	02469	subwf	MINUTE, W	
04CF	1903	02470	btfsc	STATUS, Z	
04D0	01A3	02471	clrf	MINUTE	
04D1	1473	02472	psf	UPDATE, 0	; force display update
04D2	2CBA	02473	goto	SetLoop	
		02474			
04D3		02475 IncHr			
04D3	01F4	02476	clrf	BUTTON	
04D4	0 AA4	02477	incf	HOUR, F	increment HOURs
04D5	3019	02478	movlw	.25	; if they roll over 24, reset to 0
04D6	0224	02479	subwf	HOUR, W	
04D7	1903	02480	btfsc	STATUS, Z	
04D8	01A4	02481	clrf	HOUR	
04D9	1473	02482	bsf	UPDATE,0	; force display update
04DA	2CBA	02483	goto	SetLoop	
		02484			
04DB	0008	02485	return		; return to calling routine in page 0
		02486			
			***********	******	**************************************
		; Bin2BCD16 -	Converts a 16-bit	t binary number	in TEMPH: TEMPL into a 3 byte packed
		; BCD number		i	
		RO holds	ק	diait	
		: R1 holds		thousands digits	
		: R2 holds	ones and tens	digits	
		*************	*****	***********	***************************************
		; Inputs:	TEMPH, TEMPL (16-bit binary number)	t binary number)	
		; Outputs:	RO, R1, R2 (5 digit	BCD number)	
		; Used:	LN		
		02497			

	; clear carry bit		; init bit counter	; clear output	; clear output	; clear output		; mult by 2, shift MSb to TEMPH	; mult by 2, shift MSb to R2	; mult by 2, shift MSb to R1	; mult by 2, shift MSb to R0	; mult by 2, shift MSb to Carry	; decrement bit counter					; point to R2				; point to R1				; point to R0							; W = 3 + Rn	; $TEMP = 3+Rn$; Rn=TEMP	; decimal adjust?	; W=30+Rn	; TEMP=30+Rn		; Rn=TEMP			
: Initialize variables	STATUS, C	D'16'	COUNT	RO	R1	R2		TEMPL, F	TEMPH, F	R2,F	R1,F	RO, F	COUNT, F	AdjDec2			R2	FSR	Adj BCD2		R1	FSR	Adj BCD2	1	RO	FSR	AdjBCD2	n	Loop16a2			٣	INDF, W	TEMP	TEMP, 3	INDF	3.0	INDF, W	TEMP	TEMP, 7	INDF			
. Initializ	bcf	movlw	movwf	clrf	clrf	clrf		rlf	rlf	rlf	rlf	rlf	decfsz	goto	return		movlw	movwf	call		movlw	movwf	call		movlw	movwf	call		goto			movlw	addwf	movwf	btfsc	movwf	movlw	addwf	movwf	btfsc	movwf		return	
02498 Bin2BCD16 02499	02500	02501	02502	02503	02504	02505	02506 Loop16a2	02507	02508	02509	02510	02511	02512	02513	02514	02515 AdjDec2	02516	02517	02518	02519	02520	02521	02522	02523	02524	02525	02526	02527	02528	02529	02530 AdjBCD2	02531	02532	02533	02534	02535	02536	02537	02538	02539	02540	02541	02542	02543
	1003	3010	0003	01CE	OICF	01D0		0001	0DD2	0000	ODCF	ODCE	0BD3	2CEA	8000		3050	0084	24F4		304F	0084	24F4		304臣	0084	24F4		2CE2			3003	0020	0000	1909	0800	3030	0040	6000	1BC9	0800		8000	
04DC	04DC	04DD	04DE	04DF	04E0	04E1	04E2	04E2	04E3	04臣4	04E5	04E6	04E7	04E8	04E9	04EA	04EA	04EB	04EC		04ED	04EE	04EF		04F0	04F1	04F2		04F3		04F4	04F4	04F5	04F6	04F7	04F8	04万9	04FA	04FB	04FC	04FD		04FE	

***********			************					; read RMS Voltage from CS4560			; get V high byte	; save	; get V middle byte	; save		; read RMS Current from the CS4560				; get I high byte	; save		; get I middle byte	; save		; multiply I and V to get Apparent Power (fraction of		; result in AARGBO (MSB) to AARGB3 (LSB) (use AARGBO			; full scale power					; multiply AP(fraction) and full scale Power to get		; result in AARGBO (MSB) to AARGB3 (LSB)		Apparent Power	; APx is VoltAmps in binary		; save Apparent Power low byte	
	IOT VIMS AND LIMS Power (Vrms * Irms = AP)	.PH:APL (16-bit number)	********************************					b,00011000,	TXDATA	SSPRead	RXDATAO,W	AARGBO	RXDATA1, W	AARGB1		b'00010110'	TXDATA	SSPRead		RXDATA0, W	BARGBO		RXDATA1,W	BARGB1		FXM1616U					MAXPWRH	BARGBO	MAXPWRL	BARGB1		FXM1616U				AARGBO,W	APH		AARGB1,W	APL
****	Incerrogate CSS460 for V Calculate Apparent Dower	store binary result in APH:APL	*********	cs: none	Outputs: APH, APL			movlw	movwf	call	movf	movwf	movf	movwf		movlw	movwf	call		movf	movwf		movf	movwf		call					movlw	movwf	movlw	movwf		call				movf	movwf		movf	movwf
	02545 ; INCE		02548 ;****	02549 ; Inputs:	٠.	02551	02552 CalcAP	02553	02554	02555	02556	02557	02558	02559	02560	02561	02562	02563	02564	02565	02566	02567	02568	02569	02570	02571		02572		02573	02574	02575	02576	02577	02578	02579		02580	02581	02582	02583	02584	02585	02586
								3018	0 OBC	22BF	0839	0000	083A	00C1		3016	0 OBC	22BF		0839	0.005		083A	9200		25D1	scale)		RGB2)		3098	0005	3 OCE	9200		25D1	Apparent Power			0840	0 0AD		0841	00AE
							04FF	04FF	0200	0501	0502	0503	0504	0505		0506	0507	0508		0509	050A		050B	050C			full		to AARGB2)		020区	050F	0210	0511		0512	Appar			0513	0514		0515	0516

		******************		esult in TPH:TPL.		***********						; Pulse per second MSB	ı	; Pulse per second LSB			; multiply pulses by 10	; to get True Power			; Math 16bit * 16bit multiply routine		; save results in TPH:TPL as Watts in binary							***************************************	M		\{\frac{1}{1}\frac{1}\frac{1}\frac{1}{1}\frac{1}{1}\frac{1}{1}\frac{1}{1}\frac{1}{1}\frac{1}{1}\frac{1}{1}\frac{1}{1}\frac{1}{1}\frac{1}\frac{1}{1}\frac{1}{1}\frac{1}\frac{1}{1}\frac{1}\frac{1}{1}\frac{1}\frac{1}{1}\frac			24.16		dividend in AARGB0, AARGB1,AARGB2	BARGBO, BARGB1				AARGBO, AARGB1, AARGB2	n REMBO, REMB1		
		***	second, multiply	/ 10Watt*second) and save result	as Watts in binary.	****************						PULDISPH, W	AARGBO	PULDISPL, W	AARGB1		BARGBO	0×0A	BARGB1		FXM1616U		AARGB2,W	TPH	AARGB3,W	TPL				*******	x: 477000 04+ m0x4 point ox 02: 50x 1+::0x	TITLES WELL COPIED LION CIT	******			Fixed Point Divide 24/16 ->		fixed point	d fixed point divisor in BARGBO,		ns ns		d fixed point quotient in AARGB0,	fixed		AARG / BARG
1	recurn	***	gy over the	re 1 pulse /	True Power	******************	Tubilts: none	tupaca. mone	Outputs: TPH, TPL		CalcTP	movf	movwf	movf	movwf		clrf	movlw	movwf		call		movf	movwf	movf	movwf		return		*********	um ∧M >critical	MATH 115rary AN617	*****			24/16 Bit Unsigned Fixe		Input: 24 bit unsigned	16 bit unsigned		Use: CALL FXD2416U		Output: 24 bit unsigned	16 bit unsigned		Result: AARG, REM <
02587	0.2588	02589	02591 ;	02592 ;	02593 ;	02594 ;			0.2596	02597	02598 Ca	02599	02600	02601	02602	02603	02604	02605	02606	02607	02608	02609	02610	02611	02612	02613	02614	02615	0.2616			02618	, 02820	0000	02621 ;	02622 ;	02623 ;	02624 ;	02625 ;	02626 ;	02627 ;	02628 ;	02629 ;	02630 ;	02631 ;	02632 ;
0	8000											082B	0000	082C	0001		0105	300A	9200		25D1		0842	00AF	0843	0000		8000																		
7	1750										0518	0518	0519	051A	051B		051C	051D	051E		051F		0520	0521	0522	0523		0524																		

	O CAME C	KEMBO 4 chiller	KEMBL	TEMP		AARGBO,W	REMB1, F	BARGB1,W	REMB1, F	BARGBO, W	STATUS, C	BARGBO, W	REMBO, F			STATUS, C	1	TEMP, F	AARGBO, F		7	LOOPCOUNT		AARGBO, W	REMB1, F	REMBO, F	TEMP, F	BARGB1,W	AARGBO, LSB	UADD46LA		REMB1, F	BARGBO, W	STATUS, C	BARGBO, W	REMBO, F		STATUS, C	Н	TEMP, F	UOK46LA		REMB1, F	BARGBO,W
	Ç	CLRF	CLRF	CLRF		RLF	RLF	MOVF	SUBWF	MOVF	BTFSS	INCFSZ	SUBWF		CLRW	BTFSS	MOVLW	SUBWF	RLF		MOVLW	MOVWF		RLF	RLF	RLF	RLF	MOVF	BTFSS	GOTO		SUBWF	MOVF	BTFSS	INCFSZ	SUBWF	CLRW	BTFSS	MOVLW	SUBWF	GOTO		ADDWF	MOVF
	34 FXD2416U	3.5	35 37	38	39	4.0	641	42	43	44	645	646	4.7	648	649	650	651	52	53	654	655	656	57	58 LOOPU2416A	629	09.	61	.62	663	664	65	99	.67	668	699	7.0	71	672	673	674	675	676	677 UADD46LA	678
02633	02634	0.263	02637	02638	02639	02640	026	02642	02643	02644	026	026	02647	026	026	026	026	02652	02653	026	026	026	02657	02658	026	02660	02661	02662	026	026	02665	02666	02667	026	026	02670	02671	026	026	026	026	026	026	026
	7) TO	8.7.T.O	0109		0D40	0DC8	0846	02C8	0845	1C03	0F45	02C7		0103	1C03	3001	0209	0DC0		3007	0.0CD		0D40	0DC8	0DC7	0DC9	0846	1C40	2D48		02C8	0845	1C03	0F45	02C7	0103	1C03	3001	02C9	2D51		07C8	0845
	0525	2700	9750	0527		0528	0529	052A	052B	052C	052D	052臣	052F		0530	0531	0532	0533	0534		0535	0536		0537	0538	0539	053A	053B	053C	053D		053臣	053F	0540	0541	0542	0543	0544	0545	0546	0547		0548	0549

STATUS, C	BARGBO, W	REMBO, F		STATUS, C	1	TEMP, F		AARGBO, F		LOOPCOUNT, F	LOOPU2416A		AARGB1,W	REMB1, F	REMBO, F	TEMP, F	BARGB1,W	AARGBO, LSB	UADD46L8		REMB1, F	BARGBO, W	STATUS, C	BARGBO, W	REMBO, F		STATUS, C	П	TEMP, F	UOK46L8		KEMBI, F	BARGBO, W	STATUS, C	BARGBO, W	REMBO, F		STATUS, C	1	TEMP, F		AARGB1, F		7	LOOPCOUNT
BTFSC	INCFSZ	ADDWF	CLRW	BTFSC	MOVLW	ADDWF		RLF		DECFSZ	GOTO		RLF	RLF	RLF	RLF	MOVF	BTFSS	GOTO		SUBWF	MOVF	BTFSS	INCFSZ	SUBWF	CLRW	BTFSS	MOVLW	SUBWF	GOTO		ADDWF	MOVF	BTFSC	INCFSZ	ADDWF	CLRW	BTFSC	MOVLW	ADDWF		RLF		MOVLW	MOVWF
02679	02680	02681	02682	02683	02684	02685	02686	02687 UOK46LA	02688	02689	02690	02691	02692	02693	02694	02695	02696	02697	02698	02699	02700	02701	02702	02703	02704	02705	02706	02707	02708	02709		02/11 UADD4618	02712	02713	02714	02715	02716	02717	02718	02719	02720	02721 UOK46L8	02722	02723	02724
1803	0F45	07C7	0103	1803	3001	0709		0DC0		0BCD	2D37		0D41	0DC8	0DC7	0DC9	0846	1C40	2D65		02C8	0845	1C03	0F45	02C7	0103	1C03	3001	0209	2D6E	7	0 / 08	0845	1803	0F45	0707	0103	1803	3001	0709		0DC1		3007	0 0 CD
054A	054B	054C	054D	054臣	054F	0520		0551		0552	0553		0554	0555	0556	0557	0558	0559	055A		055B	055C	055D	055臣	055F	0260	0561	0562	0563	0564	L	0.505	0566	0567	0568	0569	056A	056B	056C	056D		056臣		056F	0570

AARGB1,W	REMB1, F	REMBO, F	TEMP, F	BARGB1,W	AARGB1,LSB	UADD46LB		REMB1, F	BARGBO, W	STATUS, C	BARGBO, W	REMBO, F		STATUS, C	1	TEMP, F	UOK46LB		REMB1, F	BARGBO, W	STATUS, C	BARGBO,W	REMBO, F		STATUS, C	1	TEMP, F	AARGB1,F	LOOPCOUNT, F	LOOPU2416B		AARGB2,W	REMB1, F	REMBO, F	TEMP, F	BARGB1,W	AARGB1, LSB	UADD46L16		REMB1, F	BARGBO, W	STATUS, C
RLF	RLF	RLF	RLF	MOVF	BTFSS	GOTO		SUBWF	MOVF	BTFSS	INCFSZ	SUBWF	CLRW	BTFSS	MOVLW	SUBWF	GOTO		ADDWF	MOVF	BTFSC	INCFSZ	ADDWF	CLRW	BTFSC	MOVLW	ADDWF	RLF	DECFSZ	GOTO		RLF	RLF	RLF	RLF	MOVF	BTFSS	GOTO		SUBWF	MOVF	BTFSS
02726 LOOPU2416B	02727	02728	02729	02730	02731	02732	02733	02734	02735	02736	02737	02738	02739	02740	02741	02742	02743	02744	02745 UADD46LB	02746	02747	02748	02749	02750	02751	02752	02753	02755 UOK46LB 02756	02757	02758	02759	02760	02761	02762	02763	02764	02765	02766	02767	02768	02769	02770
0571 0D41	572	0573 0DC7	0574 0DC9	0575 0846		0577 2D82			0579 0845	057A 1C03	057B 0F45	057C 02C7	057D 0103		057F 3001	0580 02C9	0581 2D8B				0584 1803		0586 07C7				058A 07C9	058B 0DC1	058C 0BCD	058D 2D71				0590 0DC7	0591 0DC9		0593 1C41	0594 2D9F		0595 0208	0596 0845	0597 1C03

BARGBO, W	REMBO, F		STATUS, C	1	TEMP, F	UOK46L16		REMB1, F	BARGBO, W	STATUS, C	BARGBO, W	REMBO, F		STATUS, C	Н	TEMP, F		AARGB2, F		7	LOOPCOUNT	AARGB2,W	REMB1, F	REMBO, F	TEMP, F	BARGB1,W	AARGB2, LSB	UADD46LC		REMB1, F	BARGBO, W	STATUS, C	BARGBO, W	REMBO, F		STATUS, C	П	TEMP, F	UOK46LC		REMB1, F	BARGBO, W	STATUS, C	BARGBO, W
INCFSZ	SUBWF	CLRW	BTFSS	MOVLW	SUBWF	GOTO		ADDWF	MOVF	BTFSC	INCFSZ	ADDWF	CLRW	BTFSC	MOVLW	ADDWF		RLF		MOVLW	MOVWF	RLF	RLF	RLF	RLF	MOVF	BTFSS	GOTO		SUBWF	MOVF	BTFSS	INCFSZ	SUBWF	CLRW	BTFSS	MOVLW	SUBWF	GOTO		ADDWF	MOVF	BTFSC	INCFSZ
02771	02772	02773	02774	02775	02776	02777	02778	02779 UADD46L16	02780	02781	02782	02783	02784	02785	02786	02787	02788	02789 UOK46L16	02790	02791	02792	02794 LOOPU2416C	02795	02796	02797	02798	02799	02800	02801	02802	02803	02804	02805	02806	02807	02808	02809	02810	02811	02812	02813 UADD46LC	02814	02815	02816
0598 0F45	0599 02C7		059B 1C03	059C 3001	059D 02C9	059E 2DA8						05A3 07C7	05A4 0103	05A5 1803		05A7 07C9		05A8 0DC2			05AA 00CD			05AD 0DC7	05AE 0DC9	05AF 0846	05B0 1C42	05B1 2DBC			05B3 0845		05B5 0F45	05B6 02C7		05B8 1C03	05B9 3001	05BA 02C9	05BB 2DC5		05BC 07C8	05BD 0845	05BE 1803	

																						******		ltiply 16x16 -> 32		nt multiplicand in AARGBO:AARGB1	nt multiplier in BARGB0:BARGB1				unsigned fixed point product in AARGBO:AARGB1:AARGB2:AARGB3					; clear partial product										
F DEMEN		STATUS, C	1	TEMP, F		AARGB2,F		LOOPCOUNT, F	LOOPU2416C		AARGB2, LSB	UOK46L	BARGB1,W	REMB1, F	BARGBO, W	STATUS, C	BARGB0, W	REMBO, F		00×0		************		yned Fixed Point Multiply 16x16		unsigned fixed	unsigned fixed point		FXM1616U				< AARG x BARG			AARGB2	AARGB3	AARGBO,W	TEMPBO	AARGB1,W	TEMPB1		0×08	TMIODEOCI	7,7000	
קשתתמ	CLRW	BTFSC	MOVLW	ADDWF		RLF		DECFSZ	GOTO		BTFSC	GOTO	MOVF	ADDWF	MOVF	BTFSC	INCFSZ	ADDWF		RETLW		***********		16x16 Bit Unsigned		Input: 16 bit	16 bit		Use: CALL		Output: 32 bit		Result: AARG		D	CLRF	CLRF	MOVF	MOVWF	MOVF	MOVWF		MOVLW	MOVAWE	1.10 v Wr.	
817	1 4	02819	02820	02821	02822	02823 UOK46LC	02824	02825	02826	02827	828	02829	830	02831	02832	833	02834	835	02836	02837 UOK46L	02838	* *	02840 ;	02841 ;	02842 ;	02843 ;	02844 ;	02845 ;	02846 ;	02847 ;	02848 ;	02849 ;	02850 ;	02851	02852 FXM1616U	02853	02854	02855	856	857	02858	02859	860	12861	02862	1
800	0.0	02	02	02	0.2	0.2	0.5	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	02	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.5	02	0.2	0.2	0.2	0.2	02	028	028	02	02	028	0) C	;
0707	0103	1803	3001	0709		0DC2		OBCD	2DAB		1842	2DD0	0846	07C8	0845	1803	0F45	07C7		3400																01C2	0103	0840	00CA	0841	00CB		3008	ריייי)	
0.77.0	0501	05C2	0503	05C4		0505		0506	05C7		0508	0509	05CA	05CB	05CC	05CD	05CE	05CF		0220															05D1	05D1	05D2	05D3	05D4	05D5	05D6		05D7	מרזי) 1 1	

516A RRF BARGB1, F	BTFSC STATUS, C	GOTO ALUM1616NAP	DECFSZ LOOPCOUNT,	GOTO LOOPUM1616A		MOVWF				BTFSC STATUS, C	GOTO BLUM1616NAP	DECFSZ LOOPCOUNT,	GOTO LOOPUM1616B		CLRF AARGBO	CLRF AARGB1	RETLW 0x00		SNAP	BCF STATUS, C	GOTO BLUM1616NA		SNAP		GOTO ALUM1616NA			RRF BARGB1, F	BTFSS STATUS, C		MOVF TEMPB1, W	ADDWF AARGB1, F		BIFSC STATUS, C	INCFSZ TEMPBO, W	ADDWF AARGBO, F		SNA	, c.	RRF AARGDO, F	AARGB1,	AARGB1, AARGB1, AARGB2,	AARGB1, AARGB2, AARGB2, FSZ LOOPCOUN
02863 LOOPUM1616A 02864	02865	02866	02867	02868	02869	02870	02871	02872 LOOPUM1616B	02873	02874	02875	02876	02877	02878	02879	02880	02881	02882	02883 BLUM1616NAP	02884	02885	02886	02887 ALUM1616NAP	02888	02889	02890	02891 ALOOPUM1616	02892	02893	02894	02895	02896	02897	02898	02899	02900	02901	02902 ALUM1616NA	02903		02904	02904 02905	02904 02905 02906
9220	1803	2DE9	0 BCD	2DD9		0 0 CD			0000	1803	2DE7	0BCD	2DDF		0100	01C1	3400			1003	2E04			1003	2DF4			9220	1C03	2DF4	084B	07C1	084A	1803	0F4A	0700			0000		0001	0CC1 0CC2	0CC1 0CC2 0BCD
0509	05DA	05DB	05DC	05DD		05DE		05DF	05DF	0250	05E1	05E2	05臣3		05臣4	05E5	05臣6		05E7	05E7	05臣8		05臣9	05臣9	05EA		05EB	05EB	05EC	05ED	05年	05EF	05F0	05F1	05F2	05F3		05F4	05174	1	05F5	05F5 05F6	05F5 05F6 05F7

																								***************	controlling the LCD	(value to be displayed)	(LCD digit to display it on)	(this example 3)		nresentations naing the			如果你有有有有有有有有有有有有有有有的。	£		*************************************					; Select bank 2	; operates in sleep, 1/3 mux, 1/3 bias, internal RC osc,	; init lcd control register, internal voltage generator used	; $1/3$ mux, frame freq = $20kHz/(96*(2+1))$ = about 70 Hz		; Select bank 0	
	T.OODCOTMT			RAPCRO F	STATUS, C	BLUM1616NA	TEMPB1,W	AARGB1, F	TEMPBO, W	STATUS, C	TEMPBO,W	AARGBO, F			AARGBO, F	AARGB1, F	AARGB2, F	AARGB3, F	LOOPCOUNT, F	BLOOPUM1616		00x0		*********	the basics for cont	9	LoadD3			4/12/98 For pr)	*****	で 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1		**********					STATUS, RP1	b'10011110'	LCDCON	0×02	LCDPS	STATUS, RP1	
MOIL	MOVEM		BT.OODITM1616	A B B B B B B B B B B B B B B B B B B B	BTFSS	OLOD	MOVF	ADDWF	MOVF	BTFSC	INCFSZ	ADDWF		BLUM1616NA	RRF	RRF	RRF	RRF	DECFSZ	COLOD		RETLW		****************	This routine contains the	movlw	call			Written by Stan D'Sonza 4	ard with asm fi		*****	() L () C	ILCIAILZES CIIE LCD MOdule	***************	Inputs: none	Ouputs: none		ILCD	bsf	movlw	movwf	movlw	movwf	bcf	
	02909	02011			02914	02915	02916	02917	02918	02919	02920	02921	02922		02924	02925	02926	02927	02928	02929	02930	02931	02932	***: 02630	02934 ; Th	02935 ;	02936 ;	02937 ;	02938;	7W · 65920		-				•-	٠.	•-	02947	02948 InitLCD	02949	02950	02951	02952	02953	02954	
000	3008			עטטט	1003	2E04	084B	07C1	084A	1803	0F4A	0700			0000	0001	0002	0003	0BCD	2DFB		3400																			1703	309臣	008F	3002	008臣	1303	
C L	0 0 1 1 1 0 2 4 1 1	1	о Б	0.548	05FC	05FD	05FE	05FF	0090	0601	0602	0603		0604	0604	0605	9090	0607	0608	6090		060A																		060B	060B	0600	060D	1090	060F	0610	

<pre>************************************</pre>	; Select bank 2 ; clear all LCD ram locations		* 17 00 *	; get seven se; save in temp; Select bank	; if not set, skip segment
**************************************	STATUS, RP1 LCDD00 LCDD01 LCDD02	LCDD04 LCDD05 LCDD06 LCDD08 LCDD10 LCDD11	ocf return ***********************************	to LCD digit 1 (left LCDTEMP1 Get7SegDat LCDTEMP1 STATUS, RP1 D1A D1B D1C D1D D1E D1F D1G TCDTEMP1	LCDTEMP1,0 D1A
return ***********************************	bsf clrf clrf	olri clrf clrf clrf	bcf return "Loadbx" accepts da "Get7SegDat table, ay. ay. *******************************	th 0	btisc bsf
***********************************			;******; ; Each "LC; ; calls Ge; ; display; ;******; ; Inputs: ; Ouputs:	LoadD1	
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		02968 02970 02971 02972 02973 02973			03000
ω	W O H O S	4+ rV 10 00 0v 14; w	m œ	000 m n n n n at n n n c	D 0
8000	1703 0190 0191 0192	0194 0195 0196 0198 0199 0194	1303	0050 0050 0050 0050 0050 0050 0050 005	1870
0611	000000000000000000000000000000000000000	0618 0618 0618 0619 061B 061C	061D 061E	子 1 1 1 1 1 1 1 1 1 1 1 1 1	062A 062B

	; Select bank 0 ; get seven segment data in w ; save in temp	save in tem Select bank	; if not set, skip segment	; Select bank 0
LCDTEMP1, 1 D1B LCDTEMP1, 2 D1C LCDTEMP1, 3 D1D LCDTEMP1, 4 D1E LCDTEMP1, 5 D1F LCDTEMP1, 6 D1G	STATUS,RP1 to LCD digit 2 LCDTEMP1 Get7SegDat LCDTEMP1	LCDTEMP1 STATUS, RP1 D2A D2C D2C D2C D2E D2E	LCDTEMP1, 0 D2A LCDTEMP1, 1 D2B LCDTEMP1, 2 D2C LCDTEMP1, 3 D2D LCDTEMP1, 4 D2E LCDTEMP1, 5 D2F LCDTEMP1, 5 D2F LCDTEMP1, 5	D2G STATUS,RP1 LCD digit 3 LCDTEMP1
btfsc bsf btfsc bsf btfsc btfsc bsf btfsc bsf	bcf return ; Write to movwf call movwf	movwi bsf bcf bcf bcf	btfsc bsf btfsc bsf btfsc btfsc btfsc btfsc	bsf D2G bcf STATUS return ; Write to LCD digit
03001 03002 03003 03004 03005 03007 03008 03010 03011	03013 03014 03015 03016 LoadD2 03017 03018	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	03028 03029 03031 03034 03034 03036 03038	03041 03042 03043 03044 03045 LoadD3
18F0 1592 1970 1596 19F0 151A 1A70 1616 1AE0 1612 11516	1303 0008 0008 27B0 00F0	00F0 1703 1092 1296 109A 1316 1096	1870 1492 18F0 1692 1970 19F0 149A 1A70 1716	1496 1303 0008 0008
000000000000	6 6 3 6 8 6 8 6 8 6 8 6 8 6 8 6 8 6 8 6	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0645 0646 0647 0647 0649 0640 0640 0640	

<pre>; get seven segment data in w ; save in temp ; Select bank 2</pre>	; if not set, skip segment	<pre>; Select bank 0 ; get seven segment data in w ; save in temp ; Select bank 2 ; if not set, skip segment ; if not set, skip segment</pre>	
Get7SegDat LCDTEMP1 STATUS, RP1 D3A D3B D3C D3D D3E D3F	LCDTEMP1,0 D3A LCDTEMP1,1 D3B LCDTEMP1,2 D3C LCDTEMP1,3 D3D LCDTEMP1,4 D3E LCDTEMP1,5 D3F LCDTEMP1,5 D3G		LCDIEMPI,2 D4C LCDTEMP1,3
call movwf bsf bcf bcf bcf bcf	btfsc bsf btfsc btfsc btfsc btfsc btfsc btfsc btfsc	return ; Write to LCD movwf call movwf bcf bcf bcf bcf bcf bcf bcf bcf bcf bc	btisc bsf btfsc
03047 03048 03050 03051 03051 03053 03054 03055	03057 03058 03059 03061 03061 03064 03064 03066 03067 03066	03071 03071 03072 03074 03074 03076 03081 03081 03082 03083 03083 03085 03086 03089	03090 03091 03092
27B0 00F0 1703 1311 1391 1395 1319 1016	1870 1711 18F0 1791 1970 1795 19F0 1719 1A70 1416 1A12 1A12	1333 0008 0000 0000 1703 1211 1211 1215 1396 1396 1396 1315 1611	у 0 0 1 Б
0656 0657 0658 0658 0658 0650 0650	0 6 6 0 0 0 6 6 0 0 0 6 6 0 0 0 0 6 6 0	0670 0671 0672 0673 0674 0675 0677 0677 0677 0677 0677	0680

; Select bank 0	<pre>; get seven segment data in w ; save in temp ; Select bank 2</pre>		<pre>; Select bank 0 ; get seven segment data in w ; save in temp ; Select bank 2</pre>
D4D LCDTEMP1,4 D4E LCDTEMP1,5 D4F LCDTEMP1,6 D4G STATUS,RP1 to LCD digit 5 LCDTEMP1	Get7SegDat LCDTEMP1 STATUS,RP1 D5A D5B D5C D5D D5E D5E	LCDTEMP1,0 D5A LCDTEMP1,1 D5B LCDTEMP1,2 D5C LCDTEMP1,3 D5D LCDTEMP1,4 D5E LCDTEMP1,5 D5F LCDTEMP1,6	bcf STATUS,RP1 return ; Write to LCD digit 6 movwf LCDTEMP1 call Get7SegDat movwf LCDTEMP1 bsf STATUS,RP1 bcf D6A
bsf btfsc bsf btfsc bsf btfsc bsf bcf ceturn ' Write t	call movwf bsf bcf bcf bcf bcf	btfsc bsf btfsc btfsc btfsc btfsc btfsc btfsc btfsc btfsc	bcf return ; Write t movwf call movwf bsf bcf
03093 03094 03095 03096 03099 03100 03101 03102	03105 03106 03107 03108 03109 03110 03111 03112	03115 03116 03117 03118 03120 03121 03122 03123 03124 03125 03125 03126	03129 03130 03131 03132 LoadD6 03134 03135 03136 03136
1619 1A70 1796 1AF0 1792 1B70 1615 1303	2050 27B0 0005 1703 1091 1111 1115 1099 1195 1191	1870 1491 18F0 1511 1970 1499 1A70 1595 1A70 1595 1A70 1595	1303 0008 0008 2780 000 11703 1310
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0696 0697 0699 0699 0698 0696 0696 0697 0697	06A4 06A5 06A6 06A6 06A7 06A9 06A9

	; if not set, skip segment	; Select bank 0	; get seven segment data in w ; save in temp ; Select bank 2	; if not set, skip segment
D6C D6B D6F D6G	LCDTEMP1,0 D6A LCDTEMP1,1 D6B LCDTEMP1,2 D6C LCDTEMP1,3 D6D LCDTEMP1,4 D6E LCDTEMP1,5 D6E LCDTEMP1,5 D6G	STATUS, RP1 to LCD digit 7 LCDTEMP1	Get7SegDat LCDTEMP1 STATUS,RP1 D7A D7B D7C D7D D7B D7F	LCDTEMP1,0 D7A LCDTEMP1,1 D7B LCDTEMP1,2 D7C LCDTEMP1,3 D7D LCDTEMP1,4 D7D LCDTEMP1,4 D7E LCDTEMP1,5
bcf bcf bcf bcf	btfsc bsf btfsc bsf btfsc bsf btfsc bsf btfsc bsf btfsc bsf	n Lte	call movwf bsf bcf bcf bcf bcf bcf bcf	btfsc bsf bsf bsf btfsc bsf bsf bsf bsf
03139 03140 03141 03142 03143	03144 03145 03146 03147 03150 03151 03152 03155 03155 03156	03158 03159 03160 03161 LoadD7 03162	03163 03164 03165 03166 03167 03168 03170 03171	03173 03174 03175 03176 03177 03178 03179 03181 03182 03183
1394 1318 1015 1011	1870 1710 18F0 1790 1970 1794 19F0 1718 1415 1415 1411	1303 0008 00F0	27B0 00F0 1703 1210 1214 1294 1290	1870 1590 18F0 1610 1970 1598 17970 1694 1694
06AC 06AD 06AE 06AF 06B0	0 6 B 1 0 0 B B 1 0 0 B B 1 0 0 B B 1 0 0 B B 1 0 0 B B 1 0 0 B B 1 0 0 B B 1 0 0 B B 1 0 0 B 1 0 0 B 1 0 0 B 1 0 0 B 1 0 0 0 B 1 0 0 0 B 1 0 0 0 B 1 0 0 0 B 1 0 0 0 B 1 0 0 0 B 1 0 0 0 B 1 0 0 0 B 1 0 0 0 B 1 0 0 0 B 1 0 0 0 B 1 0 0 0 B 1 0 0 0 0	06BF 06C0 06C1 06C1	06 C Z O C C C C C C C C C C C C C C C C C	0 6 C C C C C C C C C C C C C C C C C C

; Select bank 0	side)	get seven segment data in w	save in temp	; Select bank 2							; if not set, skip segment														; Select bank 0			******************			of the receive buffer to the LCD			Copy the data to display to the		*******************			
LCDTEMP1,6 D7G STATUS,RP1	digit 8 (right	LCDTEMP1 Get7SeaDat	LCDTEMP1	STATUS, RP1	D8A D8B	D8C	D8D	D8E	D8F	D8G	LCDTEMP1,0	D8A	LCDTEMP1,1	D8B	LCDTEMP1,2	D8C	LCDTEMP1,3	D8D	LCDTEMP1,4	D8E	LCDTEMP1,5	D8F	LCDTEMP1,6	D8G	STATUS, RP1			*****			the contents			a diagnostic tool.	s subroutine.	***********	DATA2		
	return ; Write to LCD	movwf call	movwf	bsf	baf baf		bcf	bcf	bcf		btfsc	bsf	btfsc	bsf	btfsc	bsf	btfsc	bsf	btfsc	bsf	btfsc	bsf	btfsc	bsf	bcf	return		**********	HEX values to LCD		routine is used to write	digit HEX number		can also be used as a d	er, and call this	***********	RXDATAO, RXDATA1, RXDATA2		1)
	LoadD8																											*********	; Writes HEX	.,	; This routine	; as a 6 digit		; This can als	; receive buffer,	***********	; Inputs: RXD?	; Ouputs: none	; uses:
03185 03186 03187	03188 03189 03190	03191	03193	03194	03195	03197	03198	03199	03200	03201	03202	03203	03204	03205	03206	03207	03208	03209	03210	03211	03212	03213	03214	03215	03216	03217	03218	03219	03220	03221	03222	03223	03224	03225	03226	03227	03228	03229	00700
1B70 1594 1303	8000	00F0 27B0	00F0	1703	1010	1094	1018	1114	1110	1014	1870	1410	18F0	1490	1970	1494	19F0	1418	1A70	1514	1AF0	1510	1B70	1414	1303	8000													
06D8 06D9 06DA	06DB	06DC 06DD	06DE	06DF	06E0	06E2	06臣3	06臣4	06E5	06臣6	06E7	06E8	06臣9	06EA	06EB	06EC	06ED	06臣臣	06EF	06F0	06F1	06F2	06F3	06F4	06F5	06F6													

	; blank display		; get data from receive buffer																							************************		and writes each digit to LCD				**************************************						; clear the LCD display		; get R0	; mask off upper nibble	; LCD digit 4		; swap R1 into W
	ClrLCD		RXDATA0,W	0×0f	LoadD2	RXDATA0,W	0×0f	LoadD1		RXDATA1,W	0×0f	LoadD5	RXDATA1,W	0×0f	LoadD4		RXDATA2,W	0×0f	LoadD8	RXDATA2,W	0×0f	LoadD7				***********	LCD	in RO, R1, R2 ar		9	8	******						ClrLCD		RO,W	0×0f	LoadD4		R1,W
	call		movf	andlw	call	swapf	andlw	call		movf	andlw	call	swapf	andlw	call		movf	andlw	call	swapf	andlw	call		return		***********	Decimal values to	packed BCD numbers	RO to digit 4	to digits 5 and	to digits 7 and	******	o, R1, R2	one				call		movf	andlw	call		swapf
03232 WriteLCD	03233	03234	03235	03236	03237	03238	03239	03240	03241	03242	03243	03244	03245	03246	03247	03248	03249	03250	03251	03252	03253	03254	03255	03256	03257	03258 ;*****	03259 ; Writes Dec	03260 ; Takes pack	03261 ; Write RO t	03262 ; Write R1 t	03263 ; Write R2 t	03264 ;*******	03265 ; Inputs: R0, R1, R2	03266 ; Ouputs: none	03267	03268	03269 WriteLCD2	03270	03271	03272 WriteLCD4	03273	03274	03275	03276 WriteLCD5
	2612				263A	0E39	390F	261F		083A	390F	268B	0E3A						26DC			26C1		8000														2612			390F			0E4F
06F7	06F7		06F8	06F9	06FA	06FB	06FC	06FD		06FE	06FF	0000	0701	0702	0703		0704	0705	9020	0707	0708	0709		070A													070B	070B		070C	070D	070圧		070F

mask off upper nibble (former lower nibble) LCD digit 5	get BCD in R1		LCD digit 6		swap R2 into W	mask off upper nibble	LCD digit 7	get BCD in R2		LCD digit 8			**************************************	leading zeros are not displayed.		***************************************					; if "10K" digit is 0, leave blank				; Display 5 digits			; if "1K" digit is zero, leave blank				; Display 4 digits			; if "100" digit is zero, leave blank				; Display 3 digits		
0x0f ; LoadD5 ;	R1,W ;	0x0f	LoadD6 ;		R2,W	0x0f ;	LoadD7 ;	R2,W;	0x0f	LoadD8 ;			******	and R2,	and WHLoop	*******					RO, W	0×0F	STATUS, Z	DP5LCD	WriteLCD4			R1,W	0×0F	STATUS, Z	DP4LCD	WriteLCD5			R1,W	0×0F	STATUS, Z	DP3LCD	WriteLCD6		
andlw call	movf	andlw	call	,	swapf	andlw	call	movf	andlw	call		return	******	 packed BCD digi	ed by APLoop, TPLoop and WHLoop	***********	0, R1, R2	one			movf	andlw	btfsc	goto	call	return		swapf	andlw	btfsc	goto	call	return		movf	andlw	btfsc	goto	call	return	
03277 03278	03279 03280 WriteLCD6	03281	03282		03284 WriteLCD7	03285	03286	03288 WriteLCD8	03289	03290	03291	03292	03293	٠.			٠.	03299 ; Ouputs: none	03300	03301	03302 DispPwr	03303	03304	03305	03306	03307	03308	03309 DP5LCD	03310	03311	03312	03313	03314	03315	03316 DP4LCD	03317	03318	03319	03320	03321	03322
390F 268B	084F	390F	26A6		0520	390F	26C1	0820	390F	26DC		8000									084E	390F	1903	2F22	270C	0008		0E4F	390F	1903	2F28	270F	8000		084F	390F	1903	2F2E	2712	0008	
0710			0714 2				0717			071A 2		071B (071C (071D 3	071E 1	071F 2	0720			0722 (0723	0724	0725		0727 (0728 (0729	072A	072B	072C 2	072D (

; if "10" digit is zero, leave blank	; Display 2 digits	; Display 1 digit	org 0x07B0 ***********************************	LCD in LCDTEMP1, and call this routine. 256 byte boundry does not occur		ring this routine with LCDTEMP1=0x1B returns the device serial number rather a seven segment display pattern. ************************************			-	; set PCLATH to jump to this table	; get offset	; compare with table length	, was unere a borrow: , yes, return dash		; get offset	; add to program counter	One	TWO	; Three	; Four	; Five	; Six	; Seven
R2,W 0x0F STATUS,Z DP2LCD	WriteLCD7	WriteLCD8	****	displayed on the is returned in W. so that a memory		Entering this routine with LCDTEMP1=0x1B returns than a seven segment display pattern.			high(Get7SegDat)	PCLATH	LCDTEMP1,W	0×1D C CTER (ED)	Ox40		LCDTEMP1,W	PCL, F	b,00000110,	b'01011011'	b'01001111'	b'01100110'	b'01101101'	b'01111101'	b'00000111'
swapf andlw btfsc goto	call return	call return	org 0x07B0 ***********************************	e the character to be seven segment pattern e LCD character table	in the table itself.	ing this routine with LC a seven segment display ************************************	ts: LCDTEMP1, PCL ts: W : PCLATH	Ť		MOVWI	movf	sublw	retlw		movf	addwf ~~+^~	retlw						
03323 DP3LCD 03324 03325 03326	03327 03328 03329	03330 DP2LCD 03331 03332	* * *	; Plac; The ; Plac; Plac	03341 ; within 03342 ;	03343 ; Enterir 03344 ; than a 03345 :******	ndul ;	03350 Get7SegDat		03352 03353	03354	03355	03357	03358	03359	03360	03362	03363	03364	03365	03366	03367	03368
0E50 390F 1903 2F34	2715 0008	2718 0008							3007	0.08A	0870	3C1D	3440		0870	0782	3406	345B	344F	3466	346D	347D	3407
072E 072F 0730 0731	0732	0734	0780					07B0	07B0	07BI	07B2	07B3	07B5		07B6	07B7	07B9	07BA	07BB	07BC	07BD	07BE	07BF

b'01111111'; Eight b'01101111'; Nine		p,01111100, ; p	b'00111001' ; C	b'01011110' ; d	b'01111001'; E	b'01110001' ; F	b'01110011' ; P (0x10)	b'00111100' ; left side of W (0x11) "W1"	b'00011110' ; right side of W (0x12) "Wr"	b'01111000'; t (0x13)	b'01010000'; r (0x14)	b'01011100' ; o (0x15)	b'00011100' ; u (0x16)	b'00000000'; space (0x17)	b'01110110' ; H (0x18)	b'00110011' ; left side of M (0x19) "M1"	b'00100111' ; right side of M (0x1A) "Mr"	SERNUM, W ; serial number (0x1B)	; (0x1C)	b'00111000' ; L (0x1D)		***************************************	initial scrolling message listed in reverse order.	a group of REI	Ö	statements.	***************************************						sg)	PCLATH ; set PCLATH to jump to this table		PTRIMP,W ; get offset		0x00,0x17,0x17,0x1B,0x17,0x14,0x0E,0x13,0x0E,0x1A,0x1B,0x17	0 sp sp sn sp r E t E Mr Ml sp			0x14,0x16,0x15,0x18,0x17,0x13,0x13,0x0A,0x12,0x11,0x17,0x03	r u o H sp t t A Wr Wl sp 3	241 11::::::::::::::::::::::::::::::::::	
retlw retlw	retlw	retlw	retlw	retlw	retlw	retlw	retlw	retlw	retlw	retlw	retlw	retlw	retlw	retlw	retlw	retlw	retlw	movf	return	retlw		*********	Characters used in the	The DT directive generates	the table. This is a more	listing "RETLW 0xNN" sta	**************	Inputs: PTRTMP, PCL	Ouputs: W	Uses: PCLATH			movlw	movwf		Joom	addwf	dt				åt			
03369		03372	03373	03374	03375	03376	03377	03378	03379	03380	03381	03382	03383	03384	03385	03386	03387	03388	03389	033390	91	92	93 ;	94 ;	95 ;	96	***: 103397	NI : 83398 ;	.,	.,	\vdash	03402 Msg	03403	03404	03405	03406	03407	3417 3417 03408	3417 3414 03409 ;	3413 340E 03410	3419 3417	3416 3415 03411	3413 0341	3412 0341	3412 U341
07C0 347F		07C3 347C	07C4 3439		07C6 3479	07C7 3471	07C8 3473			07CB 3478		07CD 345C	07CE 341C	07CF 3400	07D0 3476	07D1 3433	07D2 3427	07D3 0835	07D4 0008	07D5 3438												07D6		07D7 008A		07D8 0834	07D9 0782	07DA 3400	341B	340E	341A			3413	ე 14 1

dt 0x02,0x09,0x0C,0x06,0x01,0x0C,0x01,0x10			nop ; marker to find end of tables	; check if overrun to next page,	; or tables cross 256 word boundry		********************	End of program code.		cond program memory page with "goto 0x00"	At 0x000 in the second page is an instruction to clear PCLATH. The next goto instruction will	then goto the first instruction in the first page.		If execution should somehow branch to page 1, the next 3	lines will force execution to the reset vector on page 0.		This is not the same as a reset. Among other things, the stack is not reset.		org 0x0800 ; Page 1	clrf PCLATH ; selects page 0	fill (goto 0x00), 0x1000-\$; jump to first instruction in whichever page is selected		end : directive indicating the end of code	יייי לווי ליייי לייי	'-' = Unused)	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	XXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXX	XXXXXXXXXXXXX XXXXXXXXXXXXXX XXXXXXXXX	XXXXXXXXXXXXXX XXXXXXXXXXXXXX XXXXXXXX	XXXXXXXXXXX XXXXXXXXXXXXXXX XXXXXXXXXX	XXXXXXXXXXX XXXXXXXXXXXXXXX XXXXXXXXXX	XXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX		*****	XXXXXXXXXXXXXXXX	******	******	****************	***************************************
3403 340C 03414	0341	03416	03417	03418	03419	03420	03421	03422	03423	03424	03425	03426	03427	03428	03429	03430	03431	03432	03433	03434	03435	03436	03437	n H n o	('X' = Used,	XXXXX XXXXX																	
3411 3417 3 ⁴ 3402 3409 3 ⁴	3401	3401 3410	0000																	018A	28				USAGE MAP	XXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXX	XXXXXXXXXXXXX	XXXXXXXXXXXXX	XXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	***************************************	***************	***************************************
07F2			07FA (0800	0800	0801				MEMORY 1		••	••		0100 : 3	0140 : 2	0180 : 3	0100 : 3	0200 : 3									

# G	: XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXX	XXXXXXXXXXXXX
0400	***************************************	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	*************	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
0200	XXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0540	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX
0580	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX
0500	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0090	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0640	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0680	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0000	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0700	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXX
0780				XXXXXXXXXXXXXX
0700	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXX
0800	: XXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0840	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0880	: XXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0800	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX
0060	: XXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0940	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX
0860	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX
0960	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX
0A00	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0A40	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX
0A80	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0AC0	: XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX
0B00	: XXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0B40	: XXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0880	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0BC0	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0000	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0C40	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX
0080	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX
0000	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0000	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0D40	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
000	: XXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0DC0	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0E00	: XXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0E40	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0E80	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0EC0	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0F00	: XXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0F40	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
0F80	: XXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX
OFCO	: XXXXXXXXXXXXXXX	XXXXXXXXXXXXXXX	XXXXXXXXXXXXXX	XXXXXXXXXXXXXX

All other memory blocks unused.

Program Memory Words Free: 130

Errors: 0
Warnings: 0 reported, 0 suppressed
Messages: 0 reported, 2204 suppressed

2000:

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- Microchip believes that its family of PICmicro microcontrollers is one of the most secure products of its kind on the market today, when used in the intended manner and under normal conditions.
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