

## 256-COLOR, 1/80-DUTY LCD CONTROLLER/DRIVER WITH ON-CHIP RAM

### DESCRIPTION

The  $\mu$ PD161401 is an LCD controller/driver with RAM and is capable of driving a full-dot LCD. It can display 256 colors on an RGB-STN color LCD. This LCD controller/driver can drive a full-dot LCD of up to  $101 \times 80$  pixel with a single chip.

### FEATURES

- LCD driver with on-chip display RAM
- Logic power supply operation from +1.8 V to +3.6 V
- Internal booster circuit: x 2 to x 7 selectable
- Dot display RAM:  $(101 \times 80) \times 8$  bits
- 8 (R, G)/4 (B) grayscales selectable from 17 levels
- Full-dot output: 303 segment lines and 80 common lines
- Serial interface (SI, SCL) or 8-/16-bit parallel data input (i80 or M68 system interface)
- On-chip voltage divider resistor
- Selectable bias value: 1/9 to 1/5
- Selectable duty ratio: 1/80, 1/72 and 1/64 (main duty)
- On-chip oscillator

### ORDERING INFORMATION

Part Number	Package
$\mu$ PD161401W/P	Wafer/Chip (supports COF)

**Remark** Purchasing the above chip entail the exchange of documents such as a separate memorandum or product quality, so please contact one of our sales representatives.

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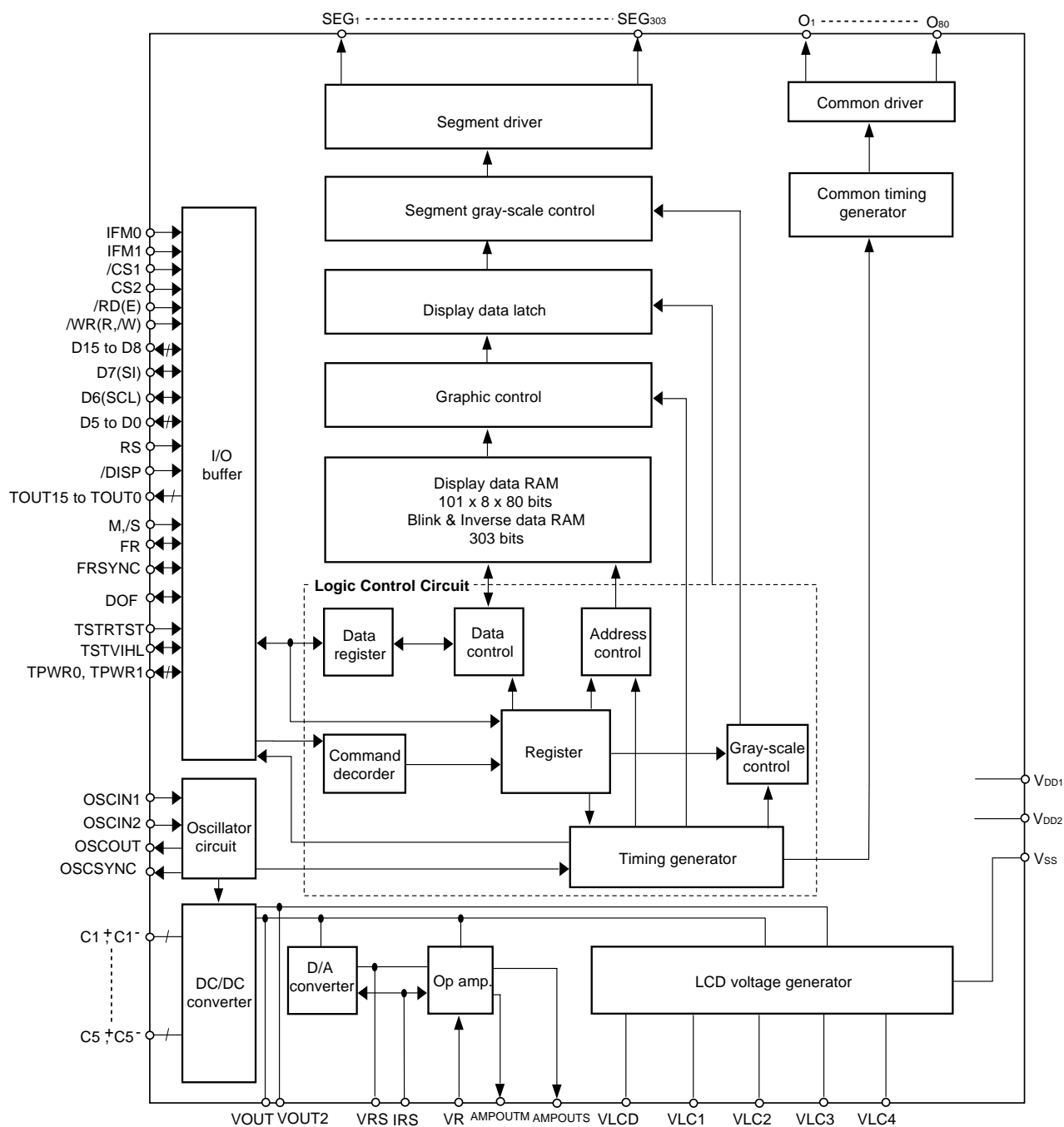
## CONTENT

<b>1. BLOCK DIAGRAM .....</b>	<b>5</b>
<b>2. PIN CONFIGURATION (Pad Layout) .....</b>	<b>6</b>
<b>3. PIN FUNCTIONS.....</b>	<b>12</b>
3.1 Power Supply Pins.....	12
3.2 Logic Circuit Pins .....	13
3.3 Driver Pins.....	15
<b>4. PIN I/O CIRCUITS AND RECOMMENDED CONNECTION OF UNUSED PINS.....</b>	<b>16</b>
<b>5. FUNCTIONAL DESCRIPTION.....</b>	<b>17</b>
<b>5.1 CPU Interface .....</b>	<b>17</b>
5.1.1 Selecting interface type.....	17
5.1.2 Parallel interface .....	17
5.1.3 Serial interface .....	19
5.1.4 Chip select .....	19
5.1.5 Accessing display data RAM and internal registers .....	19
<b>5.2 Display Data RAM .....</b>	<b>21</b>
5.2.1 Display data RAM .....	21
5.2.2 X address circuit .....	21
5.2.3 Y address circuit .....	23
5.2.4 Column address circuit .....	24
5.2.5 Common scan circuit .....	25
5.2.6 Display data latch circuit .....	28
5.2.7 Arbitrary address area access (window access mode (WAS)) .....	28
<b>5.3 Screen Processing.....</b>	<b>30</b>
5.3.1 Blink/reverse display circuit.....	30
5.3.2 Example of setting blink area.....	33
<b>5.4 Oscillator .....</b>	<b>33</b>
<b>5.5 Display Timing Generator .....</b>	<b>35</b>
<b>5.6 Power Supply Circuit.....</b>	<b>37</b>
5.6.1 Power supply circuit.....	37
5.6.2 Booster circuit .....	37
5.6.3 Voltage regulator circuit .....	39
5.6.4 Level voltage control by operational amplifier .....	42
5.6.5 Application example of power supply circuit .....	44
<b>5.7 Driving LCD .....</b>	<b>48</b>
5.7.1 Full-dot pulse modulation.....	48

5.7.2	Grayscale palette .....	51
5.7.3	Setting of display size .....	52
5.7.4	Setting of LCD N-line inversion and M-line shift.....	52
5.7.5	Reverse driving between frames .....	54
<b>5.8</b>	<b>Display Mode .....</b>	<b>55</b>
5.8.1	Selecting display mode .....	55
5.8.2	Screen scrolling .....	58
5.8.3	Scroll setting examples .....	59
<b>5.9</b>	<b>Reset .....</b>	<b>61</b>
<b>6.</b>	<b>COMMANDS .....</b>	<b>63</b>
6.1	Control Register 1 (R0) .....	64
6.2	Control Register 2 (R1) .....	65
6.3	Reset Command Register (R3) .....	66
6.4	X Address Register (R4) .....	66
6.5	Y Address Register (R5) .....	66
6.6	MIN.-X Address Register (R7) .....	67
6.7	MAX.-X Address Register (R8) .....	67
6.8	MIN.-Y Address Register (R9) .....	67
6.9	MAX.-Y Address Register (R10) .....	68
6.10	Display Memory Access Register (R12) .....	68
6.11	Main Duty Setting Register (R14) .....	69
6.12	Main Duty N-line Inversion Register (R15) .....	69
6.13	Main Duty M-line Shift Register (R16) .....	70
6.14	Sub-duty Setting Register (R17) .....	71
6.15	Sub-duty N-line Inversion Register (R18) .....	72
6.16	Sub-duty M-line Shift Register (R19) .....	73
6.17	COM Scanning Address Setting Register (R21) .....	74
6.18	Sub-duty Start Address Register (R22) .....	77
6.19	Scroll Fixed Area Position Register (R23) .....	78
6.20	Scroll Fixed Area Width Register (R27) .....	78
6.21	Scroll Step Number Register (R31) .....	79
6.22	Blink/Reverse Setting Register (R37) .....	80
6.23	Complementary Color Blink X Address Register (R38) .....	80
6.24	Complementary Color Blink Start Line Address Register (R39) .....	81
6.25	Complementary Color Blink End Line Address Register (R40) .....	81
6.26	Complementary Color Blink Data Memory Register (R41) .....	82
6.27	Specified Color Blink X Address Register (R42) .....	82
6.28	Specified Color Blink Start Line Address Register (R43) .....	83
6.29	Specified Color Blink End Line Address Register (R44) .....	83
6.30	Specified Color Blink Data Memory Register (R45) .....	84
6.31	Specified Color Setting Register (R46) .....	84

6.32	Reverse X Address Register (R47) .....	84
6.33	Reverse Start Line Address Register (R48) .....	85
6.34	Reverse End Line Address Register (R49) .....	85
6.35	Reverse Data Memory Access Register (R50) .....	86
6.36	Power System Control Register 1 (R52) .....	87
6.37	Power System Control Register 2 (R53) .....	88
6.38	Power System Control Register 3 (R54) .....	89
6.39	Power System Control Register 4 (R55) .....	90
6.40	Power System Control Register 5 (R56) .....	91
6.41	Main Electronic Volume Register (R57) .....	92
6.42	Sub-electronic Volume Register (R58) .....	92
6.43	RAM Test Mode Setting Register (R61) .....	93
6.44	Driving Mode Select Register (R64) .....	93
6.45	Main R Grayscale Data Registers (R65 to R72) .....	94
6.46	Main G Grayscale Data Registers (R73 to R80) .....	95
6.47	Main B Grayscale Data Registers (R81 to R84) .....	96
6.48	Sub R Grayscale Data Registers (R85 to R92) .....	97
6.49	Sub G Grayscale Data Registers (R93 to R100) .....	98
6.50	Sub B Grayscale Data Registers (R101 to R104) .....	99
7.	$\mu$ PD161401 REGISTER LIST .....	100
8.	POWER SEQUENCE .....	102
8.1	Power ON Sequence (with Internal Power Supply, Power ON $\rightarrow$ Display ON) .....	103
8.2	Power OFF Sequence (with Internal Power Supply) .....	105
8.3	Power ON Sequence (with External Driving Power Supply, Power ON $\rightarrow$ Display ON) .....	106
8.4	Power OFF Sequence (with External Driving Power Supply) .....	107
8.5	Flow of $V_{OUT}$ and $V_{LCD}$ Voltages from Power ON to Power OFF .....	108
8.6	Flow of $V_{OUT}$ and $V_{LCD}$ Voltages in Display Output and HALT/Standby Modes .....	109
9.	USING RAM TEST MODE .....	110
10.	ELECTRICAL SPECIFICATIONS .....	111
11.	CPU INTERFACE (Reference Example) .....	120

## 1. BLOCK DIAGRAM



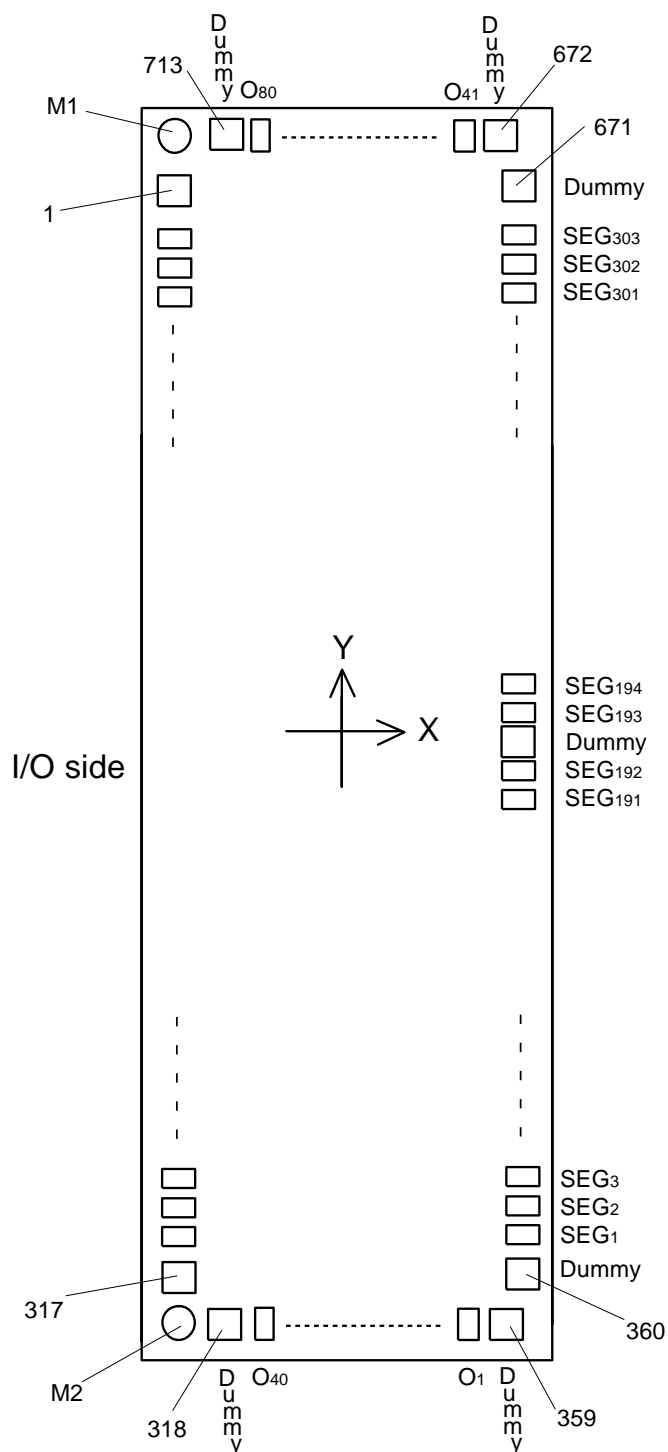
**Remark** /xxx is an active-low signal.

## 2. PIN CONFIGURATION (Pad Layout)

### • μPD161401W/P

Chip size: 2.57 x 16.05 mm<sup>2</sup>

Chip thickness: 485 μm (TYP.)



## Details of pad and alignment mark

### Pad type

#### A type

Pad size (Al): 39 x 71 μm<sup>2</sup> TYP.

Bump size : 33 x 65 μm<sup>2</sup> TYP.

Bump height: 17 μm TYP.

#### B type

Pad size (Al): 93 x 71 μm<sup>2</sup> TYP.

Bump size: 87 x 65 μm<sup>2</sup> TYP.

Bump height: 17 μm TYP.

### Alignment mark (unit: μm)

	X	Y
M1	-1140.00	7560.00
M2	-1140.00	-7560.00

### Shape of mark (unit: μm)

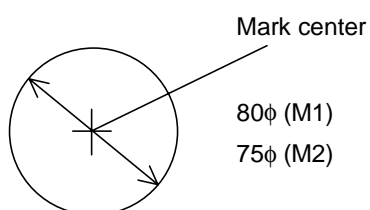


Table 2-1 Pad Layout (1/4)

Pad No.	Pad Name	Pad Type	Pad Layout [μm]		Pad No.	Pad Name	Pad Type	Pad Layout [μm]		Pad No.	Pad Name	Pad Type	Pad Layout [μm]	
			X	Y				X	Y				X	Y
1	DUMMY	B	-1144.50	7230.00	71	VSS	A	-1144.50	4000.00	141	D11	A	-1144.50	850.00
2	VSS	A	-1144.50	7105.00	72	VSS	A	-1144.50	3955.00	142	D11	A	-1144.50	805.00
3	VSS	A	-1144.50	7060.00	73	VSS	A	-1144.50	3910.00	143	D10	A	-1144.50	760.00
4	VSS	A	-1144.50	7015.00	74	M-/S	A	-1144.50	3865.00	144	D10	A	-1144.50	715.00
5	VOOUT	A	-1144.50	6970.00	75	M-/S	A	-1144.50	3820.00	145	D10	A	-1144.50	670.00
6	VOOUT	A	-1144.50	6925.00	76	M-/S	A	-1144.50	3775.00	146	VSS	A	-1144.50	625.00
7	VOOUT	A	-1144.50	6880.00	77	VDD1	A	-1144.50	3730.00	147	VSS	A	-1144.50	580.00
8	VOOUT2	A	-1144.50	6835.00	78	VDD1	A	-1144.50	3685.00	148	VSS	A	-1144.50	535.00
9	VOOUT2	A	-1144.50	6790.00	79	VDD1	A	-1144.50	3640.00	149	D9	A	-1144.50	490.00
10	VOOUT2	A	-1144.50	6745.00	80	IFM0	A	-1144.50	3595.00	150	D9	A	-1144.50	445.00
11	VSS	A	-1144.50	6700.00	81	IFM0	A	-1144.50	3550.00	151	D9	A	-1144.50	400.00
12	VSS	A	-1144.50	6655.00	82	IFM0	A	-1144.50	3505.00	152	D8	A	-1144.50	355.00
13	VSS	A	-1144.50	6610.00	83	VSS	A	-1144.50	3460.00	153	D8	A	-1144.50	310.00
14	C5-	A	-1144.50	6565.00	84	VSS	A	-1144.50	3415.00	154	D8	A	-1144.50	265.00
15	C5-	A	-1144.50	6520.00	85	VSS	A	-1144.50	3370.00	155	VSS	A	-1144.50	220.00
16	C5-	A	-1144.50	6475.00	86	IFM1	A	-1144.50	3325.00	156	VSS	A	-1144.50	175.00
17	C5+	A	-1144.50	6430.00	87	IFM1	A	-1144.50	3280.00	157	VSS	A	-1144.50	130.00
18	C5+	A	-1144.50	6385.00	88	IFM1	A	-1144.50	3235.00	158	D7	A	-1144.50	85.00
19	C5+	A	-1144.50	6340.00	89	VDD1	A	-1144.50	3190.00	159	D7	A	-1144.50	40.00
20	C4-	A	-1144.50	6295.00	90	VDD1	A	-1144.50	3145.00	160	D7	A	-1144.50	-5.00
21	C4-	A	-1144.50	6250.00	91	VDD1	A	-1144.50	3100.00	161	D6	A	-1144.50	-50.00
22	C4-	A	-1144.50	6205.00	92	IRS	A	-1144.50	3055.00	162	D6	A	-1144.50	-95.00
23	C4+	A	-1144.50	6160.00	93	IRS	A	-1144.50	3010.00	163	D6	A	-1144.50	-140.00
24	C4+	A	-1144.50	6115.00	94	IRS	A	-1144.50	2965.00	164	D5	A	-1144.50	-185.00
25	C4+	A	-1144.50	6070.00	95	VSS	A	-1144.50	2920.00	165	D5	A	-1144.50	-230.00
26	C3-	A	-1144.50	6025.00	96	VSS	A	-1144.50	2875.00	166	D5	A	-1144.50	-275.00
27	C3-	A	-1144.50	5980.00	97	VSS	A	-1144.50	2830.00	167	VSS	A	-1144.50	-320.00
28	C3-	A	-1144.50	5935.00	98	/CS1	A	-1144.50	2785.00	168	VSS	A	-1144.50	-365.00
29	C3+	A	-1144.50	5890.00	99	/CS1	A	-1144.50	2740.00	169	VSS	A	-1144.50	-410.00
30	C3+	A	-1144.50	5845.00	100	/CS1	A	-1144.50	2695.00	170	D4	A	-1144.50	-455.00
31	C3+	A	-1144.50	5800.00	101	CS2	A	-1144.50	2650.00	171	D4	A	-1144.50	-500.00
32	C2-	A	-1144.50	5755.00	102	CS2	A	-1144.50	2605.00	172	D4	A	-1144.50	-545.00
33	C2-	A	-1144.50	5710.00	103	CS2	A	-1144.50	2560.00	173	D3	A	-1144.50	-590.00
34	C2-	A	-1144.50	5665.00	104	VDD1	A	-1144.50	2515.00	174	D3	A	-1144.50	-635.00
35	C2+	A	-1144.50	5620.00	105	VDD1	A	-1144.50	2470.00	175	D3	A	-1144.50	-680.00
36	C2+	A	-1144.50	5575.00	106	VDD1	A	-1144.50	2425.00	176	D2	A	-1144.50	-725.00
37	C2+	A	-1144.50	5530.00	107	/DISP	A	-1144.50	2380.00	177	D2	A	-1144.50	-770.00
38	C1-	A	-1144.50	5485.00	108	/DISP	A	-1144.50	2335.00	178	D2	A	-1144.50	-815.00
39	C1-	A	-1144.50	5440.00	109	/DISP	A	-1144.50	2290.00	179	VSS	A	-1144.50	-860.00
40	C1-	A	-1144.50	5395.00	110	RS	A	-1144.50	2245.00	180	VSS	A	-1144.50	-905.00
41	C1+	A	-1144.50	5350.00	111	RS	A	-1144.50	2200.00	181	VSS	A	-1144.50	-950.00
42	C1+	A	-1144.50	5305.00	112	RS	A	-1144.50	2155.00	182	D1	A	-1144.50	-995.00
43	C1+	A	-1144.50	5260.00	113	VSS	A	-1144.50	2110.00	183	D1	A	-1144.50	-1040.00
44	VSS	A	-1144.50	5215.00	114	VSS	A	-1144.50	2065.00	184	D1	A	-1144.50	-1085.00
45	VSS	A	-1144.50	5170.00	115	VSS	A	-1144.50	2020.00	185	D0	A	-1144.50	-1130.00
46	VSS	A	-1144.50	5125.00	116	/WR (R, /W)	A	-1144.50	1975.00	186	D0	A	-1144.50	-1175.00
47	TPWR1	A	-1144.50	5080.00	117	/WR (R, /W)	A	-1144.50	1930.00	187	D0	A	-1144.50	-1220.00
48	TPWR1	A	-1144.50	5035.00	118	/WR (R, /W)	A	-1144.50	1885.00	188	VSS	A	-1144.50	-1265.00
49	TPWR1	A	-1144.50	4990.00	119	/RD (E)	A	-1144.50	1840.00	189	VSS	A	-1144.50	-1310.00
50	TPWR0	A	-1144.50	4945.00	120	/RD (E)	A	-1144.50	1795.00	190	VSS	A	-1144.50	-1355.00
51	TPWR0	A	-1144.50	4900.00	121	/RD (E)	A	-1144.50	1750.00	191	FRSYNC	A	-1144.50	-1400.00
52	TPWR0	A	-1144.50	4855.00	122	VDD1	A	-1144.50	1705.00	192	FRSYNC	A	-1144.50	-1445.00
53	VRS	A	-1144.50	4810.00	123	VDD1	A	-1144.50	1660.00	193	FRSYNC	A	-1144.50	-1490.00
54	VRS	A	-1144.50	4765.00	124	VDD1	A	-1144.50	1615.00	194	FR	A	-1144.50	-1535.00
55	VRS	A	-1144.50	4720.00	125	D15	A	-1144.50	1570.00	195	FR	A	-1144.50	-1580.00
56	VSS	A	-1144.50	4675.00	126	D15	A	-1144.50	1525.00	196	FR	A	-1144.50	-1625.00
57	VSS	A	-1144.50	4630.00	127	D15	A	-1144.50	1480.00	197	DOF	A	-1144.50	-1670.00
58	VSS	A	-1144.50	4585.00	128	D14	A	-1144.50	1435.00	198	DOF	A	-1144.50	-1715.00
59	VSS	A	-1144.50	4540.00	129	D14	A	-1144.50	1390.00	199	DOF	A	-1144.50	-1760.00
60	VSS	A	-1144.50	4495.00	130	D14	A	-1144.50	1345.00	200	OSCSYNC	A	-1144.50	-1805.00
61	VSS	A	-1144.50	4450.00	131	D13	A	-1144.50	1300.00	201	OSCSYNC	A	-1144.50	-1850.00
62	VDD2	A	-1144.50	4405.00	132	D13	A	-1144.50	1255.00	202	OSCSYNC	A	-1144.50	-1895.00
63	VDD2	A	-1144.50	4360.00	133	D13	A	-1144.50	1210.00	203	VSS	A	-1144.50	-1940.00
64	VDD2	A	-1144.50	4315.00	134	VSS	A	-1144.50	1165.00	204	VSS	A	-1144.50	-1985.00
65	VDD1	A	-1144.50	4270.00	135	VSS	A	-1144.50	1120.00	205	VSS	A	-1144.50	-2030.00
66	VDD1	A	-1144.50	4225.00	136	VSS	A	-1144.50	1075.00	206	OSCI1	A	-1144.50	-2075.00
67	VDD1	A	-1144.50	4180.00	137	D12	A	-1144.50	1030.00	207	OSCI1	A	-1144.50	-2120.00
68	VSS	A	-1144.50	4135.00	138	D12	A	-1144.50	985.00	208	OSCI1	A	-1144.50	-2165.00
69	VSS	A	-1144.50	4090.00	139	D12	A	-1144.50	940.00	209	VSS	A	-1144.50	-2210.00
70	VSS	A	-1144.50	4045.00	140	D11	A	-1144.50	895.00	210	VSS	A	-1144.50	-2255.00



Table 2-1 Pad Layout (2/4)

Pad No.	Pad Name	Pad Type	Pad Layout [μm]		Pad No.	Pad Name	Pad Type	Pad Layout [μm]		Pad No.	Pad Name	Pad Type	Pad Layout [μm]	
			X	Y				X	Y				X	Y
211	VSS	A	-1144.50	-2300.00	281	VSS	A	-1144.50	-5450.00	351	O8	A	505.00	-7773.00
212	OSCIN2	A	-1144.50	-2345.00	282	VSS	A	-1144.50	-5495.00	352	O7	A	550.00	-7773.00
213	OSCIN2	A	-1144.50	-2390.00	283	VSS	A	-1144.50	-5540.00	353	O6	A	595.00	-7773.00
214	OSCIN2	A	-1144.50	-2435.00	284	VSS	A	-1144.50	-5585.00	354	O5	A	640.00	-7773.00
215	VSS	A	-1144.50	-2480.00	285	VSS	A	-1144.50	-5630.00	355	O4	A	685.00	-7773.00
216	VSS	A	-1144.50	-2525.00	286	VSS	A	-1144.50	-5675.00	356	O3	A	730.00	-7773.00
217	VSS	A	-1144.50	-2570.00	287	VR	A	-1144.50	-5720.00	357	O2	A	775.00	-7773.00
218	OSCOU	A	-1144.50	-2615.00	288	VR	A	-1144.50	-5765.00	358	O1	A	820.00	-7773.00
219	OSCOU	A	-1144.50	-2660.00	289	VR	A	-1144.50	-5810.00	359	DUMMY	B	945.00	-7773.00
220	OSCOU	A	-1144.50	-2705.00	290	AMPOUTM	A	-1144.50	-5855.00	360	DUMMY	B	1033.00	-7080.00
221	VSS	A	-1144.50	-2750.00	291	AMPOUTM	A	-1144.50	-5900.00	361	SEG1	A	1033.00	-6955.00
222	VSS	A	-1144.50	-2795.00	292	AMPOUTM	A	-1144.50	-5945.00	362	SEG2	A	1033.00	-6910.00
223	VSS	A	-1144.50	-2840.00	293	VSS	A	-1144.50	-5990.00	363	SEG3	A	1033.00	-6865.00
224	TSTRST	A	-1144.50	-2885.00	294	VSS	A	-1144.50	-6035.00	364	SEG4	A	1033.00	-6820.00
225	TSTRST	A	-1144.50	-2930.00	295	VSS	A	-1144.50	-6080.00	365	SEG5	A	1033.00	-6775.00
226	TSTRST	A	-1144.50	-2975.00	296	AMPOUTS	A	-1144.50	-6125.00	366	SEG6	A	1033.00	-6730.00
227	TSTVIHL	A	-1144.50	-3020.00	297	AMPOUTS	A	-1144.50	-6170.00	367	SEG7	A	1033.00	-6685.00
228	TSTVIHL	A	-1144.50	-3065.00	298	AMPOUTS	A	-1144.50	-6215.00	368	SEG8	A	1033.00	-6640.00
229	TSTVIHL	A	-1144.50	-3110.00	299	VSS	A	-1144.50	-6260.00	369	SEG9	A	1033.00	-6595.00
230	TOUT15	A	-1144.50	-3155.00	300	VSS	A	-1144.50	-6305.00	370	SEG10	A	1033.00	-6550.00
231	TOUT15	A	-1144.50	-3200.00	301	VSS	A	-1144.50	-6350.00	371	SEG11	A	1033.00	-6505.00
232	TOUT15	A	-1144.50	-3245.00	302	VLCD	A	-1144.50	-6395.00	372	SEG12	A	1033.00	-6460.00
233	TOUT14	A	-1144.50	-3290.00	303	VLCD	A	-1144.50	-6440.00	373	SEG13	A	1033.00	-6415.00
234	TOUT14	A	-1144.50	-3335.00	304	VLCD	A	-1144.50	-6485.00	374	SEG14	A	1033.00	-6370.00
235	TOUT14	A	-1144.50	-3380.00	305	VLC1	A	-1144.50	-6530.00	375	SEG15	A	1033.00	-6325.00
236	TOUT13	A	-1144.50	-3425.00	306	VLC1	A	-1144.50	-6575.00	376	SEG16	A	1033.00	-6280.00
237	TOUT13	A	-1144.50	-3470.00	307	VLC1	A	-1144.50	-6620.00	377	SEG17	A	1033.00	-6235.00
238	TOUT13	A	-1144.50	-3515.00	308	VLC2	A	-1144.50	-6665.00	378	SEG18	A	1033.00	-6190.00
239	TOUT12	A	-1144.50	-3560.00	309	VLC2	A	-1144.50	-6710.00	379	SEG19	A	1033.00	-6145.00
240	TOUT12	A	-1144.50	-3605.00	310	VLC2	A	-1144.50	-6755.00	380	SEG20	A	1033.00	-6100.00
241	TOUT12	A	-1144.50	-3650.00	311	VLC3	A	-1144.50	-6800.00	381	SEG21	A	1033.00	-6055.00
242	TOUT11	A	-1144.50	-3695.00	312	VLC3	A	-1144.50	-6845.00	382	SEG22	A	1033.00	-6010.00
243	TOUT11	A	-1144.50	-3740.00	313	VLC3	A	-1144.50	-6890.00	383	SEG23	A	1033.00	-5965.00
244	TOUT11	A	-1144.50	-3785.00	314	VLC4	A	-1144.50	-6935.00	384	SEG24	A	1033.00	-5920.00
245	TOUT10	A	-1144.50	-3830.00	315	VLC4	A	-1144.50	-6980.00	385	SEG25	A	1033.00	-5875.00
246	TOUT10	A	-1144.50	-3875.00	316	VLC4	A	-1144.50	-7025.00	386	SEG26	A	1033.00	-5830.00
247	TOUT10	A	-1144.50	-3920.00	317	DUMMY	B	-1144.50	-7150.00	387	SEG27	A	1033.00	-5785.00
248	TOUT9	A	-1144.50	-3965.00	318	DUMMY	B	-1060.00	-7773.00	388	SEG28	A	1033.00	-5740.00
249	TOUT9	A	-1144.50	-4010.00	319	O40	A	-935.00	-7773.00	389	SEG29	A	1033.00	-5695.00
250	TOUT9	A	-1144.50	-4055.00	320	O39	A	-890.00	-7773.00	390	SEG30	A	1033.00	-5650.00
251	TOUT8	A	-1144.50	-4100.00	321	O38	A	-845.00	-7773.00	391	SEG31	A	1033.00	-5605.00
252	TOUT8	A	-1144.50	-4145.00	322	O37	A	-800.00	-7773.00	392	SEG32	A	1033.00	-5560.00
253	TOUT8	A	-1144.50	-4190.00	323	O36	A	-755.00	-7773.00	393	SEG33	A	1033.00	-5515.00
254	TOUT7	A	-1144.50	-4235.00	324	O35	A	-710.00	-7773.00	394	SEG34	A	1033.00	-5470.00
255	TOUT7	A	-1144.50	-4280.00	325	O34	A	-665.00	-7773.00	395	SEG35	A	1033.00	-5425.00
256	TOUT7	A	-1144.50	-4325.00	326	O33	A	-620.00	-7773.00	396	SEG36	A	1033.00	-5380.00
257	TOUT6	A	-1144.50	-4370.00	327	O32	A	-575.00	-7773.00	397	SEG37	A	1033.00	-5335.00
258	TOUT6	A	-1144.50	-4415.00	328	O31	A	-530.00	-7773.00	398	SEG38	A	1033.00	-5290.00
259	TOUT6	A	-1144.50	-4460.00	329	O30	A	-485.00	-7773.00	399	SEG39	A	1033.00	-5245.00
260	TOUT5	A	-1144.50	-4505.00	330	O29	A	-440.00	-7773.00	400	SEG40	A	1033.00	-5200.00
261	TOUT5	A	-1144.50	-4550.00	331	O28	A	-395.00	-7773.00	401	SEG41	A	1033.00	-5155.00
262	TOUT5	A	-1144.50	-4595.00	332	O27	A	-350.00	-7773.00	402	SEG42	A	1033.00	-5110.00
263	TOUT4	A	-1144.50	-4640.00	333	O26	A	-305.00	-7773.00	403	SEG43	A	1033.00	-5065.00
264	TOUT4	A	-1144.50	-4685.00	334	O25	A	-260.00	-7773.00	404	SEG44	A	1033.00	-5020.00
265	TOUT4	A	-1144.50	-4730.00	335	O24	A	-215.00	-7773.00	405	SEG45	A	1033.00	-4975.00
266	TOUT3	A	-1144.50	-4775.00	336	O23	A	-170.00	-7773.00	406	SEG46	A	1033.00	-4930.00
267	TOUT3	A	-1144.50	-4820.00	337	O22	A	-125.00	-7773.00	407	SEG47	A	1033.00	-4885.00
268	TOUT3	A	-1144.50	-4865.00	338	O21	A	-80.00	-7773.00	408	SEG48	A	1033.00	-4840.00
269	TOUT2	A	-1144.50	-4910.00	339	O20	A	-35.00	-7773.00	409	SEG49	A	1033.00	-4795.00
270	TOUT2	A	-1144.50	-4955.00	340	O19	A	10.00	-7773.00	410	SEG50	A	1033.00	-4750.00
271	TOUT2	A	-1144.50	-5000.00	341	O18	A	55.00	-7773.00	411	SEG51	A	1033.00	-4705.00
272	TOUT1	A	-1144.50	-5045.00	342	O17	A	100.00	-7773.00	412	SEG52	A	1033.00	-4660.00
273	TOUT1	A	-1144.50	-5090.00	343	O16	A	145.00	-7773.00	413	SEG53	A	1033.00	-4615.00
274	TOUT1	A	-1144.50	-5135.00	344	O15	A	190.00	-7773.00	414	SEG54	A	1033.00	-4570.00
275	TOUT0	A	-1144.50	-5180.00	345	O14	A	235.00	-7773.00	415	SEG55	A	1033.00	-4525.00
276	TOUT0	A	-1144.50	-5225.00	346	O13	A	280.00	-7773.00	416	SEG56	A	1033.00	-4480.00
277	TOUT0	A	-1144.50	-5270.00	347	O12	A	325.00	-7773.00	417	SEG57	A	1033.00	-4435.00
278	VSS	A	-1144.50	-5315.00	348	O11	A	370.00	-7773.00	418	SEG58	A	1033.00	-4390.00
279	VSS	A	-1144.50	-5360.00	349	O10	A	415.00	-7773.00	419	SEG59	A	1033.00	-4345.00
280	VSS	A	-1144.50	-5405.00	350	O9	A	460.00	-7773.00	420	SEG60	A	1033.00	-4300.00

Table 2-1 Pad Layout (3/4)

Pad No.	Pad Name	Pad Type	Pad Layout [μm]		Pad No.	Pad Name	Pad Type	Pad Layout [μm]		Pad No.	Pad Name	Pad Type	Pad Layout [μm]	
			X	Y				X	Y				X	Y
421	SEG61	A	1033.00	-4255.00	491	SEG131	A	1033.00	-1105.00	561	SEG194	A	1033.00	2045.00
422	SEG62	A	1033.00	-4210.00	492	SEG132	A	1033.00	-1060.00	562	SEG195	A	1033.00	2090.00
423	SEG63	A	1033.00	-4165.00	493	SEG133	A	1033.00	-1015.00	563	SEG196	A	1033.00	2135.00
424	SEG64	A	1033.00	-4120.00	494	SEG134	A	1033.00	-970.00	564	SEG197	A	1033.00	2180.00
425	SEG65	A	1033.00	-4075.00	495	SEG135	A	1033.00	-925.00	565	SEG198	A	1033.00	2225.00
426	SEG66	A	1033.00	-4030.00	496	SEG136	A	1033.00	-880.00	566	SEG199	A	1033.00	2270.00
427	SEG67	A	1033.00	-3985.00	497	SEG137	A	1033.00	-835.00	567	SEG200	A	1033.00	2315.00
428	SEG68	A	1033.00	-3940.00	498	SEG138	A	1033.00	-790.00	568	SEG201	A	1033.00	2360.00
429	SEG69	A	1033.00	-3895.00	499	SEG139	A	1033.00	-745.00	569	SEG202	A	1033.00	2405.00
430	SEG70	A	1033.00	-3850.00	500	SEG140	A	1033.00	-700.00	570	SEG203	A	1033.00	2450.00
431	SEG71	A	1033.00	-3805.00	501	SEG141	A	1033.00	-655.00	571	SEG204	A	1033.00	2495.00
432	SEG72	A	1033.00	-3760.00	502	SEG142	A	1033.00	-610.00	572	SEG205	A	1033.00	2540.00
433	SEG73	A	1033.00	-3715.00	503	SEG143	A	1033.00	-565.00	573	SEG206	A	1033.00	2585.00
434	SEG74	A	1033.00	-3670.00	504	SEG144	A	1033.00	-520.00	574	SEG207	A	1033.00	2630.00
435	SEG75	A	1033.00	-3625.00	505	SEG145	A	1033.00	-475.00	575	SEG208	A	1033.00	2675.00
436	SEG76	A	1033.00	-3580.00	506	SEG146	A	1033.00	-430.00	576	SEG209	A	1033.00	2720.00
437	SEG77	A	1033.00	-3535.00	507	SEG147	A	1033.00	-385.00	577	SEG210	A	1033.00	2765.00
438	SEG78	A	1033.00	-3490.00	508	SEG148	A	1033.00	-340.00	578	SEG211	A	1033.00	2810.00
439	SEG79	A	1033.00	-3445.00	509	SEG149	A	1033.00	-295.00	579	SEG212	A	1033.00	2855.00
440	SEG80	A	1033.00	-3400.00	510	SEG150	A	1033.00	-250.00	580	SEG213	A	1033.00	2900.00
441	SEG81	A	1033.00	-3355.00	511	SEG151	A	1033.00	-205.00	581	SEG214	A	1033.00	2945.00
442	SEG82	A	1033.00	-3310.00	512	SEG152	A	1033.00	-160.00	582	SEG215	A	1033.00	2990.00
443	SEG83	A	1033.00	-3265.00	513	SEG153	A	1033.00	-115.00	583	SEG216	A	1033.00	3035.00
444	SEG84	A	1033.00	-3220.00	514	SEG154	A	1033.00	-70.00	584	SEG217	A	1033.00	3080.00
445	SEG85	A	1033.00	-3175.00	515	SEG155	A	1033.00	-25.00	585	SEG218	A	1033.00	3125.00
446	SEG86	A	1033.00	-3130.00	516	SEG156	A	1033.00	20.00	586	SEG219	A	1033.00	3170.00
447	SEG87	A	1033.00	-3085.00	517	SEG157	A	1033.00	65.00	587	SEG220	A	1033.00	3215.00
448	SEG88	A	1033.00	-3040.00	518	SEG158	A	1033.00	110.00	588	SEG221	A	1033.00	3260.00
449	SEG89	A	1033.00	-2995.00	519	SEG159	A	1033.00	155.00	589	SEG222	A	1033.00	3305.00
450	SEG90	A	1033.00	-2950.00	520	SEG160	A	1033.00	200.00	590	SEG223	A	1033.00	3350.00
451	SEG91	A	1033.00	-2905.00	521	SEG161	A	1033.00	245.00	591	SEG224	A	1033.00	3395.00
452	SEG92	A	1033.00	-2860.00	522	SEG162	A	1033.00	290.00	592	SEG225	A	1033.00	3440.00
453	SEG93	A	1033.00	-2815.00	523	SEG163	A	1033.00	335.00	593	SEG226	A	1033.00	3485.00
454	SEG94	A	1033.00	-2770.00	524	SEG164	A	1033.00	380.00	594	SEG227	A	1033.00	3530.00
455	SEG95	A	1033.00	-2725.00	525	SEG165	A	1033.00	425.00	595	SEG228	A	1033.00	3575.00
456	SEG96	A	1033.00	-2680.00	526	SEG166	A	1033.00	470.00	596	SEG229	A	1033.00	3620.00
457	SEG97	A	1033.00	-2635.00	527	SEG167	A	1033.00	515.00	597	SEG230	A	1033.00	3665.00
458	SEG98	A	1033.00	-2590.00	528	SEG168	A	1033.00	560.00	598	SEG231	A	1033.00	3710.00
459	SEG99	A	1033.00	-2545.00	529	SEG169	A	1033.00	605.00	599	SEG232	A	1033.00	3755.00
460	SEG100	A	1033.00	-2500.00	530	SEG170	A	1033.00	650.00	600	SEG233	A	1033.00	3800.00
461	SEG101	A	1033.00	-2455.00	531	SEG171	A	1033.00	695.00	601	SEG234	A	1033.00	3845.00
462	SEG102	A	1033.00	-2410.00	532	SEG172	A	1033.00	740.00	602	SEG235	A	1033.00	3890.00
463	SEG103	A	1033.00	-2365.00	533	SEG173	A	1033.00	785.00	603	SEG236	A	1033.00	3935.00
464	SEG104	A	1033.00	-2320.00	534	SEG174	A	1033.00	830.00	604	SEG237	A	1033.00	3980.00
465	SEG105	A	1033.00	-2275.00	535	SEG175	A	1033.00	875.00	605	SEG238	A	1033.00	4025.00
466	SEG106	A	1033.00	-2230.00	536	SEG176	A	1033.00	920.00	606	SEG239	A	1033.00	4070.00
467	SEG107	A	1033.00	-2185.00	537	SEG177	A	1033.00	965.00	607	SEG240	A	1033.00	4115.00
468	SEG108	A	1033.00	-2140.00	538	SEG178	A	1033.00	1010.00	608	SEG241	A	1033.00	4160.00
469	SEG109	A	1033.00	-2095.00	539	SEG179	A	1033.00	1055.00	609	SEG242	A	1033.00	4205.00
470	SEG110	A	1033.00	-2050.00	540	SEG180	A	1033.00	1100.00	610	SEG243	A	1033.00	4250.00
471	SEG111	A	1033.00	-2005.00	541	SEG181	A	1033.00	1145.00	611	SEG244	A	1033.00	4295.00
472	SEG112	A	1033.00	-1960.00	542	SEG182	A	1033.00	1190.00	612	SEG245	A	1033.00	4340.00
473	SEG113	A	1033.00	-1915.00	543	SEG183	A	1033.00	1235.00	613	SEG246	A	1033.00	4385.00
474	SEG114	A	1033.00	-1870.00	544	SEG184	A	1033.00	1280.00	614	SEG247	A	1033.00	4430.00
475	SEG115	A	1033.00	-1825.00	545	SEG185	A	1033.00	1325.00	615	SEG248	A	1033.00	4475.00
476	SEG116	A	1033.00	-1780.00	546	SEG186	A	1033.00	1370.00	616	SEG249	A	1033.00	4520.00
477	SEG117	A	1033.00	-1735.00	547	SEG187	A	1033.00	1415.00	617	SEG250	A	1033.00	4565.00
478	SEG118	A	1033.00	-1690.00	548	SEG188	A	1033.00	1460.00	618	SEG251	A	1033.00	4610.00
479	SEG119	A	1033.00	-1645.00	549	SEG189	A	1033.00	1505.00	619	SEG252	A	1033.00	4655.00
480	SEG120	A	1033.00	-1600.00	550	SEG190	A	1033.00	1550.00	620	SEG253	A	1033.00	4700.00
481	SEG121	A	1033.00	-1555.00	551	SEG191	A	1033.00	1595.00	621	SEG254	A	1033.00	4745.00
482	SEG122	A	1033.00	-1510.00	552	SEG192	A	1033.00	1640.00	622	SEG255	A	1033.00	4790.00
483	SEG123	A	1033.00	-1465.00	553	DUMMY	A	1033.00	1685.00	623	SEG256	A	1033.00	4835.00
484	SEG124	A	1033.00	-1420.00	554	DUMMY	A	1033.00	1730.00	624	SEG257	A	1033.00	4880.00
485	SEG125	A	1033.00	-1375.00	555	DUMMY	A	1033.00	1775.00	625	SEG258	A	1033.00	4925.00
486	SEG126	A	1033.00	-1330.00	556	DUMMY	A	1033.00	1820.00	626	SEG259	A	1033.00	4970.00
487	SEG127	A	1033.00	-1285.00	557	DUMMY	A	1033.00	1865.00	627	SEG260	A	1033.00	5015.00
488	SEG128	A	1033.00	-1240.00	558	DUMMY	A	1033.00	1910.00	628	SEG261	A	1033.00	5060.00
489	SEG129	A	1033.00	-1195.00	559	DUMMY	A	1033.00	1955.00	629	SEG262	A	1033.00	5105.00
490	SEG130	A	1033.00	-1150.00	560	SEG193	A	1033.00	2000.00	630	SEG263	A	1033.00	5150.00

Table 2-1 Pad Layout (4/4)

Pad No.	Pad Name	Pad Type	Pad Layout [μm]		Pad No.	Pad Name	Pad Type	Pad Layout [μm]	
			X	Y				X	Y
631	SEG264	A	1033.00	5195.00	701	O69	A	-435.00	7773.00
632	SEG265	A	1033.00	5240.00	702	O70	A	-480.00	7773.00
633	SEG266	A	1033.00	5285.00	703	O71	A	-525.00	7773.00
634	SEG267	A	1033.00	5330.00	704	O72	A	-570.00	7773.00
635	SEG268	A	1033.00	5375.00	705	O73	A	-615.00	7773.00
636	SEG269	A	1033.00	5420.00	706	O74	A	-660.00	7773.00
637	SEG270	A	1033.00	5465.00	707	O75	A	-705.00	7773.00
638	SEG271	A	1033.00	5510.00	708	O76	A	-750.00	7773.00
639	SEG272	A	1033.00	5555.00	709	O77	A	-795.00	7773.00
640	SEG273	A	1033.00	5600.00	710	O78	A	-840.00	7773.00
641	SEG274	A	1033.00	5645.00	711	O79	A	-885.00	7773.00
642	SEG275	A	1033.00	5690.00	712	O80	A	-930.00	7773.00
643	SEG276	A	1033.00	5735.00	713	DUMMY	B	-1055.00	7773.00
644	SEG277	A	1033.00	5780.00					
645	SEG278	A	1033.00	5825.00					
646	SEG279	A	1033.00	5870.00					
647	SEG280	A	1033.00	5915.00					
648	SEG281	A	1033.00	5960.00					
649	SEG282	A	1033.00	6005.00					
650	SEG283	A	1033.00	6050.00					
651	SEG284	A	1033.00	6095.00					
652	SEG285	A	1033.00	6140.00					
653	SEG286	A	1033.00	6185.00					
654	SEG287	A	1033.00	6230.00					
655	SEG288	A	1033.00	6275.00					
656	SEG289	A	1033.00	6320.00					
657	SEG290	A	1033.00	6365.00					
658	SEG291	A	1033.00	6410.00					
659	SEG292	A	1033.00	6455.00					
660	SEG293	A	1033.00	6500.00					
661	SEG294	A	1033.00	6545.00					
662	SEG295	A	1033.00	6590.00					
663	SEG296	A	1033.00	6635.00					
664	SEG297	A	1033.00	6680.00					
665	SEG298	A	1033.00	6725.00					
666	SEG299	A	1033.00	6770.00					
667	SEG300	A	1033.00	6815.00					
668	SEG301	A	1033.00	6860.00					
669	SEG302	A	1033.00	6905.00					
670	SEG303	A	1033.00	6950.00					
671	DUMMY	A	1033.00	7075.00					
672	DUMMY	A	950.00	7773.00					
673	O41	A	825.00	7773.00					
674	O42	A	780.00	7773.00					
675	O43	A	735.00	7773.00					
676	O44	A	690.00	7773.00					
677	O45	A	645.00	7773.00					
678	O46	A	600.00	7773.00					
679	O47	A	555.00	7773.00					
680	O48	A	510.00	7773.00					
681	O49	A	465.00	7773.00					
682	O50	A	420.00	7773.00					
683	O51	A	375.00	7773.00					
684	O52	A	330.00	7773.00					
685	O53	A	285.00	7773.00					
686	O54	A	240.00	7773.00					
687	O55	A	195.00	7773.00					
688	O56	A	150.00	7773.00					
689	O57	A	105.00	7773.00					
690	O58	A	60.00	7773.00					
691	O59	A	15.00	7773.00					
692	O60	A	-30.00	7773.00					
693	O61	A	-75.00	7773.00					
694	O62	A	-120.00	7773.00					
695	O63	A	-165.00	7773.00					
696	O64	A	-210.00	7773.00					
697	O65	A	-255.00	7773.00					
698	O66	A	-300.00	7773.00					
699	O67	A	-345.00	7773.00					
700	O68	A	-390.00	7773.00					

### 3. PIN FUNCTIONS

#### 3.1 Power Supply Pins

Symbol	Pin Name	Pin No.	I/O	Description
V <sub>DD1</sub>	Logic power supply	65 to 67, 77 to 79, 89 to 91, 104 to 106, 122 to 124	—	Supplies power to the logic circuit.
V <sub>DD2</sub>	Booster circuit power supply	62 to 64	—	Supplies power to the booster circuit.
V <sub>SS</sub>	Logic and driver ground pin	2 to 4, 11 to 13, 44 to 46, 56 to 61, 68 to 73, 83 to 85, 95 to 97, 113 to 115, 134 to 136, 146 to 148, 155 to 157, 167 to 169, 179 to 181, 188 to 190, 203 to 205, 209 to 211, 215 to 217, 221 to 223, 278 to 286, 293 to 295, 299 to 301	—	Ground pin for the logic and driver circuits.
V <sub>OUT</sub> , V <sub>OUT2</sub>	Driver power supply	5 to 7, 8 to 10	—	Supply power to the driver (output pins of the internal booster circuit). Connect a 1 μF capacitor between GND and these pins. When the internal booster circuit is not used, the driver power can be directly input to the V <sub>OUT</sub> pin. At this time, leave V <sub>OUT2</sub> open.
V <sub>LCD</sub> , V <sub>LC1</sub> to V <sub>LC4</sub>	Driver reference power supply	302 to 304, 305 to 316	—	Supply the reference power for driving the LCD. Connect a capacitor between GND and these pins when an internal bias is selected.
C <sub>1</sub> <sup>+</sup> , C <sub>1</sub> <sup>-</sup> C <sub>2</sub> <sup>+</sup> , C <sub>2</sub> <sup>-</sup> C <sub>3</sub> <sup>+</sup> , C <sub>3</sub> <sup>-</sup> C <sub>4</sub> <sup>+</sup> , C <sub>4</sub> <sup>-</sup> C <sub>5</sub> <sup>+</sup> , C <sub>5</sub> <sup>-</sup>	Booster capacitor connection pin	43 to 14	—	These pins are used to connect capacitors for the internal booster circuit. Connect a 1 μF capacitor between the corresponding (+) and (-) pins.

### 3.2 Logic Circuit Pins (1/3)

Symbol	Pin Name	Pin No.	I/O	Description															
/CS1, CS2	Chip select	98 to 100, 101 to 103	Input	These pins are chip select signal pins. When /CS1 = L (CS2 = H), the chip is active, and data/command can be input or output and I/O manipulated.															
/RD (E)	Read (enable)	119 to 121	Input	When i80 system parallel data transfer is selected (/RD), read is enabled by this signal. When this pin is L, data is output to the data bus. When M68 system parallel data transfer is selected (E), this pin inputs an enable signal that triggers data write or read. But in the $\mu$ PD161401, the data of the display access memory register, the complementary color blink data memory register, the specified color blink data memory register and the reverse data memory access register (R12, R41, R45, R50) cannot be read.															
/WR (R,/W)	Write (read/write)	116 to 118	Input	When i80 system parallel data transfer is selected (/WR), write is enabled by this signal. Data is written at the rising edge of this signal. When M68 system parallel data transfer is selected (R, /W), this pin determines the data transfer direction, as follows: 0: Write 1: Read															
IFM0, IFM1	Interface selection	86 to 88, 80 to 82	Input	Selects an interface mode <table border="1"><thead><tr><th>IFM1</th><th>IFM0</th><th>Interface Mode</th></tr></thead><tbody><tr><td>L</td><td>L</td><td>Serial</td></tr><tr><td>L</td><td>H</td><td>Setting prohibited</td></tr><tr><td>H</td><td>L</td><td>i80 series parallel</td></tr><tr><td>H</td><td>H</td><td>M68 series parallel</td></tr></tbody></table>	IFM1	IFM0	Interface Mode	L	L	Serial	L	H	Setting prohibited	H	L	i80 series parallel	H	H	M68 series parallel
IFM1	IFM0	Interface Mode																	
L	L	Serial																	
L	H	Setting prohibited																	
H	L	i80 series parallel																	
H	H	M68 series parallel																	
D <sub>0</sub> to D <sub>15</sub> (SI) (SCL)	Data bus (serial input) (serial clock)	187 to 182, 178 to 170, 166 to 158, 154 to 149, 145 to 137, 133 to 125	I/O	This is a bi-directional data bus connected to an 8- or 16-bit standard CPU bus. When the serial interface mode is selected (IFM1, IFM0 = L, L), D <sub>7</sub> functions as a serial data input pin (SI), and D <sub>6</sub> serves as a serial clock input pin (SCL). At this time, D <sub>0</sub> to D <sub>5</sub> and D <sub>8</sub> to D <sub>15</sub> go into a high-impedance state. When the 8-bit data bus is selected, only D <sub>0</sub> to D <sub>7</sub> are used, and D <sub>8</sub> to D <sub>15</sub> go into a high-impedance state. Data is input starting from its higher byte, followed by the lower byte. If the chip is not selected, all D <sub>0</sub> to D <sub>15</sub> go into a high-impedance state.															
RS	Index register/data command selection	110 to 112	Input	This pin is usually connected to the least significant bit of a standard CPU address bus to identify whether data is an index register or data/command. RS = H: Indicates that D <sub>0</sub> to D <sub>15</sub> are data/command. RS = L: Indicates that D <sub>0</sub> to D <sub>15</sub> are an index register.															

(2/3)

Symbol	Pin Name	Pin No.	I/O	Description															
/DISP	Reset	107 to 109	Input	Making /DISP low initializes the DISP flag in the control register 1 (R0) and turns OFF the display. When the serial interface is used, the write counter is also initialized. Making /DISP high enables writing. To light the display after it has been turned OFF by this pin, make /DISP high and set the DISP flag to 1.															
FR	Frame signal	194 to 196	I/O	This pin inputs or outputs a liquid crystal AC signal. M,/S = H : Output M,/S = L : Input When two or more μPD161401s are used in master/slave mode, the respective FR pins must be connected to each other.															
FR <sub>SYNC</sub>	Frame sync signal	191 to 193	I/O	This pin inputs or outputs a liquid crystal AC sync signal. M,/S = H : Output M,/S = L : Input When two or more μPD161401s are used in master/slave mode, the respective FR <sub>SYNC</sub> pins must be connected to each other.															
DOF	Display blink	197 to 199	I/O	This pin controls blinking of the LCD. M,/S = H : Output M,/S = L : Input When two or more μPD161401s are used in master/slave mode, the respective DOF pins must be connected to each other.															
M,/S	Master/slave	74 to 76	Input	<p>This pin selects master or slave mode. In the master mode, it outputs a timing signal necessary for driving the LCD. In the slave mode, this timing signal is input from an external source to synchronize the LCD. M,/S = H : Master mode M,/S = L : Slave mode</p> <p>The status of each pin, including this pin, and the power circuit is as follows depending on the status of the M,/S pin.</p> <table border="1"> <thead> <tr> <th>M,/S</th><th>Power Circuit</th><th>FR</th><th>FR<sub>SYNC</sub></th><th>DOF</th></tr> </thead> <tbody> <tr> <td>H</td><td>Enabled</td><td>Output</td><td>Output</td><td>Output</td></tr> <tr> <td>L</td><td>Disabled</td><td>Input</td><td>Input</td><td>Input</td></tr> </tbody> </table>	M,/S	Power Circuit	FR	FR <sub>SYNC</sub>	DOF	H	Enabled	Output	Output	Output	L	Disabled	Input	Input	Input
M,/S	Power Circuit	FR	FR <sub>SYNC</sub>	DOF															
H	Enabled	Output	Output	Output															
L	Disabled	Input	Input	Input															
IRS	V <sub>LCD</sub> adjustment	92 to 94	Input	<p>This pin selects the resistor used to adjust the V<sub>LCD</sub> voltage level.</p> <p>IRS = H: The internal resistor is used. IRS = L: The internal resistor is not used.</p> <p>The V<sub>LCD</sub> voltage level is adjusted by an external voltage divider resistor connected to the V<sub>R</sub> pin.</p> <p>This pin is enabled only when the master operation mode is selected. If the slave mode is selected, this pin is fixed to H or L.</p>															

(3/3)

Symbol	Pin Name	Pin No.	I/O	Description
OSC <sub>IN1</sub>	Oscillation signal pin	206 to 208	Input	These pins are connected with a resistor inserted between OSC <sub>IN1</sub> and OSC <sub>OUT</sub> , and between OSC <sub>IN2</sub> and OSC <sub>OUT</sub> . When an external oscillator is used, input a clock signal to the OSC <sub>IN</sub> pin and leave the OSC <sub>OUT</sub> pin open.
OSC <sub>IN2</sub>		212 to 214	Input	
OSC <sub>OUT</sub>		218 to 220	Output	
OSC <sub>SYNC</sub>	Display clock output	200 to 202	Output	This pin outputs a clock for display. When using the μPD161401 in the master or slave mode, refer to <b>5.4 Oscillator</b> .
T <sub>OUT0</sub> to T <sub>OUT15</sub>	Test output	230 to 277	Output	These pins are used when the μPD161401 is in the test mode. Usually, leave these pins open.
TSTRTST, TSTVIHL	Test input pin	224 to 226, 227 to 229	Input	These pins are used to set the μPD161401 in the test mode. Usually, connect these pins to V <sub>SS</sub> .
TPWR <sub>0</sub> , TPWR <sub>1</sub>	Test input/output pin	50 to 52, 47 to 49	I/O	These pins are used to input/output test signals when the μPD161401 is in the test mode. Usually, leave these pins open.

### 3.3 Driver Pins

Symbol	Pin Name	Pin No.	I/O	Description
SEG <sub>1</sub> to SEG <sub>303</sub>	Segment	361 to 670	Output	These pins output segment signals.
O <sub>1</sub> to O <sub>80</sub>	Common	319 to 358, 673 to 712	Output	These pins output common signals.
V <sub>RS</sub>	Operational amplifier input	53 to 55	Input	These are the input pins of the operational amplifier that adjusts the LCD driving voltage. V <sub>RS</sub> is used to input the reference voltage of the amplifier for LCD voltage adjustment. V <sub>R</sub> is used to connect a feedback resistor for the operational amplifier. The feedback resistor is connected between this pin and GND, AMP <sub>OUTM</sub> , or AMP <sub>OUTS</sub> . This pin is enabled only when the internal divider resistor for V <sub>LCD</sub> voltage adjustment is not used (IRS = L). When the internal divider resistor is used (IRS = H), this pin is not used.
V <sub>R</sub>		287 to 289		
AMP <sub>OUTM</sub>	Operational amplifier output	290 to 292	Output	These pins are the output pins of the operational amplifier that adjusts the LCD driving voltage. The signals output by these pins are connected to the LCD driving voltage adjuster resistor (refer to <b>5.6.3 Voltage regulator circuit</b> ) only when the internal resistor for LCD voltage adjustment is not used (IRS = L). It is recommended to connect a capacitor of 0.01 to 0.1 μF to these pins to stabilize the output of the internal operational amplifier.
AMP <sub>OUTS</sub>		296 to 298		
DUMMY	Dummy pin	1, 317, 318, 359, 360, 553 to 559, 671, 672, 713	–	These pins are not connected to the internal circuit.

#### 4. PIN I/O CIRCUITS AND RECOMMENDED CONNECTION OF UNUSED PINS

The I/O circuit type of each pin and recommended connection of unused pins are shown in the table below.

Symbol	Input Type	I/O	Recommended of Unused Pins	Note
/CS1	Schmitt-trigger A	Input	Connect this pin to V <sub>SS</sub> .	–
CS2	Schmitt-trigger A	Input	Connect this pin to V <sub>DD1</sub> .	–
/RD(E)	Schmitt-trigger A	Input	Connect to V <sub>DD1</sub> (i80 system interface), or to V <sub>DD1</sub> or V <sub>SS</sub> (serial interface).	–
/WR(R,/W)	Schmitt-trigger A	Input	Connect to V <sub>DD1</sub> or V <sub>SS</sub> (serial interface).	–
IFM1, IFM0	Schmitt-trigger A	Input	Mode setting pin	1
D <sub>0</sub> to D <sub>5</sub>	Schmitt-trigger B	I/O	Leave open.	–
D <sub>6</sub> (SCL)	Schmitt-trigger B	I/O	–	–
D <sub>7</sub> (SI)	Schmitt-trigger B	I/O	–	–
D <sub>8</sub> to D <sub>15</sub>	Schmitt-trigger B	I/O	Leave open.	–
RS	Schmitt-trigger A	Input	Register setting pin	2
/DISP	Schmitt-trigger C	Input	Connect to V <sub>DD1</sub> .	–
FR	Schmitt-trigger A	I/O	Leave open (in master mode, M,/S = H).	–
FR <sub>SYNC</sub>	Schmitt-trigger A	I/O	Leave open (in master mode, M,/S = H).	–
DOF	Schmitt-trigger A	I/O	Leave open (in master mode, M,/S = H).	–
M,/S	Schmitt-trigger A	Input	Mode setting pin	1
IRS	Schmitt-trigger A	Input	Mode setting pin	1
OSC <sub>IN1</sub>	Schmitt-trigger A	Input	Connect to V <sub>DD1</sub> or V <sub>SS</sub> .	–
OSC <sub>IN2</sub>	Schmitt-trigger A	Input	Connect to V <sub>DD1</sub> or V <sub>SS</sub> .	–
OSC <sub>OUT</sub>	–	Output	Leave open (when an external clock is used).	–
OSC <sub>SYNC</sub>	–	Output	Leave open.	–
T <sub>OUT0</sub> to T <sub>OUT15</sub>	–	Output	Leave open.	–
TSTRTST	Schmitt-trigger A	Input	Connect this pin to V <sub>SS</sub> (in normal operation mode).	–
TSTVIHL	Schmitt-trigger A	Input	Connect this pin to V <sub>SS</sub> (in normal operation mode).	–
TPWR	–	I/O	Leave open.	–

**Notes** 1. Connect this pin to V<sub>DD1</sub> or V<sub>SS</sub> depending on the mode selected.

2. Input V<sub>DD1</sub> or V<sub>SS</sub> output from the CPU to this pin depending on the mode selected.

**Remark** Schmitt-trigger A : Schmitt inverter

Schmitt-trigger B : Schmitt NAND

Schmitt-trigger C : Schmitt inverter (with delay circuit)



## 5. FUNCTIONAL DESCRIPTION

### 5.1 CPU Interface

#### 5.1.1 Selecting interface type

The μPD161401 transfers data through an 8-bit bi-directional data bus (D<sub>7</sub> to D<sub>0</sub>), a 16-bit bi-directional data bus (D<sub>15</sub> to D<sub>0</sub>), or a serial data input (SI) pin. Interface type can be selected by making the IFM1, IFM0 pin high or low, as shown in the following table.

IFM1	IFM0	Interface type
L	L	Serial data input
L	H	Setting Prohibited
H	L	i80 system CPU
H	H	M68 system CPU

Parallel data input or serial data input can be chosen as by setting the polarity of IFM1 terminal, as shown in the following table.

IFM1	/CS1, CS2	RS	/RD	/WR	D <sub>15</sub> to D <sub>8</sub>	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub> to D <sub>0</sub>
H: Parallel input	/CS1, CS2	RS	/RD	/WR	D <sub>15</sub> to D <sub>8</sub>	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub> to D <sub>0</sub>
L: Serial input	/CS1, CS2	RS	Note1	Note1	Hi-Z <sup>Note2</sup>	SI	SCL	Hi-Z <sup>Note2</sup>

**Notes 1.** Fix these pins to the high or low level.

**2.** Hi-Z: High impedance

#### 5.1.2 Parallel interface

When the parallel interface is selected (IFM = H), an 8-bit bi-directional data bus (D<sub>7</sub> to D<sub>0</sub>) or 16-bit bi-directional data bus (D<sub>15</sub> to D<sub>0</sub>) can be selected by setting the BMOD flag of the control register 2 (R1) to 1 or 0. In addition, the μPD161401 can be directly connected to an i80 or M68 system by making the IFM0 pin high or low as shown in the following table.

IFM0	/CS1, CS2	RS	/RD	/WR	BMOD	D <sub>15</sub> to D <sub>8</sub>	D <sub>7</sub> to D <sub>0</sub>
H: M68 system CPU	/CS1, CS2	RS	E	R,/W	0	D <sub>15</sub> to D <sub>8</sub>	D <sub>7</sub> to D <sub>0</sub>
					1	Hi-Z <sup>Note</sup>	D <sub>7</sub> to D <sub>0</sub>
L: i80 system CPU	/CS1, CS2	RS	/RD	/WR	0	D <sub>15</sub> to D <sub>8</sub>	D <sub>7</sub> to D <sub>0</sub>
					1	Hi-Z <sup>Note</sup>	D <sub>7</sub> to D <sub>0</sub>

**Note** Hi-Z : High impedance (may be open)

The data bus signals are identified by the combination of the RS, /RD(E), /WR (R,/W) signals as shown in the following table.

Common	M68		i80		Common	Data Bus		Function
RS	R <sub>i</sub> /W	E	/RD	/WR	BMOD	D <sub>15</sub> to D <sub>8</sub>	D <sub>7</sub> to D <sub>0</sub>	
1	1	1	0	1	0	Note1	Note1	Reads the register.
					1	Hi-Z	OUT	
1	0	1	1	0	0	Note2	IN	Writes the display data/register.
					1	Hi-Z	IN	
0	1	1	0	1	0	Hi-Z	OUT	Prohibited
					1	Hi-Z	OUT	
0	0	1	1	0	0	Hi-Z	IN	Writes the control index register.
					1	Hi-Z	IN	
0/1	Other					Hi-Z	Hi-Z	—

**Remark** IN : Input status (cannot be open), OUT : Output status, Hi-Z : High impedance (may be open)

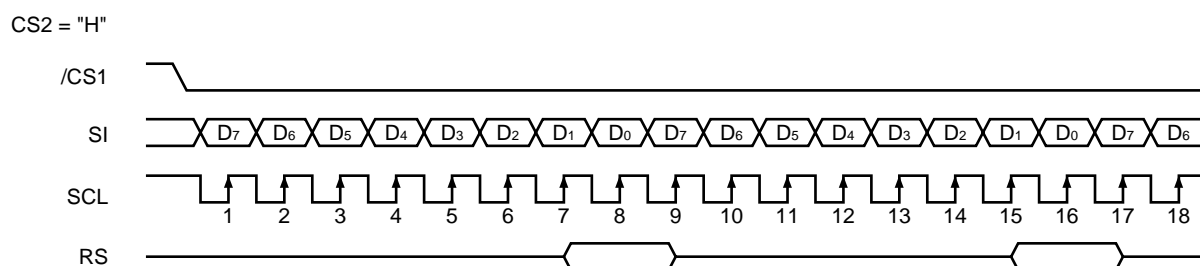
**Notes1.** In the μPD161401, the data of the display access memory register, the complementary color blink data memory register, the specified color blink data memory register and the reverse data memory access register (R12, R41, R45, R50) are read-prohibited. However, if R12 is selected, the data bus signals D<sub>15</sub> to D<sub>0</sub> enter an output state. If another register is specified, the D<sub>15</sub> to D<sub>8</sub> signals become Hi-Z and the D<sub>7</sub> to D<sub>0</sub> signals enter an output state.

- Only the display access memory register (R12) enters the input state. If another register is specified, the D<sub>15</sub> to D<sub>8</sub> signals become Hi-Z.

### 5.1.3 Serial interface

When the serial interface has been selected (IFM1, IFM0 = L, L), as long as the chip is in an active state ( $\text{/CS1} = \text{L}$ ,  $\text{CS2} = \text{H}$ ), serial data input (SI) and serial clock input (SCL) can be received. Serial data is read in the order of  $\text{D}_7$ , then  $\text{D}_6$  to  $\text{D}_0$  at the rising edge of the serial clock input from the serial input pin. This data is converted to parallel data in synchronization with the 8th rising edge of the serial clock. Serial input data is judged as display data/command data if  $\text{RS} = \text{H}$  and an index if  $\text{RS} = \text{L}$ . The RS input is read every 8th rising edge of the serial clock after the chip becomes active and is used for data discrimination.

Figure 5-1. Serial Interface Signal Chart



- Remarks 1.** If the chip is not in an active state, the shift register and counter are reset to their initial statuses.
2. The serial clock counter is reset by initialization from the  $\text{/DISP}$  pin.
  3. Data cannot be read when using serial interface mode.
  4. Care must be taken when performing SCL wiring to avoid effects from terminal radiation or external noise caused by the wiring length. It is recommended to confirm operation using the actual equipment to be used.

### 5.1.4 Chip select

The  $\mu$ PD161401 has chip select pins ( $\text{/CS1}$  and  $\text{CS2}$ ). The CPU parallel interface or Serial interface can be used only when  $\text{/CS1} = \text{L}$  ( $\text{CS2} = \text{H}$ ).

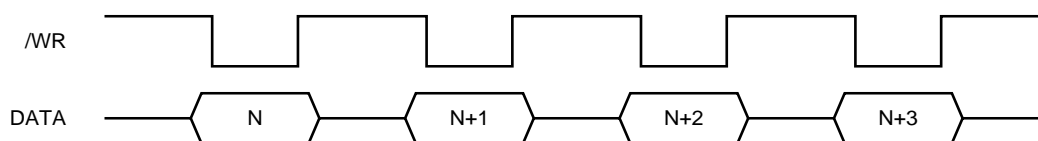
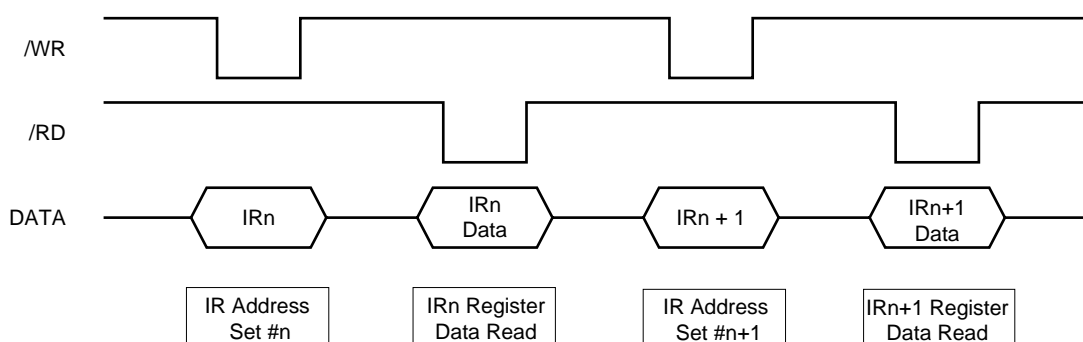
If the chip select pins are not active, the  $\text{D}_0$  to  $\text{D}_{15}$  pins go into a high-impedance state, and the  $\text{RS}$ ,  $\text{/RD}$ , and  $\text{/WR}$  pins do not become active.

### 5.1.5 Accessing display data RAM and internal registers

When the CPU accesses the  $\mu$ PD161401, the CPU only has to satisfy the requirement of the cycle time ( $t_{\text{cyc}}$ ) and can transfer data at high speeds. Usually, it is not necessary for the CPU to take wait time into consideration.

When the CPU writes data to the  $\mu$ PD161401, no dummy data is necessary. When reading data, dummy data is not necessary either. In the  $\mu$ PD161401, the data of the display access memory register, the complementary color blink data memory register, the specified color blink data memory register and the reverse data memory access register ( $\text{R12}$ ,  $\text{R41}$ ,  $\text{R45}$ ,  $\text{R50}$ ) cannot be read. **Figure 5-2** illustrates as follows.

Figure 5–2. Writing and Reading

**Writing****Reading (other than display memory access register)**

**Caution** Display access memory register, the complementary color blink data memory register, the specified color blink data memory register and the reverse data memory access register (R12, R41, R45, R50) cannot be read.

## 5.2 Display Data RAM

### 5.2.1 Display data RAM

This RAM stores dot data for display and consists of  $(101 \times 80) \times 8$  bits. Any address of this RAM can be accessed by specifying an X address and a Y address.

Display data D<sub>0</sub> to D<sub>15</sub> transmitted from the CPU corresponds to the pixels on the LCD (refer to **Table 5–1**). If the μPD161401 is used in a multi-chip configuration, restrictions on display data transfer are relaxed and display setting can be performed relatively freely.

The CPU writes data to the display RAM via I/O buffers. This write operation is performed independently of an operation to read signals for driving the LCD. Therefore, even if the display data RAM is asynchronously accessed, adverse effects such as flickering do not occur on the current LCD screen.

**Table 5–1. Display Data RAM**

MSB								LSB							
D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
Dot (R)			Dot (G)			Dot (B)		Dot (R)			Dot (G)			Dot (B)	
Pixel 1								Pixel 2							

LCD panel

Pixel 1	Pixel 2	Pixel 3	Pixel 4	Pixel 5	Pixel 6	Pixel 7	Pixel 8	
Pixel 1	Pixel 2	Pixel 3	Pixel 4	Pixel 5	Pixel 6	Pixel 7	Pixel 8	
00H	01H	02H	03H	04H	05H	06H	07H	

### 5.2.2 X address circuit

An X address of the display data RAM is specified by using the X address register (R4) as shown in **Figure 5–5**. If the X address increment mode (INC = 0: control register 2 (R1)) is used, the specified X address is incremented or decremented by one each time display data is written. Whether the address is incremented or decremented is specified by the XDIR flag of control register 2 (R1) as shown in **Table 5–2**.

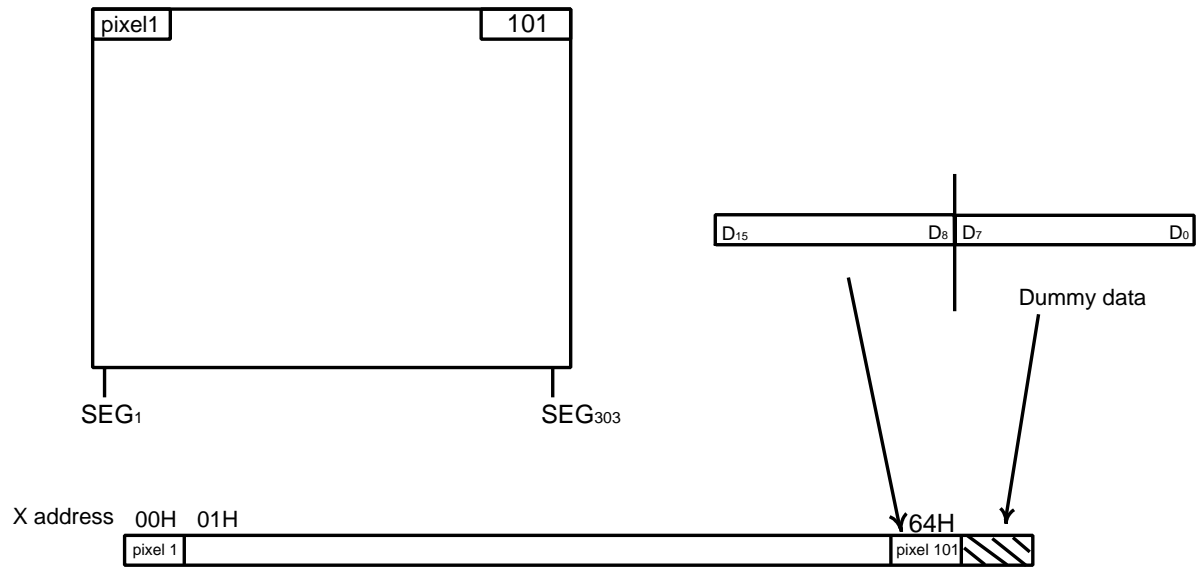
In the increment mode, the X address is incremented up to 64H. If more display data is written, the Y address is incremented (YDIR = 0) or decremented (YDIR = 1), and the X address returns to 00H.

In the decrement mode, the X address is decremented to 00H. If more display data is written, the Y address is incremented (YDIR = 0) or decremented (YDIR = 1), and the X address returns to 64H.

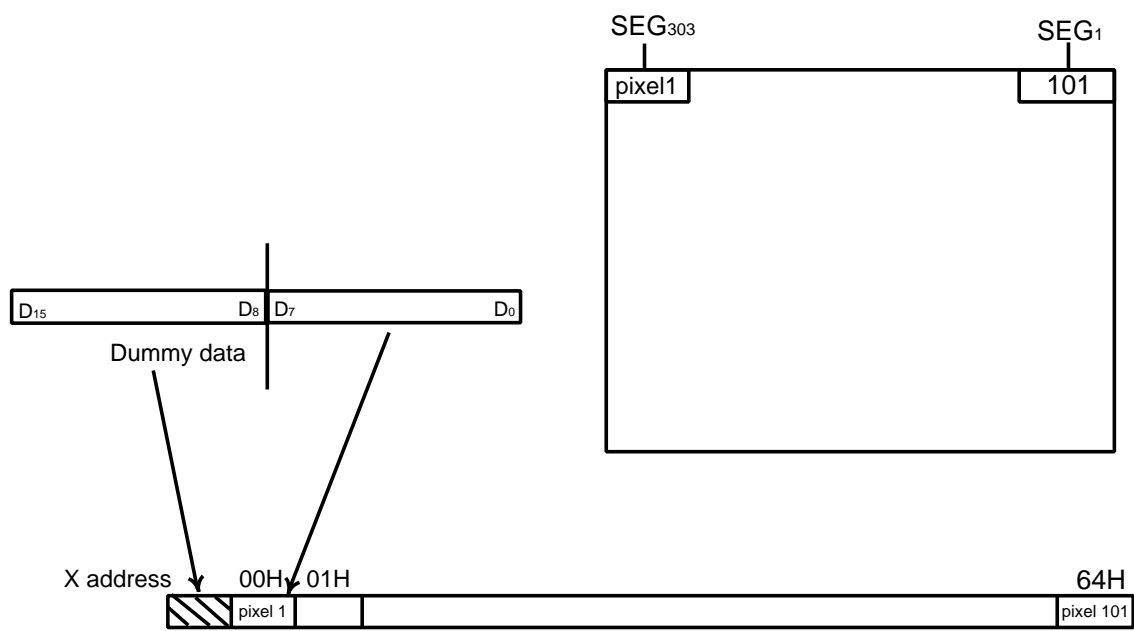
When the 16-bit data bus is selected (BMOD = 0), only an even address can be specified. Moreover, when the 16-bit data bus is selected, dummy data is required as shown in **Figure 5–3**.

Figure 5-3. About Dummy Data Required when the 16-bit Data Bus is Selected

• When an ADC = 0



• When an ADC = 1



### 5.2.3 Y address circuit

A Y address of the display data RAM is specified by using the Y address register (R5) as shown in **Figure 5–5**. If the Y address increment mode (INC = 1: control register 2 (R1)) is used, the specified Y address is incremented or decremented by one each time display is written. Whether the address is incremented or decremented is specified by the YDIR flag of control register 2 (R1) as shown in **Table 5–2**.

In the increment mode, the Y address is incremented up to 4FH. If more display data is written, the X address is incremented (XDIR = 0) or decremented (XDIR = 1), and the Y address returns to 00H.

In the decrement mode, the Y address is decremented to 00H. If more display data is written, the X address is incremented (XDIR = 0) or decremented (XDIR = 1), and the Y address returns to 4FH.

The relationship between the setting of INC, XDIR, and YDIR of control register 2 (R1) and the address is as follows:

**Table 5–2. Relationship between INC, XDIR, and YDIR, and Address**

INC	Setting
0	The address is successively incremented or decremented in the X direction when data is accessed.
1	The address is successively incremented or decremented in the Y direction when data is accessed <sup>Note</sup> .

**Note** This setting cannot be used when the 16-bit parallel interface is used.

XDIR	Setting
0	Increments the X address (+1) when data is accessed.
1	Decrements the X address (–1) when data is accessed.

YDIR	Setting
0	Increments the Y address (+1) when data is accessed.
1	Decrements the Y address (–1) when data is accessed.

**Table 5–3. Combination of INC, XDIR, and YDIR, and Address Direction**

INC	XDIR	YDIR	Image of Address Scanning
0	0	0	A-1
	0	1	A-2
	1	0	A-3
	1	1	A-4
1	0	0	B-1
	0	1	B-2
	1	0	B-3
	1	1	B-4

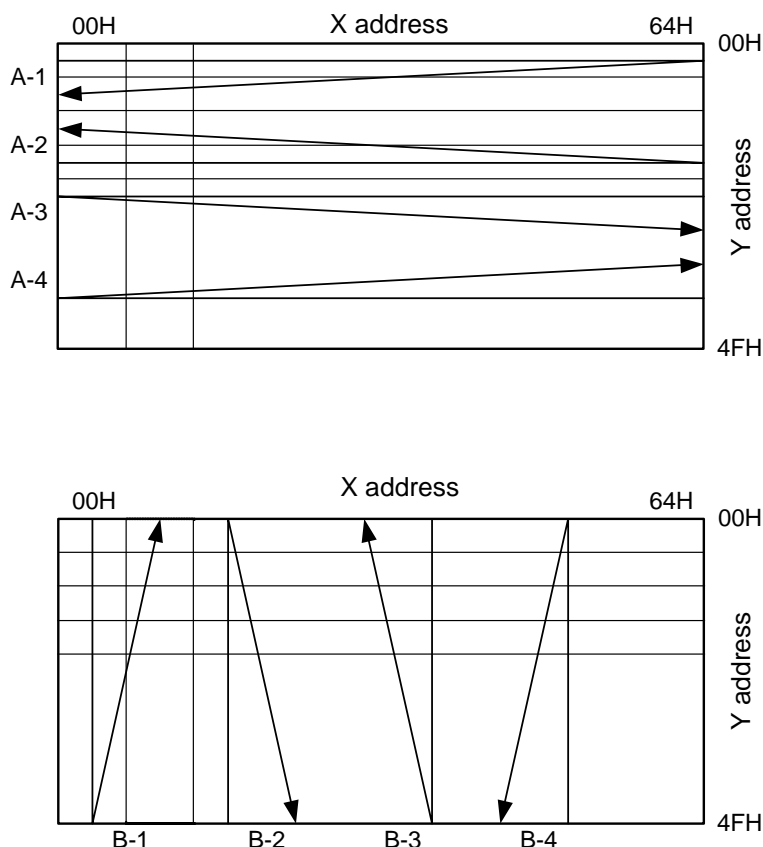
**Caution** If the access direction is changed by using INC, XDIR, or YDIR, be sure to set the X address register (R4) and Y address register (R5) before accessing the display RAM.

### Y address register (R5)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
	YA6	YA5	YA4	YA3	YA2	YA1	YA0

YA6 to YA0	Sets a line address.
------------	----------------------

Figure 5-4. Combination of INC, XDIR, and YDIR, and Address Scanning Image



### 5.2.4 Column address circuit

When the contents of the display data RAM are displayed, column addresses are output to the SEG output pins as shown in **Figure 5-5**.

The correspondence relationship between the column addresses of the display RAM and segment outputs can be reversed by the ADC flag (segment driver direction select flag) of control register 1 (R0). This reduces the restrictions on chip layout when the LCD module is assembled.

Table 5-4. Relationship between Column Address of Display RAM and Segment Output

SEG Output		SEG <sub>1</sub>		SEG <sub>303</sub>
ADC (D <sub>1</sub> )	0	000H	→ Column address →	12EH
	1	12EH	← Column address ←	000H



### 5.2.5 Common scan circuit

The common scan circuit sets the sequence for the scan line of the common signal in which the display RAM is to be read. The RAM line reading direction is set as shown in **Table 5–5** by the COMR flag of control register 1 (R0).

For example, if the duty ratio is 1/64, the number of scroll steps is 0, and COMR = 0, the RAM line reading direction is from 00H to 3FH. If COMR = 1, it is from 3FH to 00H.

**Table 5–5. Relationship between Common Scan Circuit and Scan Direction**

COMR	0	00H	→	4FH
(D <sub>0</sub> )	1	4FH	→	00H

In addition, scanning of the common outputs can be assigned by using the COM scanning address setting register (R21) as shown in **Table 5–6**, so that the scanning can be started from any O<sub>1</sub> to O<sub>80</sub> output pin. Therefore, the common wiring of the LCD panel can be optimized when any duty ratio is selected.

When COMR = 0, the scan start (COM<sub>1</sub>) pin and scan end (COM<sub>a</sub>) pin are the O<sub>n</sub> and O<sub>(n+a-1)</sub> pins, respectively. The value of a is 64, 72, and 80 for 1/64 duty, 1/72 duty, and 1/80 duty, respectively. When COMR = 1, the scan start (COM<sub>1</sub>) pin and scan end (COM<sub>a</sub>) pin are the O<sub>(82-a-n)</sub> and O<sub>(80-n+1)</sub> pins, respectively.

Examples of COM scan address settings for 1/64 duty, 1/72 duty, and 1/80 duty are shown in **Tables 5–5, 5–7, and 5–8**, respectively.

**Table 5–6. COM Scanning Address Setting (1/64 duty)**

CSA4	CSA3	CSA2	CSA1	CSA0	n	COMR = 0			COMR = 1		
						the scan start (COM <sub>1</sub> ) pin	→	the scan end (COM <sub>a</sub> ) <sup>Note</sup> pin	the scan start (COM <sub>1</sub> ) pin	→	the scan end (COM <sub>a</sub> ) <sup>Note</sup> pin
						O <sub>n</sub>	→	O <sub>(n+a-1)</sub> <sup>Note</sup>	O <sub>(82-a-n)</sub> <sup>Note</sup>	→	O <sub>(80-n+1)</sub>
0	0	0	0	0	1	O <sub>1</sub>	→	O <sub>64</sub>	O <sub>17</sub>	→	O <sub>80</sub>
0	0	0	0	1	2	O <sub>2</sub>	→	O <sub>65</sub>	O <sub>16</sub>	→	O <sub>79</sub>
0	0	0	1	0	3	O <sub>3</sub>	→	O <sub>66</sub>	O <sub>15</sub>	→	O <sub>78</sub>
0	0	0	1	1	4	O <sub>4</sub>	→	O <sub>67</sub>	O <sub>14</sub>	→	O <sub>77</sub>
0	0	1	0	0	5	O <sub>5</sub>	→	O <sub>68</sub>	O <sub>13</sub>	→	O <sub>76</sub>
0	0	1	0	1	6	O <sub>6</sub>	→	O <sub>69</sub>	O <sub>12</sub>	→	O <sub>75</sub>
0	0	1	1	0	7	O <sub>7</sub>	→	O <sub>70</sub>	O <sub>11</sub>	→	O <sub>74</sub>
0	0	1	1	1	8	O <sub>8</sub>	→	O <sub>71</sub>	O <sub>10</sub>	→	O <sub>73</sub>
0	1	0	0	0	9	O <sub>9</sub>	→	O <sub>72</sub>	O <sub>9</sub>	→	O <sub>72</sub>
0	1	0	0	1	10	O <sub>10</sub>	→	O <sub>73</sub>	O <sub>8</sub>	→	O <sub>71</sub>
0	1	0	1	0	11	O <sub>11</sub>	→	O <sub>74</sub>	O <sub>7</sub>	→	O <sub>70</sub>
0	1	0	1	1	12	O <sub>12</sub>	→	O <sub>75</sub>	O <sub>6</sub>	→	O <sub>69</sub>
0	1	1	0	0	13	O <sub>13</sub>	→	O <sub>76</sub>	O <sub>5</sub>	→	O <sub>68</sub>
0	1	1	0	1	14	O <sub>14</sub>	→	O <sub>77</sub>	O <sub>4</sub>	→	O <sub>67</sub>
0	1	1	1	0	15	O <sub>15</sub>	→	O <sub>78</sub>	O <sub>3</sub>	→	O <sub>66</sub>
0	1	1	1	1	16	O <sub>16</sub>	→	O <sub>79</sub>	O <sub>2</sub>	→	O <sub>65</sub>
1	0	0	0	0	17	O <sub>17</sub>	→	O <sub>80</sub>	O <sub>1</sub>	→	O <sub>64</sub>

**Note** When in 1/64 duty, a = 64.

Table 5-7. COM Scanning Address Setting (1/72 duty)

CSA4	CSA3	CSA2	CSA1	CSA0	n	COMR = 0		COMR = 1		Remark
						the scan start (COM <sub>1</sub> ) pin	→ the scan end (COM <sub>a</sub> ) <sup>Note</sup> pin	the scan start (COM <sub>1</sub> ) pin	→ the scan end (COM <sub>a</sub> ) <sup>Note</sup> pin	
						O <sub>n</sub>	→ O <sub>(n+a-1)</sub> <sup>Note</sup>	O <sub>(82-a-n)</sub> <sup>Note</sup>	→ O <sub>(80-n+1)</sub>	
0	0	0	0	0	1	O <sub>1</sub>	→ O <sub>72</sub>	O <sub>9</sub>	→ O <sub>80</sub>	Prohibit since here
0	0	0	0	1	2	O <sub>2</sub>	→ O <sub>73</sub>	O <sub>8</sub>	→ O <sub>79</sub>	
0	0	0	1	0	3	O <sub>3</sub>	→ O <sub>74</sub>	O <sub>7</sub>	→ O <sub>78</sub>	
0	0	0	1	1	4	O <sub>4</sub>	→ O <sub>75</sub>	O <sub>6</sub>	→ O <sub>77</sub>	
0	0	1	0	0	5	O <sub>5</sub>	→ O <sub>76</sub>	O <sub>5</sub>	→ O <sub>76</sub>	
0	0	1	0	1	6	O <sub>6</sub>	→ O <sub>77</sub>	O <sub>4</sub>	→ O <sub>75</sub>	
0	0	1	1	0	7	O <sub>7</sub>	→ O <sub>78</sub>	O <sub>3</sub>	→ O <sub>74</sub>	
0	0	1	1	1	8	O <sub>8</sub>	→ O <sub>79</sub>	O <sub>2</sub>	→ O <sub>73</sub>	
0	1	0	0	0	9	O <sub>9</sub>	→ O <sub>80</sub>	O <sub>1</sub>	→ O <sub>72</sub>	
0	1	0	0	1	10					

**Note** When in 1/72 duty, a = 72

**Caution** The COM scan address setting register (R21) should be set so that  $O_1 \leq \text{scan start pin}$  and  $\text{scan end pin} \leq O_{80}$ . If any other settings are made the IC operation is not guaranteed.

Table 5-8. COM Scanning Address Setting (1/80 duty)

CSA4	CSA3	CSA2	CSA1	CSA0	n	COMR = 0		COMR = 1		Remark
						the scan start (COM <sub>1</sub> ) pin	→ the scan end (COM <sub>a</sub> ) <sup>Note</sup> pin	the scan start (COM <sub>1</sub> ) pin	→ the scan end (COM <sub>a</sub> ) <sup>Note</sup> pin	
						O <sub>n</sub>	→ O <sub>(n+a-1)</sub> <sup>Note</sup>	O <sub>(82-a-n)</sub> <sup>Note</sup>	→ O <sub>(80-n+1)</sub>	
0	0	0	0	0	1	O <sub>1</sub>	→ O <sub>80</sub>	O <sub>1</sub>	→ O <sub>80</sub>	Prohibit since here
0	0	0	0	1	2					

**Note** When in 1/80 duty, a = 80

**Caution** When this μPD161401 is used in 1/80 duty, the COM scan address setting register (R21) should be set to CSA4, CSA3, CSA2, CSA1, CSA0 = 0, 0, 0, 0, 0. If any other settings are made the IC operation is not guaranteed.

### Figure 5–5. Configuration of X Address Register

[illegible]

### 5.2.6 Display data latch circuit

The display data latch circuit temporarily stores (latches) the display data that is output from the display data RAM to the LCD driver circuit.

The display scan command for forwarding or reversing data and the display ON/OFF command control the latched data and do not affect the data of the display data RAM.

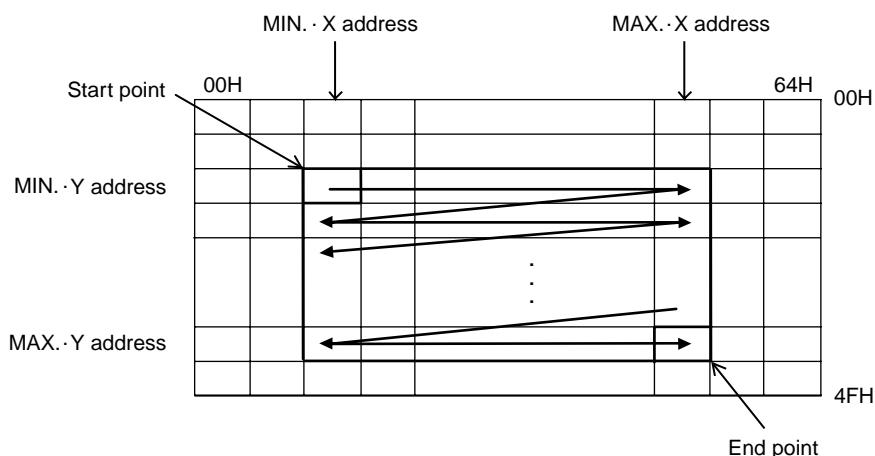
### 5.2.7 Arbitrary address area access (window access mode (WAS))

With the μPD161401, any area of the display RAM selected by the MIN.·X/Y address registers (R7 and R9) and MAX.·X/Y address registers (R8 and R10) can be accessed.

First, select the area to be accessed by using the MIN.·X/Y address registers and MAX.·X/Y address registers. When WAS of control register 1 is set to 1, the window access mode is then selected. The address scanning setting by INC, XDIR, and YDIR of control register 2 (R1) is also valid in this mode, in the same manner as when data is normally written to the display RAM. In addition, data can be written from any address by specifying the X address register (R4) and Y address register (R5).

Note that the display RAM must be accessed after setting the X address register (R6) and Y address register (R7) if the window access area has been set or changed by the MIN.·X/Y address register (R7, R9) or MAX.·X/Y address register (R8, R10).

Figure 5–6. Example of Incrementing Address When INC = 0, XDIR = 0, and YDIR = 0

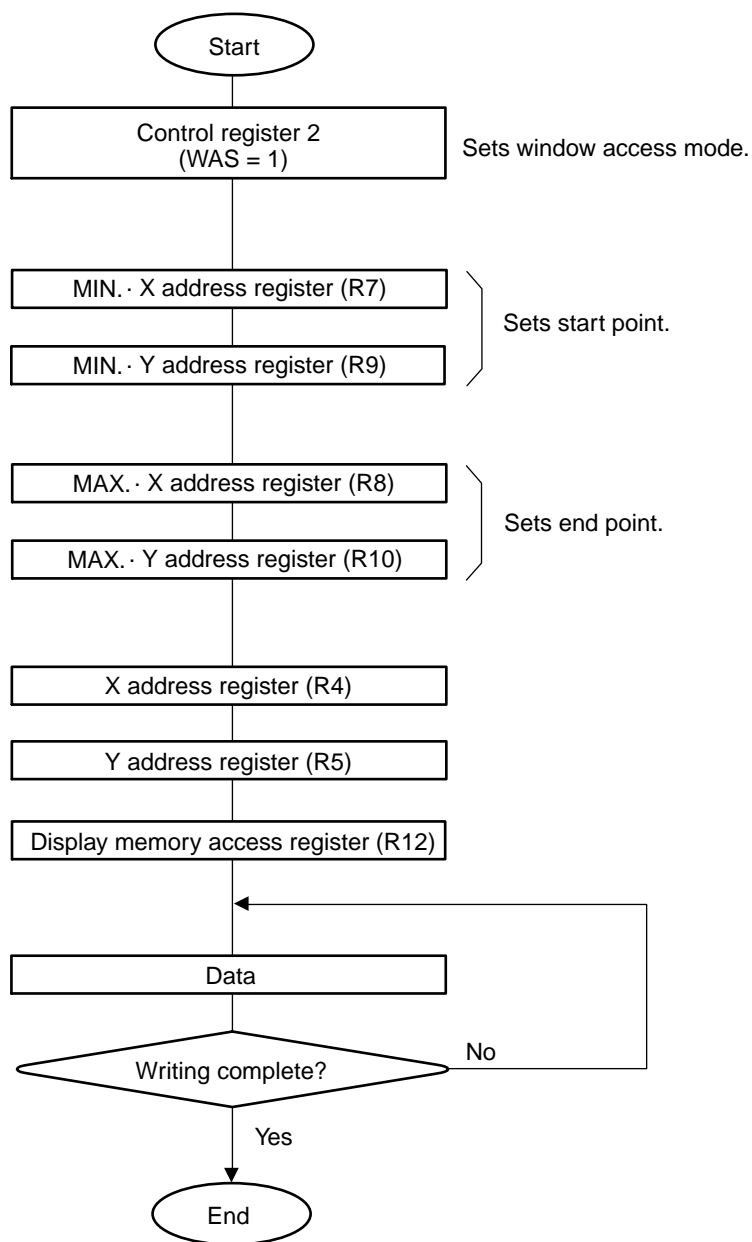


**Cautions 1.** When using the window access mode, the relationship between the start point and end point shown in the table below must be established.

Item	Address Relation Ship
X address	$00H \leq \text{MIN.·X address} \leq \text{X address (R4)} \leq \text{MAX.·X address} \leq 64H$
Y address	$00H \leq \text{MIN.·Y address} \leq \text{Y address (R5)} \leq \text{MAX.·Y address} \leq 4FH$

- If invalid address data is set as the MIN./MAX.·address, operation is not guaranteed.
- Access the display RAM after setting the X address register (R6) and Y address register (R7) if the window access area has been set or changed by the MIN.·X/Y address register (R7, R9) or MAX.·X/Y address register (R8, R10).

Figure 5-7. Example of Sequence in Window Access Mode



## 5.3 Screen Processing

### 5.3.1 Blink/reverse display circuit

The μPD161401 can blink or reverse a specific area of the full-dot display. Blinking is to turn ON/OFF display repeatedly at about 1 Hz (complementary color or specified color can be selected) and reversing is to reverse the grayscale data on the display.

The area to be blinked is specified by using the complementary color/specified color blink start/end line address registers (R39, R40, R43, and R44), complementary color/specified color blink X address registers (R38, R42), and complementary color/specified color blink data memory registers (R41, R45).

First, select a blink display start line address and end line address by using the start/end line address registers. Next, select the column to be blinked by using the blink X address register and blink data memory register.

The specified color blink is blinked between the graphic data and the color data specified by the specified color setting register (R46).

To select an area to be reversed, use the reverse start/end line address registers (R48, R49), reverse X address register (R47), and reverse data memory access register (R50).

First, select line addresses at which reverse display is started and stopped, by using the reverse start/end line address registers. Next, select a column to be reversed, by using the reverse X address register and reverse data memory access register. The specified blink/reverse X address is incremented by one each time blink/reverse data has been input.

The complementary color/specified color blink RAM and reverse RAM store the data to be blinked and reversed. Each RAM is configured of 101 bits (12 × 8 + 5 bits).

To access a desired bit, specify an X address. Blink/reverse data D<sub>0</sub> to D<sub>7</sub> transmitted from the CPU corresponds to SEG<sub>x</sub> on the LCD, as illustrated in **Figure 5–8**.

If the BLD bit and INV bit of the blink/reverse setting register (R37) are set to H after an area and data have been set, blinking or reversing the data is started. **Figure 5–9** shows the relationship between the start line address, end line address, blinking/reversing data, and LCD.

If the same area is specified for complementary color blinking and specified color blinking, the specified color blinking takes precedence.

**Table 5–9. Reversing Operation and Display**

Original Grayscale	After Reversing (supplement color)
R/G display data	
0, 0, 0	1, 1, 1
0, 0, 1	1, 1, 0
0, 1, 0	1, 0, 1
0, 1, 1	1, 0, 0
1, 0, 0	0, 1, 1
1, 0, 1	0, 1, 0
1, 1, 0	0, 0, 1
1, 1, 1	0, 0, 0
B display data	
0, 0	1, 1
0, 1	1, 0
1, 0	0, 1
1, 1	0, 0

Figure 5–8. Correspondence between Blink/Reverse Data and Segment

When an ADC = 0

R38,R42,R47 X address	D <sub>3</sub>	0								0																1								
	D <sub>2</sub>	0								0																1								
	D <sub>1</sub>	0								0																0								
	D <sub>0</sub>	0								1																0								
		00H								01H																0CH								
Data	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>									D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>		
																																Note	Note	Note

00	01	02	03	04	05	06	07	08	09	0A	0B	0C	0D	0E	0F				60	61	62	63	64
pixel1	pixel2	pixel3	pixel4	pixel5	pixel6	pixel7	pixel8	pixel9	pixel10	pixel11	pixel12	pixel13	pixel14	pixel15	pixel16				pixel17	pixel18	pixel19	pixel100	pixel101

Column output  
LCD  
Output

**Note** The value written in D<sub>2</sub> to D<sub>0</sub> of X address 0CH is invalid.

When an ADC = 1

R38,R42,R47 X address	D <sub>3</sub>	0							0							1								
	D <sub>2</sub>	0							0							1								
	D <sub>1</sub>	0							0							0								
	D <sub>0</sub>	0							1							0								
		00H							01H							0CH								
Data	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>

00	01	02	03	04	05	06	07	08	09	0A	0B	0C	0D	0E	0F		60	61	62	63	64
pixel1	pixel2	pixel3	pixel4	pixel5	pixel6	pixel7	pixel8	pixel9	pixel10	pixel11	pixel12	pixel13	pixel14	pixel15	pixel16		pixel17	pixel18	pixel19	pixel100	pixel101

Column output  
LCD  
Output

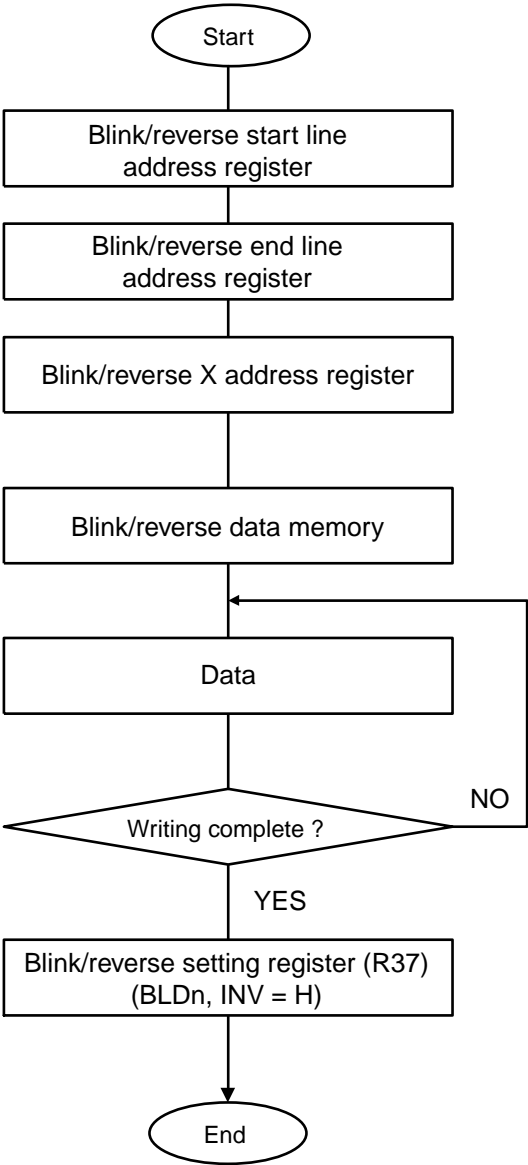
**Note** The value written in D<sub>7</sub> to D<sub>5</sub> of X address 00H is invalid.

Figure 5–9. Blink/Reverse Display Area Setting Image

	n	n+1	n+2	n+3	n+4	n+5	n+6	n+7
Blink/reverse data	001110010	0011001110	001010100	001001110	000101010	001110010	001110010	000101010
Start line								
End line								

/// : Blink or reverse pixel

Figure 5-10. Example of Sequence of Setting Blink/Reverse Display



The data configuration of the range specification registers (start/end line address registers R39, R40, R43, R44, R48, and R49) of each line is in the format shown below. Each display area is set in this format. .

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
	X <sub>6</sub>	X <sub>5</sub>	X <sub>4</sub>	X <sub>3</sub>	X <sub>2</sub>	X <sub>1</sub>	X <sub>0</sub>

X <sub>6</sub> to X <sub>0</sub>	Sets start/end line addresses.
----------------------------------	--------------------------------

**Remark** X<sub>7</sub>: CBS, CBE, SBS, SBE, IVS, IVE



### 5.3.2 Example of setting blink area

This section explains how to specify an area to be blinked, taking complementary color blinking as an example. The same setting is also applied to specified color blinking and reverse display.

#### (1) Example of using 1 chip at duty ratio of 1/80

T.B.D.

**Remark** T.B.D. (To be determined.)

#### (2) Example of using 2 chip (Master and slave) at duty ratio of 1/80

T.B.D.

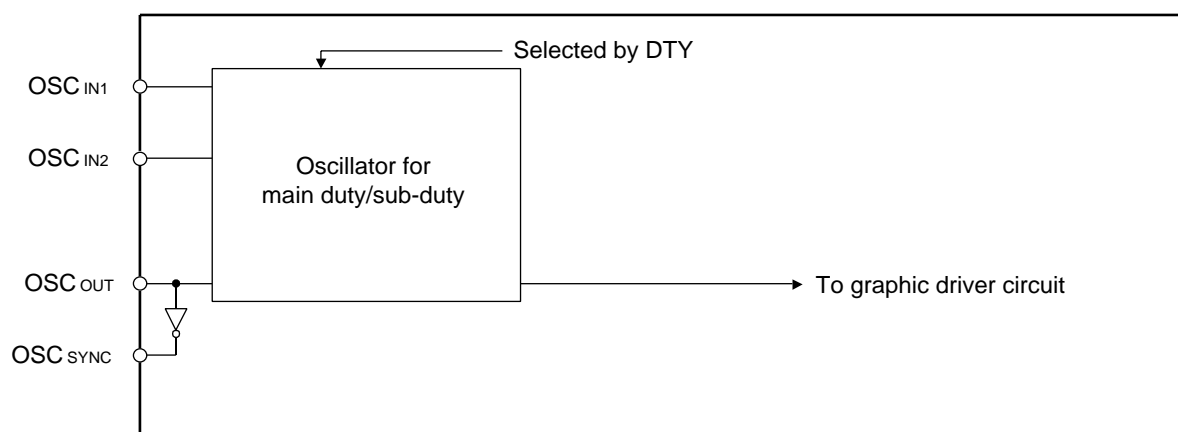
## 5.4 Oscillator

The μPD161401 has a CR oscillator (with external R) for main duty/sub-duty display. This oscillator generates the display clock.

This oscillator is controlled by the DTY flag of control register 2 (R1), and the configuration of its display clock can be set in accordance with the system used.

The function of each circuit of the oscillator is shown below. The main duty display/sub-duty display oscillator becomes valid only when oscillation resistors (RM and RS) are connected to it. The clock for main duty display or sub-duty display can be selected depending on the status of the DTY flag of control register 2 (R1).

**Figure 5-11. Oscillator Block**



The relationship between the frame frequency ( $f_{\text{FRAME}}$ ) in the normal display mode, oscillation frequency ( $f_{\text{OSCINn}}$ ), and set duty frame is as follows.

$$f_{\text{FRAME}} = f_{\text{OSCINn}} \div 16 \div N$$

$N$  = Duty ratio

Table 5–10 shows the relationship between oscillation resistors RM and RS, and the display clock circuit.

Table 5–10. Relationship between Display Clock Circuit, Pins, and Resistor

RM Connection	RS Connection	Clock for Main Duty Display	Clock for Sub-duty Display	Example
Connected	Connected	Internal oscillation	Internal oscillation	A
Not connected	Not connected	External clock	External clock	B

Figure 5–12. Example of Using Clock

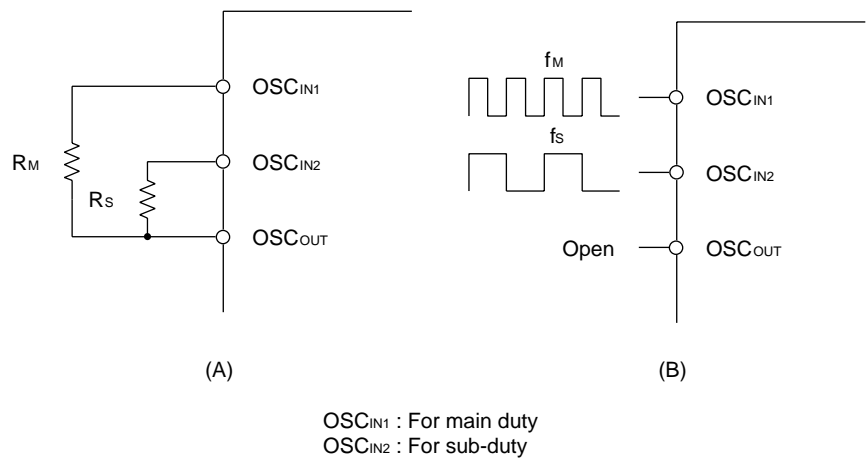
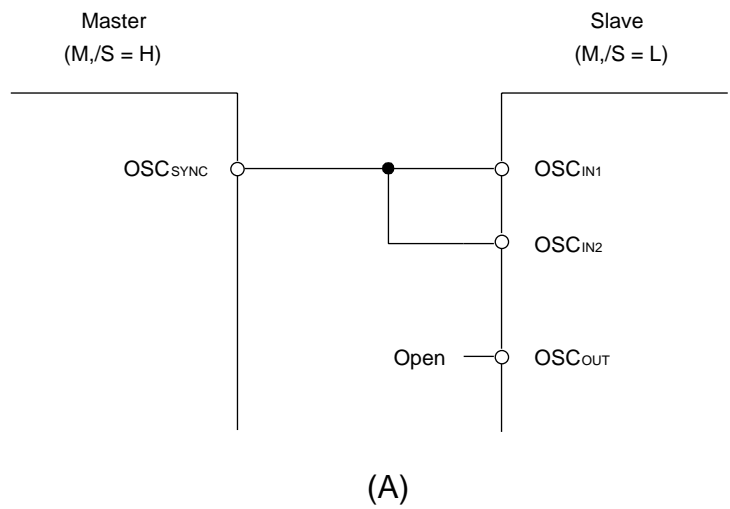


Figure 5–13. Example of Master/Slave Connection



### 5.5 Display Timing Generator

The display timing generator generates timing signals for the line address circuit and display data latch circuit, from the display clock. The display data is latched to the display data latch circuit in synchronization with the display clock and output to the segment driver output pins. The display data can be read completely independently of the access to the display data RAM by the CPU. Therefore, even if the display data RAM is asynchronously accessed, no adverse effect, such as flickering, occurs on the LCD.

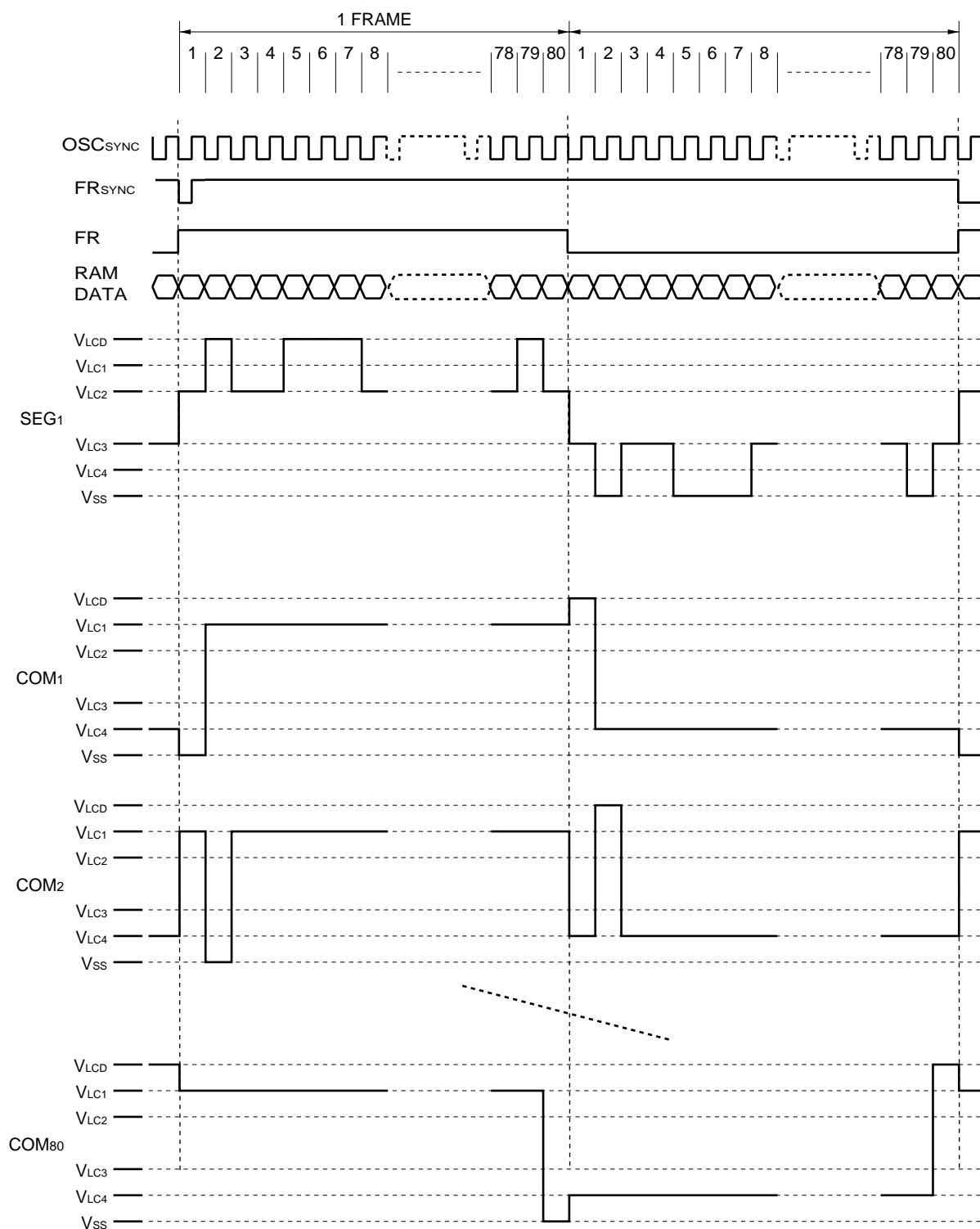
The internal common timing, LCD AC signal (FR), and frame synchronization signal (FR<sub>SYNC</sub>) are generated by the display clock. A driver waveform in the frame AC driving mode shown in **Figure 5-14** is generated for the LCD driver circuit.

When the  $\mu$ PD161401 is used in a multi-chip configuration, the display timing signals for the slave chip (FR and FR<sub>SYNC</sub>) must be supplied from the master chip.

**Table 5-11. Relationship between FR, FR<sub>SYNC</sub>, and Operation Mode**

Operation Mode	FR	FR <sub>SYNC</sub>
Master (M,/S = H)	Output	Output
Slave (M,/S = L)	Input	Input

Figure 5-14. Driver Waveform in Frame AC Driver Mode



## 5.6 Power Supply Circuit

### 5.6.1 Power supply circuit

The power supply circuit generates the voltage necessary for driving the LCD. The power circuit consists of a booster circuit, voltage regulator circuit, and voltage follower circuit.

Power system control register 1 (R52) turns ON/OFF the transformer, reference voltage generator, voltage regulator circuit (V regulator circuit), and voltage follower circuit (V/F circuit). Part of the internal power supply function and an external power supply can be used in combination. **Table 5–12** shows the functions controlled by the 4-bit data of power system control register 1 (R52). **Table 5–13** shows examples of combinations of the power circuit functions.

**Table 5–12. Function of Each Bit of Power System Control Register**

Item	Status	
	1	0
OP3 : Booster circuit control bit	ON	OFF
OP2 : Reference voltage generator control bit	ON	OFF
OP1 : Voltage regulator circuit (V regulator circuit) control bit	ON	OFF
OP0 : Voltage follower circuit (V/F circuit) control bit	ON	OFF

**Table 5–13. Examples of Combinations (Reference Values)**

Status	OP3	OP2	OP1	OP0	Booster Circuit	Reference voltage	V Regulator Circuit	V/F Circuit	External Power Input	Booster System Pins
<1> Only internal power supply is used	1	1	1	1	O	O	O	O	V <sub>DD2</sub>	Used
<2> External V <sub>OUT</sub> power supply	0	1	1	1	×	O	O	O	V <sub>DD2</sub> , V <sub>OUT</sub>	Open
<3> Only V/F circuit is used	1	0	0	1	O	×	×	O	V <sub>DD2</sub> , AMP <sub>OUT</sub>	Used
<4> Only external power supply is used	0	0	0	0	×	×	×	×	V <sub>DD2</sub> , V <sub>OUT</sub> , V <sub>LCD</sub> , V <sub>LC1</sub> to V <sub>LC4</sub>	Open

**Remarks 1.** The “booster system pins” are the C<sub>1</sub><sup>+</sup>, C<sub>1</sub><sup>–</sup> to C<sub>5</sub><sup>+</sup>, C<sub>5</sub><sup>–</sup> pins.

**2.** All the power circuits are turned OFF when the μPD161401 serves as a slave (M,/S pin = L).

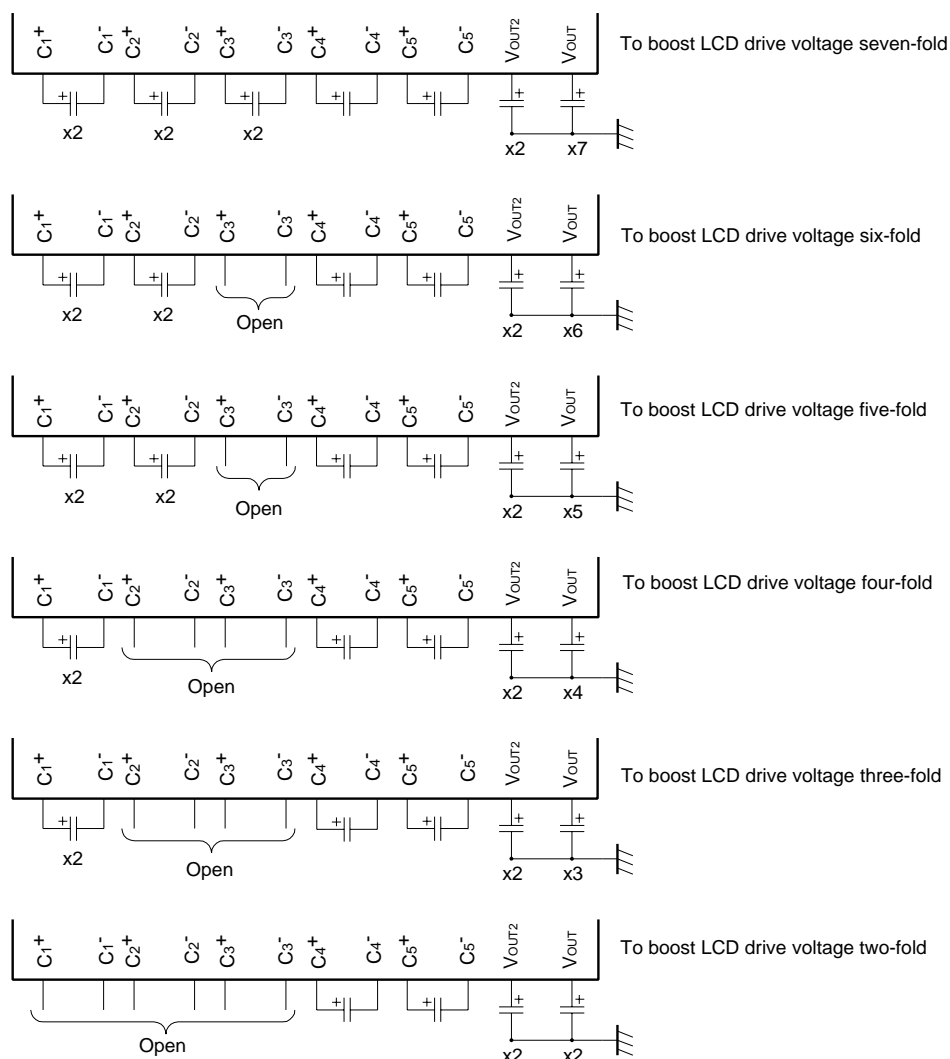
### 5.6.2 Booster circuit

The power supply circuit has an internal booster circuit that increases the LCD driver voltage two- to seven-fold. Because this booster circuit uses the internal oscillator signals, either the oscillator must be operating or an external display clock must be input to operate this circuit.

The booster circuit usually uses the C<sub>1</sub><sup>+</sup>, C<sub>1</sub><sup>–</sup> to C<sub>5</sub><sup>+</sup>, C<sub>5</sub><sup>–</sup> pins and V<sub>DD2</sub> pins. Keep the wiring impedance of these pins as low as possible. The number of boosting steps for main duty display and sub-duty display is set as shown in **Table 5–14** by the MBT<sub>n</sub> and SBT<sub>n</sub> flags of power system control register 4 (R55).

For the number of boosting steps and how to connect capacitors, refer to **Figure 5–15**.

Figure 5–15. Number of Boosting Steps and Capacitor Connection



**Remark** “xN” (N = 2 to 7) of the capacitors in the above figure indicates the maximum voltage applied to the capacitors.

$$xN : V_{DD2} \times N \text{ (V)}$$

Table 5–14. Number of Boosting Steps of Main Duty/Sub-duty Display Booster Circuit (during Normal Display)

MBT2	MBT1	MBT0	Number of Boosting steps (unit: fold)
SBT2	SBT1	SBT0	
0	0	0	Two
0	0	1	Three
0	1	0	Four
0	1	1	Five
1	0	0	Six
1	0	1	Seven
1	1	0	Prohibited
1	1	1	Prohibited

### 5.6.3 Voltage regulator circuit

The boosted voltage from  $V_{OUT}$  is supplied to the voltage regulator circuit and output to the LCD drive voltage pin  $V_{LCD}$ . Because the μPD161401 has a 128-step electronic volume function and an internal  $V_{LCD}$  adjuster resistor, a high-accuracy voltage regulator circuit can be configured by adding only a few components.

#### $V_{LCD}$ regulator circuit

##### (a) When internal resistor for adjusting $V_{LCD}$ is used

By using the internal resistor for adjusting  $V_{LCD}$  and the electronic control function, LCD drive voltage  $V_{LCD}$  can be controlled and the contrast of the LCD can be adjusted by using commands. In this case, no external resistor is necessary. Where  $V_{LCD} < V_{OUT}$ , the value of  $V_{LCD}$  can be calculated as follows:

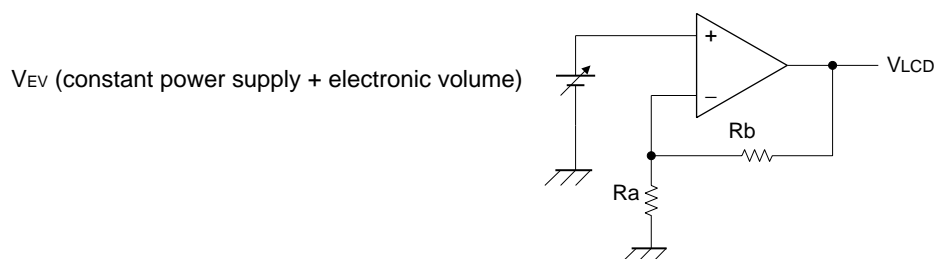
**Example** Calculating value of  $V_{LCD}$  (where  $V_{LCD} < V_{OUT}$ )

$$V_{LCD} = \left(1 + \frac{R_b}{R_a}\right) V_{EV}$$

$$V_{LCD} = \left(1 + \frac{R_b}{R_a}\right) \left(1 - \frac{\alpha}{256}\right) V_{REG}$$

**Remark**  $V_{EV} = \left(1 - \frac{\alpha}{256}\right) V_{REG}$

Figure 5–16. Example of Circuit Using Internal Resistor for Adjustment  $V_{LCD}$



$V_{REG}$  is the internal fixed power source of the IC and has three types of temperature characteristic curves. These temperature characteristic curves can be adjusted as shown in **Table 5–15** depending on the setting of power system control register 1 (R52) (TCS2 to TCS0).

**Table 5–15** shows  $V_{REG}$  at  $T_A = 25^\circ\text{C}$ .

Table 5–15. Adjusting Temperature Characteristic Curve

Status	TCS2	TCS1	TCS0	Temperature Gradient (unit: %/°C)	$V_{REG}$ (TYP.) (unit: V)
Internal power supply	0	0	0	–0.12	1.77
	0	0	1	–0.13	1.69
	0	1	0	–0.15	1.63
	0	1	1	–0.17	1.59
When external reference power supply is used	1	×	×	–	–

$\alpha$  is the value of the electronic volume register. It can take any of 128 values in accordance with the data set to the 7-bit electronic control register. The value of  $\alpha$  set by the main electronic volume register (R57) (main duty display) and sub-electronic volume register (R58) (sub-duty display) is shown in **Table 5–16**.

**Table 5–16. Changes in Value of  $\alpha$  Depending on Setting of Electronic Volume Register**

MEV6	MEV5	MEV4	MEV3	MEV2	MEV1	MEV0	$\alpha$
SEV6	SEV5	SEV4	SEV3	SEV2	SEV1	SEV0	
0	0	0	0	0	0	0	256
0	0	0	0	0	0	1	126
0	0	0	0	0	1	0	125
0	0	0	0	0	1	1	124
			⋮				⋮
1	1	1	1	1	0	1	2
1	1	1	1	1	1	0	1
1	1	1	1	1	1	1	0

Rb/Ra is a ratio of the internal resistors for adjusting  $V_{LCD}$ . This resistance ratio can be adjusted in 128 steps, by using power control register 2 (R53) (VRRn: main duty display mode, and SVRn: sub-duty display mode). The value of the reference voltage ( $1 + Rb/Ra$ ) is determined as shown in **Table 5–17**, depending on the setting of 4 bits of the  $V_{LCD}$  internal resistance ratio register.

**Table 5–17. Determining Reference Voltage Value by Setting of Internal Resistance Ratio Register**

Register				$1 + Rb/Ra$
VRR3	VRR2	VRR1	VRR0	
SVR3	SVR2	SVR1	SVR0	
0	0	0	0	3
0	0	0	1	4
0	0	1	0	5
0	0	1	1	6
0	1	0	0	7
0	1	0	1	8
0	1	1	0	9
0	1	1	1	10
1	0	0	0	11
1	0	0	1	12
1	0	1	0	13
1	0	1	1	14
1	1	0	0	15
1	1	0	1	16
1	1	1	0	17
1	1	1	1	18



**(b) When external resistor is used (when internal resistor for adjusting  $V_{LCD}$  is not used)**

LCD drive voltage  $V_{LCD}$  can be controlled not only by a setting of the internal resistor for adjusting  $V_{LCD}$  ( $IRS = L$ ) but also by connecting resistors  $R_{ae}$ ,  $R_{be}$ , and  $R_{ce}$  between  $V_{SS}$  and  $V_R$ , between  $V_R$  and  $AMP_{OUTM}$ , and between  $V_R$  and  $AMP_{OUTS}$ , respectively. In this case also, LCD drive voltage  $V_{LCD}$  and the contrast of the LCD can be adjusted by using the electronic control function and commands.

In addition, the μPD161401 can select two values of  $V_{LCD}$  for normal display and partial display. These values are set by using an external divider resistor and automatically selected by the DTY flag of control register 2 (R1).

Where  $V_{LCD} < V_{OUT}$ , the value of  $V_{LCD}$  can be calculated by the expression in Example 1 ( $DTY = 0$ ) and the expression in Example 2 ( $DTY = 1$ ).

**Example 1.** To calculate value of  $V_{LCD}$  ( $DTY = 0$ , in main duty display mode)

$$V_{LCD} = \left(1 + \frac{R_{be}}{R_{ae}}\right) V_{EV}$$

$$V_{LCD} = \left(1 + \frac{R_{be}}{R_{ae}}\right) \left(1 - \frac{\alpha}{256}\right) V_{REG}$$

**Remark**  $V_{EV} = \left(1 - \frac{\alpha}{256}\right) V_{REG}$

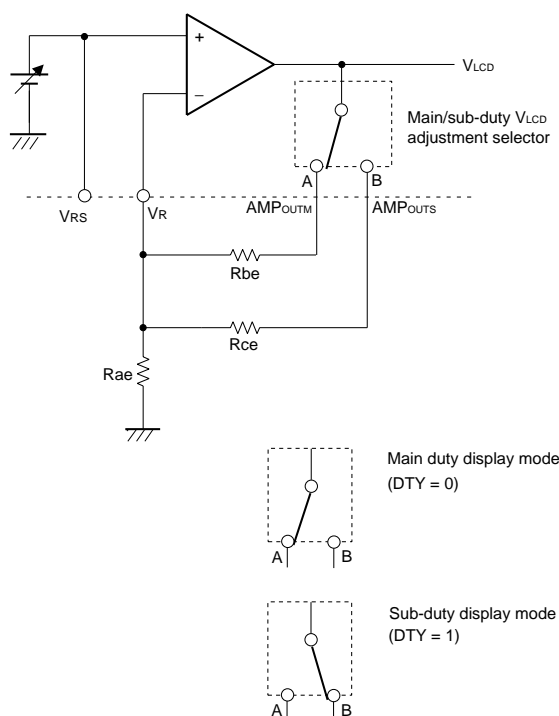
**Example 2.** To calculate value of  $V_{LCD}$  ( $DTY = 1$ , in sub-duty display mode)

$$V_{LCD} = \left(1 + \frac{R_{ce}}{R_{ae}}\right) V_{EV}$$

$$V_{LCD} = \left(1 + \frac{R_{ce}}{R_{ae}}\right) \left(1 - \frac{\alpha}{256}\right) V_{REG}$$

**Remark**  $V_{EV} = \left(1 - \frac{\alpha}{256}\right) V_{REG}$

**Figure 5-17. Example of Circuit Using External Resistor**



#### 5.6.4 Level voltage control by operational amplifier

Although the μPD161401 has a power-saving power supply circuit, the display quality may be degraded if it is used to drive a high-load LCD panel. The driving capability of the segment output can be controlled as shown in **Table 5–18** by LCS1 and LCS0 of power system control register 5 (R56), and the driving capability of the common outputs can be controlled as shown in **Table 5–19** by LCC1 and LCC0 of the same register. By controlling the driving capability, the display quality and power consumption may be improved. Determine the driving capability in accordance with the actual display status. If the display quality is not sufficiently improved in any driving mode, it will be necessary to supply the LCD drive voltage from an external power supply.

In addition, the operational amplifier driving modes shown in **Table 5–20** can be selected by the setting of HPM1 and HPM0, so that the wait time to stabilize the supply voltage immediately after the power has been turned ON or OFF can be shortened.

PSM1 specifies whether a boosting voltage of  $V_{DD2} \times 2$  is applied to the  $V_{LC3}$  or  $V_{LC4}$  level voltage follower of (refer to **Table 5–21**). If a voltage boosted two-fold is applied to the voltage follower circuit, the current consumption may be reduced.

Thoroughly confirm and evaluate the  $V_{LC3}$  and  $V_{LC4}$  levels of the LCD panel with the actual system to determine whether the two-fold LCD drive voltage is to be supplied.

PSM0 can be used to set the current value of all the voltage follower circuits as shown in **Table 5–22**.

**Table 5–18. Setting Driving Capability of Segment Outputs (LCS1, LCS0 = 0, 0)**

LCS1	LCS0	Segment Output Driving Capability (unit: fold)
0	0	One
0	1	Two
1	0	Four
1	1	Eight

**Table 5–19. Setting Driving Capability of Common Outputs (LCS1, LCS0 = 0, 0)**

LCC1	LCC0	Common Output Driving Capability (unit: fold)
0	0	Two
0	1	Four
1	0	Eight
1	1	Sixteen

**Table 5–20. Setting Operation Mode of Operational Amplifier**

HPM1	HPM0	Mode Setting
0	0	Normal mode
0	1	Power supply ON mode 1
1	0	Power supply OFF mode
1	1	Power supply ON mode 2

**Table 5–21. Setting of Two-Fold Drive Voltage**

PSM1	Mode Setting
0	Not used
1	Used

**Table 5–22. Voltage Follower Bias Current Setting**

PSM0	Bias Current Setting (unit: fold)
0	One
1	Two

5.6.5 Application example of power supply circuit

Figure 5-18. IRS = H, [OP3, OP2, OP1, OP0] = [1, 1, 1, 1]

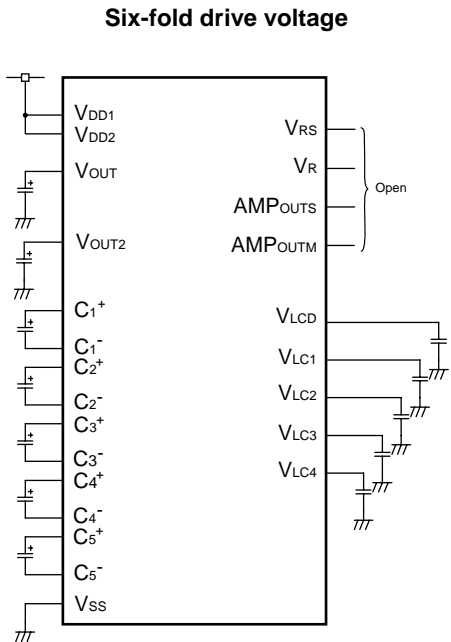


Figure 5-19. IRS = L, [OP3, OP2, OP1, OP0] = [1, 1, 1, 1]

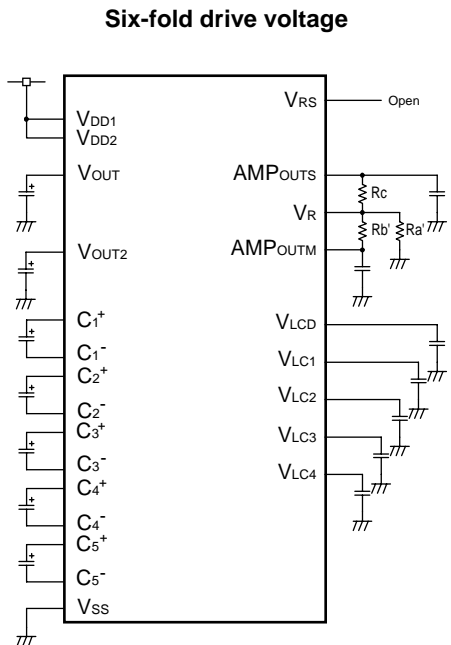


Figure 5–20. IRS = H, [OP3, OP2, OP1, OP0] = [0, 0, 0, 1]

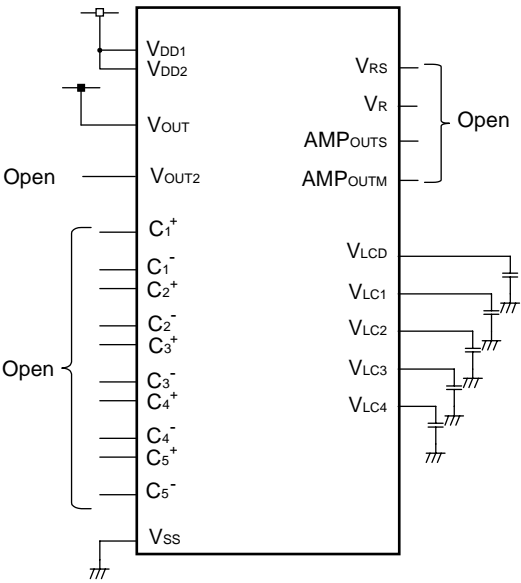


Figure 5–21. IRS = L, [OP3, OP2, OP1, OP0] = [0, 0, 0, 1]

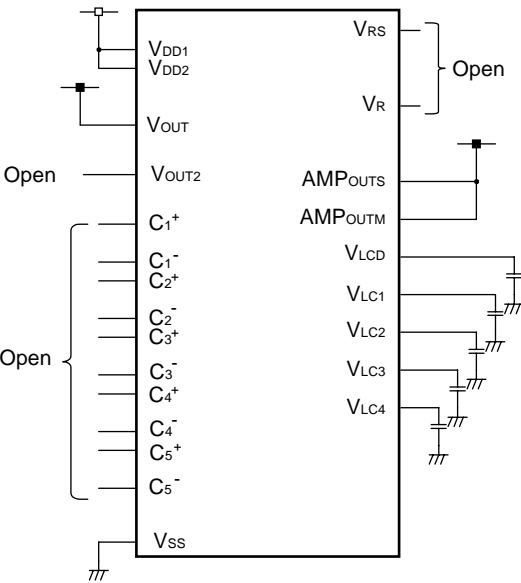


Figure 5–22. IRS = L, [OP3, OP2, OP1, OP0] = [0, 0, 0, 0]

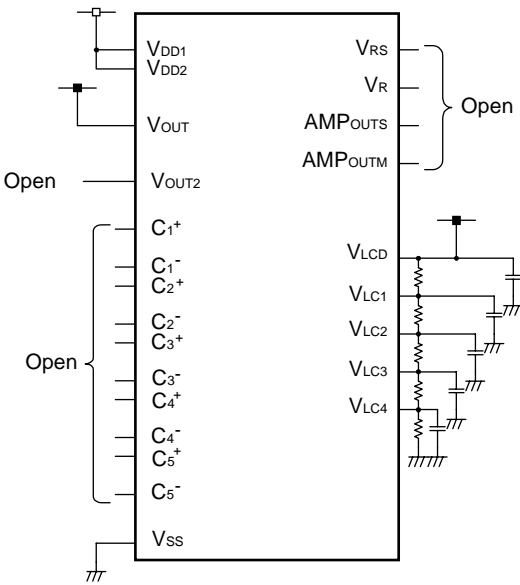
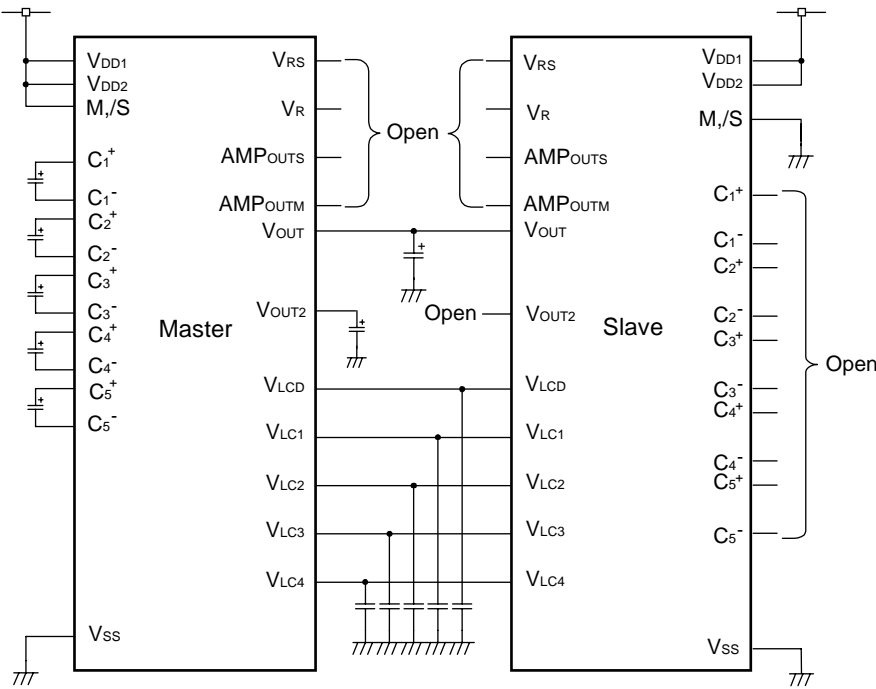
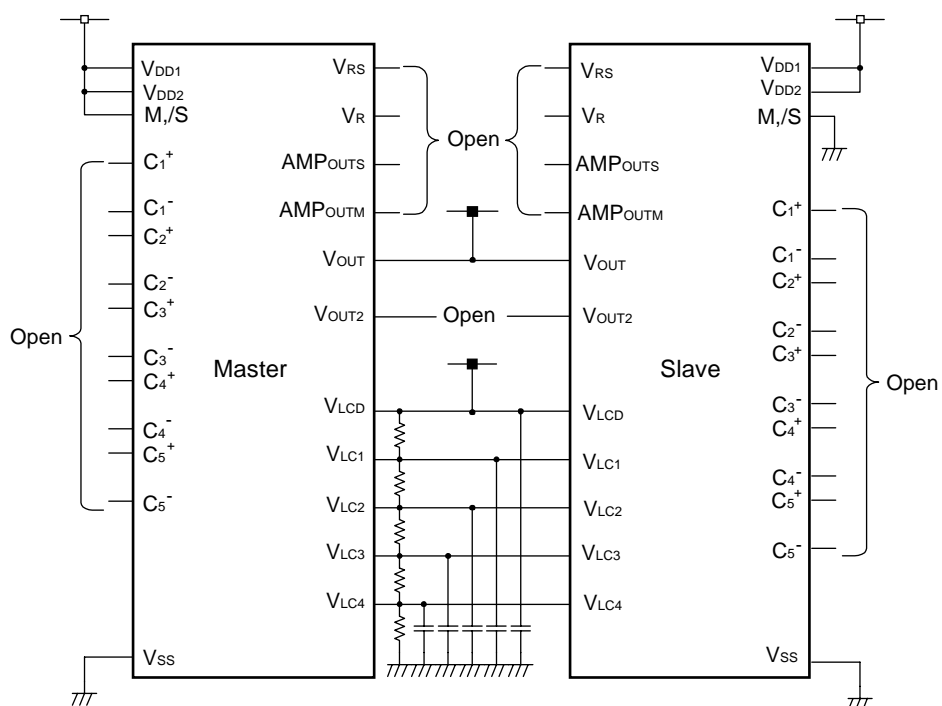


Figure 5–23. Master/Slave Connection Example 1



**Figure 5–24. Master/Slave Connection Example 2**



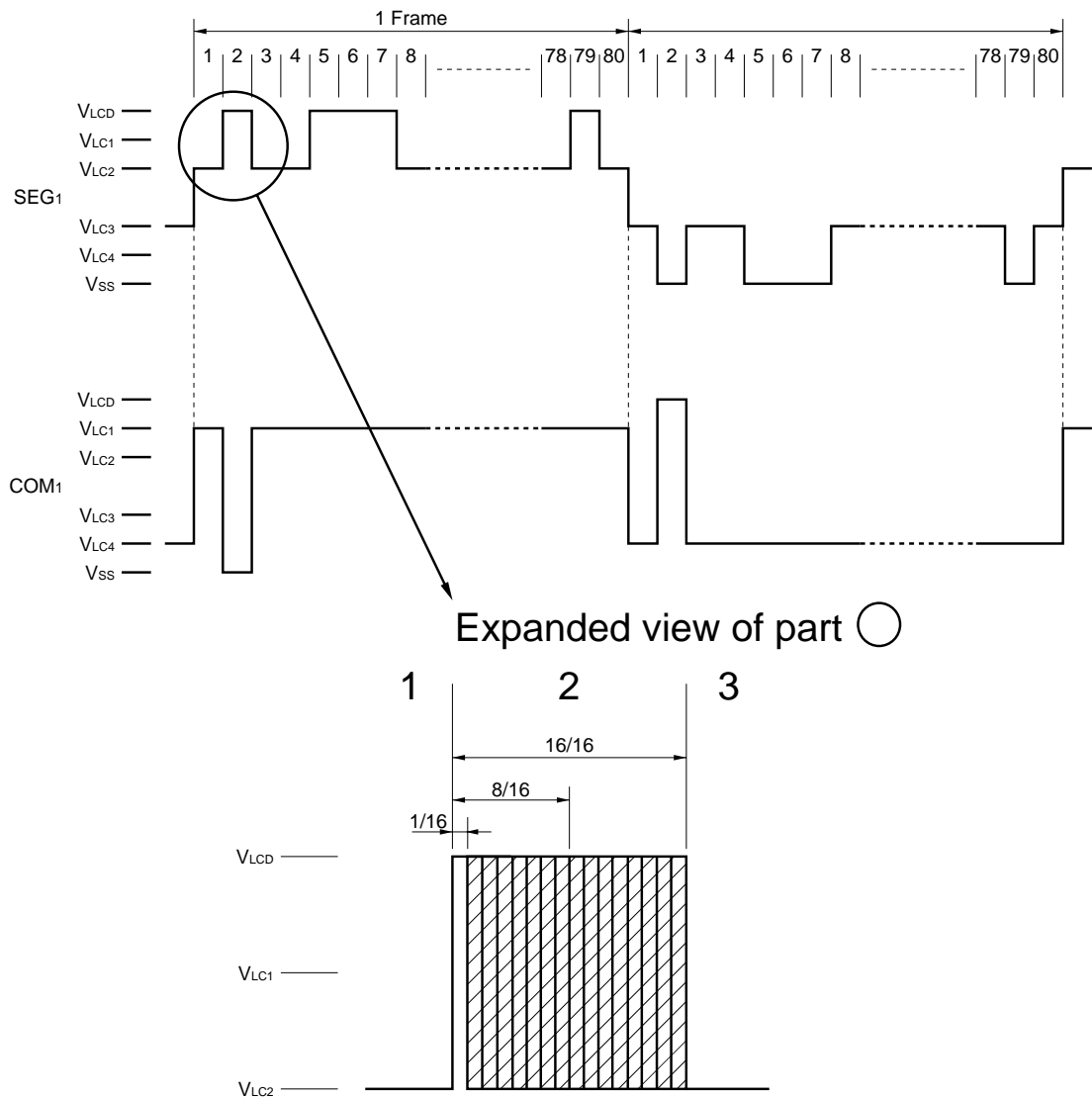
5.7 Driving LCD

The μPD161401 has a full-dot driver. This full-dot driver can modulate grayscale, depending on the setting of the pulse widths. In this driving mode, eight R/G output grayscales and four B output grayscales are selected from a 17-stage grayscale palette, and the selected grayscales are registered to the output grayscale palette of the IC. For details, refer to **Table 5–23** Example of Pulse Width Modulation Output.

5.7.1 Full-dot pulse modulation

The pulse width modulation function of the μPD161401 divides the segment pulse width of the signal for normal LCD display (16), and outputs the divided pulse width in accordance with the output timing of dots at the ratio of the grayscale palette selected by a command.

Figure 5–25. Full-Dot Pulse Width Modulation



**Caution** The width of the common output pulse is not modulated.



The pulse is output in the form of combined odd line/even line or even line/odd line output, as shown in **Figure 5–26**. **Table 5–23** shows the combination of the rising and falling edges of the pulse of each frame.

**Figure 5–26. Example of Pulse Width Modulation Output of Odd/Even Line**

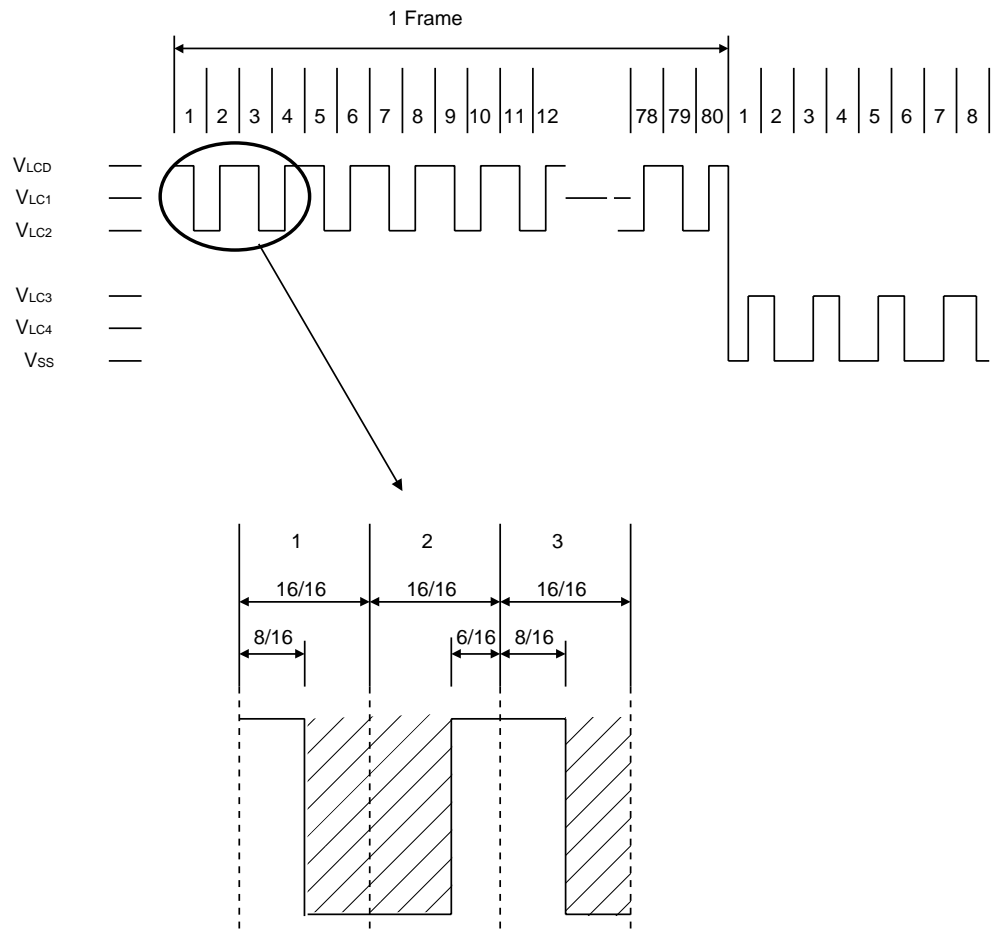


Table 5-23. Pulse Width Modulation Output

Grayscale Level	COM	1 or 2 Frames		3 or 4 Frames	
		SEG Odd Number	SEG Even Number	SEG Odd Number	SEG Even Number
0	2n+1	0	0	0	0
	2n+2	0	0	0	0
1	2n+1	1 $\uparrow$	1 $\downarrow$	1 $\downarrow$	1 $\uparrow$
	2n+2	1 $\downarrow$	1 $\uparrow$	1 $\uparrow$	1 $\downarrow$
2	2n+1	2 $\uparrow$	2 $\downarrow$	2 $\downarrow$	2 $\uparrow$
	2n+2	2 $\downarrow$	2 $\uparrow$	2 $\uparrow$	2 $\downarrow$
3	2n+1	3 $\uparrow$	3 $\downarrow$	3 $\downarrow$	3 $\uparrow$
	2n+2	3 $\downarrow$	3 $\uparrow$	3 $\uparrow$	3 $\downarrow$
4	2n+1	4 $\uparrow$	4 $\downarrow$	4 $\downarrow$	4 $\uparrow$
	2n+2	4 $\downarrow$	4 $\uparrow$	4 $\uparrow$	4 $\downarrow$
5	2n+1	5 $\uparrow$	5 $\downarrow$	5 $\downarrow$	5 $\uparrow$
	2n+2	5 $\downarrow$	5 $\uparrow$	5 $\uparrow$	5 $\downarrow$
6	2n+1	6 $\uparrow$	6 $\downarrow$	6 $\downarrow$	6 $\uparrow$
	2n+2	6 $\downarrow$	6 $\uparrow$	6 $\uparrow$	6 $\downarrow$
7	2n+1	7 $\uparrow$	7 $\downarrow$	7 $\downarrow$	7 $\uparrow$
	2n+2	7 $\downarrow$	7 $\uparrow$	7 $\uparrow$	7 $\downarrow$
8	2n+1	8 $\uparrow$	8 $\downarrow$	8 $\downarrow$	8 $\uparrow$
	2n+2	8 $\downarrow$	8 $\uparrow$	8 $\uparrow$	8 $\downarrow$
9	2n+1	9 $\uparrow$	9 $\downarrow$	9 $\downarrow$	9 $\uparrow$
	2n+2	9 $\downarrow$	9 $\uparrow$	9 $\uparrow$	9 $\downarrow$
10	2n+1	10 $\uparrow$	10 $\downarrow$	10 $\downarrow$	10 $\uparrow$
	2n+2	10 $\downarrow$	10 $\uparrow$	10 $\uparrow$	10 $\downarrow$
11	2n+1	11 $\uparrow$	11 $\downarrow$	11 $\downarrow$	11 $\uparrow$
	2n+2	11 $\downarrow$	11 $\uparrow$	11 $\uparrow$	11 $\downarrow$
12	2n+1	12 $\uparrow$	12 $\downarrow$	12 $\downarrow$	12 $\uparrow$
	2n+2	12 $\downarrow$	12 $\uparrow$	12 $\uparrow$	12 $\downarrow$
13	2n+1	13 $\uparrow$	13 $\downarrow$	13 $\downarrow$	13 $\uparrow$
	2n+2	13 $\downarrow$	13 $\uparrow$	13 $\uparrow$	13 $\downarrow$
14	2n+1	14 $\uparrow$	14 $\downarrow$	14 $\downarrow$	14 $\uparrow$
	2n+2	14 $\downarrow$	14 $\uparrow$	14 $\uparrow$	14 $\downarrow$
15	2n+1	15 $\uparrow$	15 $\downarrow$	15 $\downarrow$	15 $\uparrow$
	2n+2	15 $\downarrow$	15 $\uparrow$	15 $\uparrow$	15 $\downarrow$
16	2n+1	16 $\uparrow$	16 $\downarrow$	16 $\downarrow$	16 $\uparrow$
	2n+2	16 $\downarrow$	16 $\uparrow$	16 $\uparrow$	16 $\downarrow$

Remarks 1. n: Integer of 0 to 39

2.  $\uparrow$ A: Pulse rises in the middle of A line output.

3.  $\downarrow$ A: Pulse rises at the beginning of A line output.

4. A: PWM pulse width (A/16)

### 5.7.2 Grayscale palette

The μPD161401 has 17 levels of grayscale outputs. Eight R/G output grayscales and four B output grayscales can be selected for each of main duty display and sub-duty display, by using the grayscale data registers (R65 to R104), and can be output as the grayscale outputs of the IC to R/G/B.

**Table 5–24. Correspondence of Grayscale Levels of Grayscale Data Registers**

Grayscale Level	Set Value of Grayscale Data Register					Remark
	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	
Level 0	0	0	0	0	0	OFF data
Level 1	0	0	0	0	1	
Level 2	0	0	0	1	0	
Level 3	0	0	0	1	1	
Level 4	0	0	1	0	0	
Level 5	0	0	1	0	1	
Level 6	0	0	1	1	0	
Level 7	0	0	1	1	1	
Level 8	0	1	0	0	0	50%
Level 9	0	1	0	0	1	
Level 10	0	1	0	1	0	
Level 11	0	1	0	1	1	
Level 12	0	1	1	0	0	
Level 13	0	1	1	0	1	
Level 14	0	1	1	1	0	
Level 15	0	1	1	1	1	
Level 16	1	0	0	0	0	100%

### 5.7.3 Setting of display size

The μPD161401 can set the main duty cycles in a range of 1/80, 1/72 and 1/64 duty, the sub-duty cycles in a range of 1/48, 1/40, 1/32, 1/24 and 1/16 duty. This can be done by setting MDT6 to MDT0 and SDT6 to SDT0 of the main duty setting register (R14) and sub-duty setting register (R17) as **Table 5–25** and **5–26**:

**Table 5–25. Setting of Main Duty (R14)**

MDT6	MDT5	MDT4	MDT3	MDT2	MDT1	MDT0	Duty
1	0	0	1	1	1	1	1/80
1	0	0	0	1	1	1	1/72
0	1	1	1	1	1	1	1/64

**Table 5–26. Setting of Sub-duty (R17)**

SDT6	SDT5	SDT4	SDT3	SDT2	SDT1	SDT0	Duty
0	1	0	1	1	1	1	1/48
0	1	0	0	1	1	1	1/40
0	0	1	1	1	1	1	1/32
0	0	1	0	1	1	1	1/24
0	0	0	1	1	1	1	1/16

### 5.7.4 Setting of LCD N-line inversion and M-line shift

During main duty display, the shift amount of the reverse position of AC driving and the reverse position of each display frame can be set by the main duty N-line inversion register (R15) and main duty M-line shift register (R16). They can also be set by the sub-duty N-line inversion register (R18) and sub-duty M-line shift register (R19) during sub-duty display.

The N-line reverse cycle function can set a line to be reversed as shown in **Table 5–27**, depending on the setting of MID5 to MID0 or SID5 to SID0 of the main or sub-duty N-line inversion register.

The M-line shift amount of the reverse position of each display frame can be set as shown in **Table 5–28**, by using MSD5 to MSD0 or SSD5 to SSD0 of the main or sub-duty M-line shift register.

**Table 5–27. Setting of N-line Inversion Register (R15)**

MID5	MID4	MID3	MID2	MID1	MID0	Reversed Cycle
SID5	SID4	SID3	SID2	SID1	SID0	
0	0	0	0	0	0	1
0	0	0	0	0	1	2
0	0	0	0	1	0	3
0	0	0	0	1	1	4
		⋮				⋮
1	0	0	1	0	1	38
1	0	0	1	1	0	39
1	0	0	1	1	1	40

Table 5–28. Setting of M-line Shift Register

MSD5	MSD4	MSD3	MSD2	MSD1	MSD0	Reversed Position Shift Amount
SSD5	SSD4	SSD3	SSD2	SSD1	SSD0	
0	0	0	0	0	0	0
0	0	0	0	0	1	1
0	0	0	0	1	0	2
0	0	0	0	1	1	3
		⋮				⋮
1	0	0	1	1	0	38
1	0	0	1	1	1	39
1	0	1	0	0	0	40

Make sure that the display size, reverse cycle, and shift amount of reverse position have the relationship indicated by the following expression:

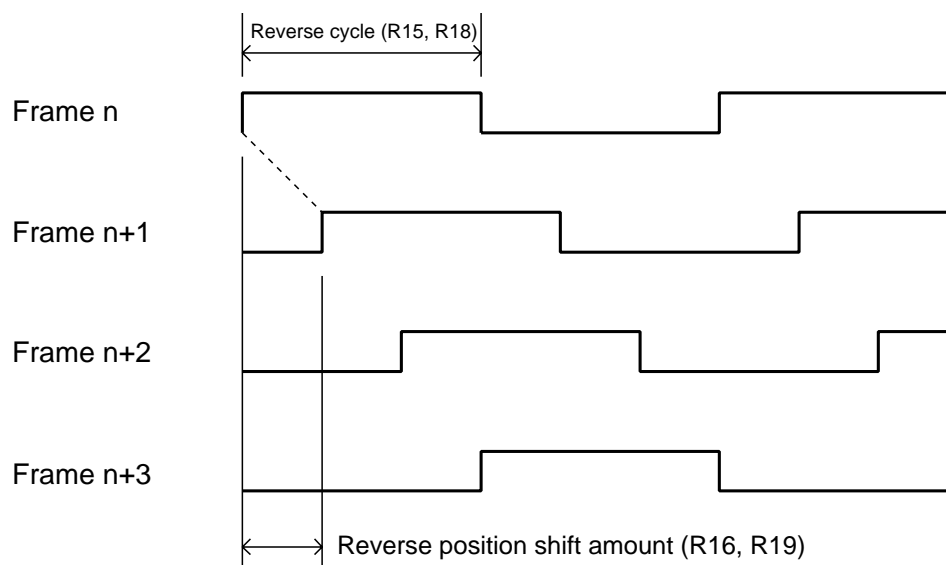
$$\text{Display size (duty)} \geq \text{reverse cycle} \geq \text{reverse shift amount}$$

### 5.7.5 Reverse driving between frames

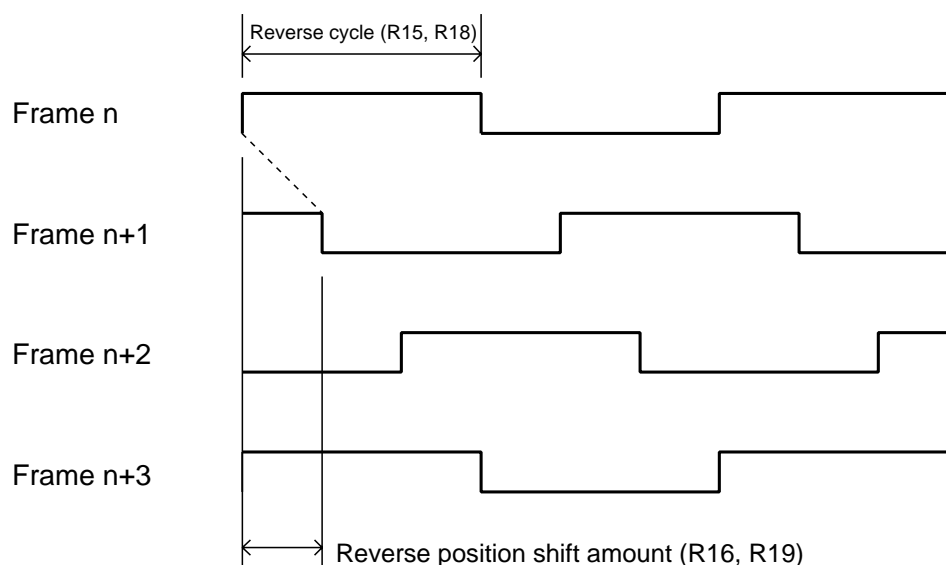
In the μPD161401, the LCD drive waveform can be reversed and output between frames by setting the FXOR flag of Driving mode select register (R64), as shown in **Figure 5–27**. This function is executed in combination with the reverse cycle and reverse shift functions.

**Figure 5–27. Image of Reversal between Pulse Width Modulation Frames**

Reversal between frames not implemented (FXOR = 0)



Implementation of reversal between frames (FXOR = 1)



## 5.8 Display Mode

### 5.8.1 Selecting display mode

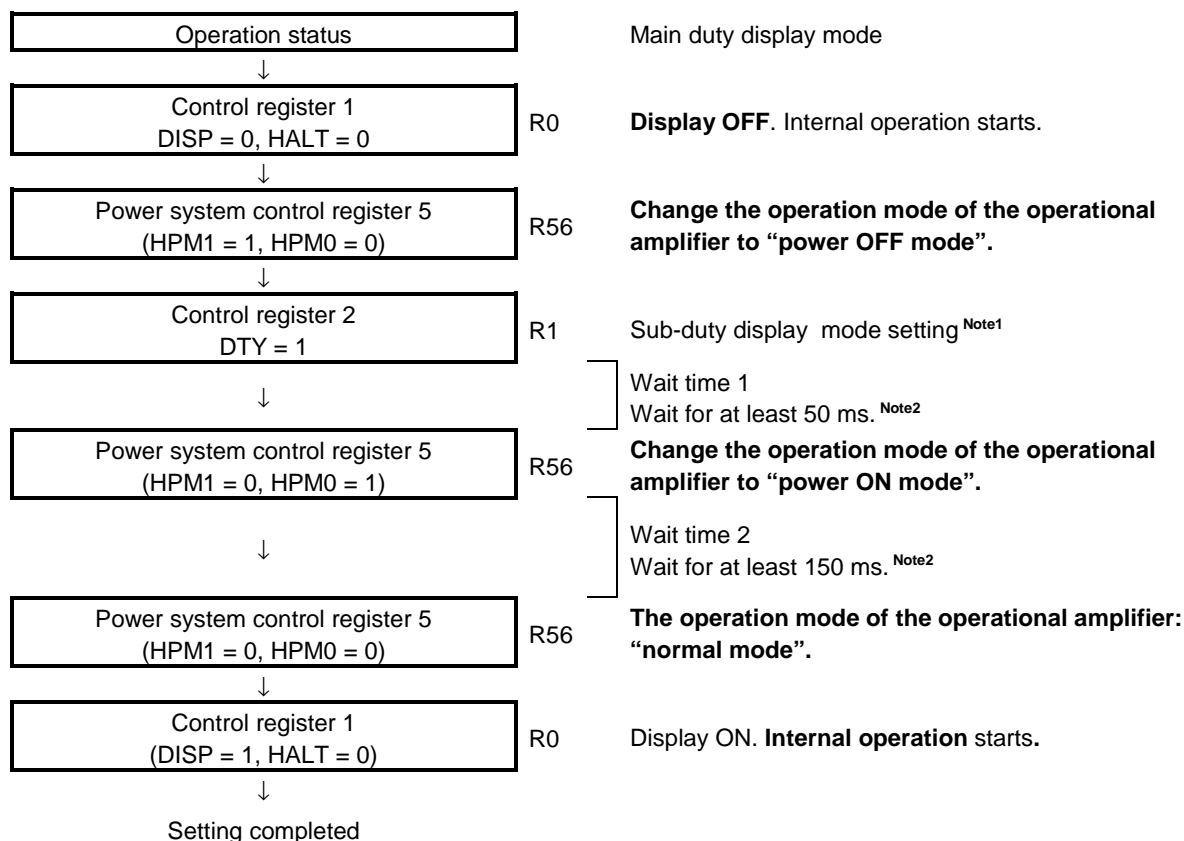
The μPD161401 has two display modes: main duty display and sub-duty display. In each of these modes, any duty ratio can be selected and parts other than the display area can be scanned with a non-selected waveform.

The display mode can be selected by using the DTY flag of control register 2 (R1), and parameters such as the duty ratio, bias value, and number of boosting steps are automatically selected as shown in the table below.

Display Setting	Main Duty Display (DTY = 0)	Sub-duty Display (DTY = 1)
Duty ratio	Main duty setting register (R14)	Sub-duty setting register (R17)
N-line inversion	Main duty N-line inversion register (R15)	Sub-duty N-line inversion register (R18)
M-line shift	Main duty M-line shift register (R16)	Sub-duty M-line shift register (R19)
V <sub>LCD</sub> adjustment	Power system control register 2 (R53) VRR3 to VRR0	Power system control register 2 (R53) SVR3 to SVR0
Bias value	Power system control register 3 (R54) BIS2 to BIS0	Power system control register 3 (R54) SBIS2 to SBIS0
Number of boosting steps	Power system control register 4 (R55) MBT2 to MBT0	Power system control register 4 (R55) SBT2 to SBT0
Electronic volume	Main electronic volume register (R57)	Sub-electronic volume register (R58)
Grayscale data setting	Main R grayscale data registers (R65 to R72) Main G grayscale data registers (R73 to R80) Main B grayscale data registers (R81 to R84)	Sub R grayscale data registers (R85 to R92) Sub G grayscale data registers (R93 to R100) Sub B grayscale data registers (R101 to R104)

When the mode is changed from the main duty display mode to the sub-duty display mode or vice versa, the display screen may be temporarily disturbed, depending on the setting of each duty mode, if electric charge remains in the smoothing capacitor connected between the LCD drive voltage pins (V<sub>LCD</sub>, V<sub>LC1</sub> to V<sub>LC4</sub>) and V<sub>SS</sub>. It is recommended that the following power sequence be observed to avoid any trouble that may occur when the display mode is changed.

★ (1) Main duty display mode to sub-duty display mode

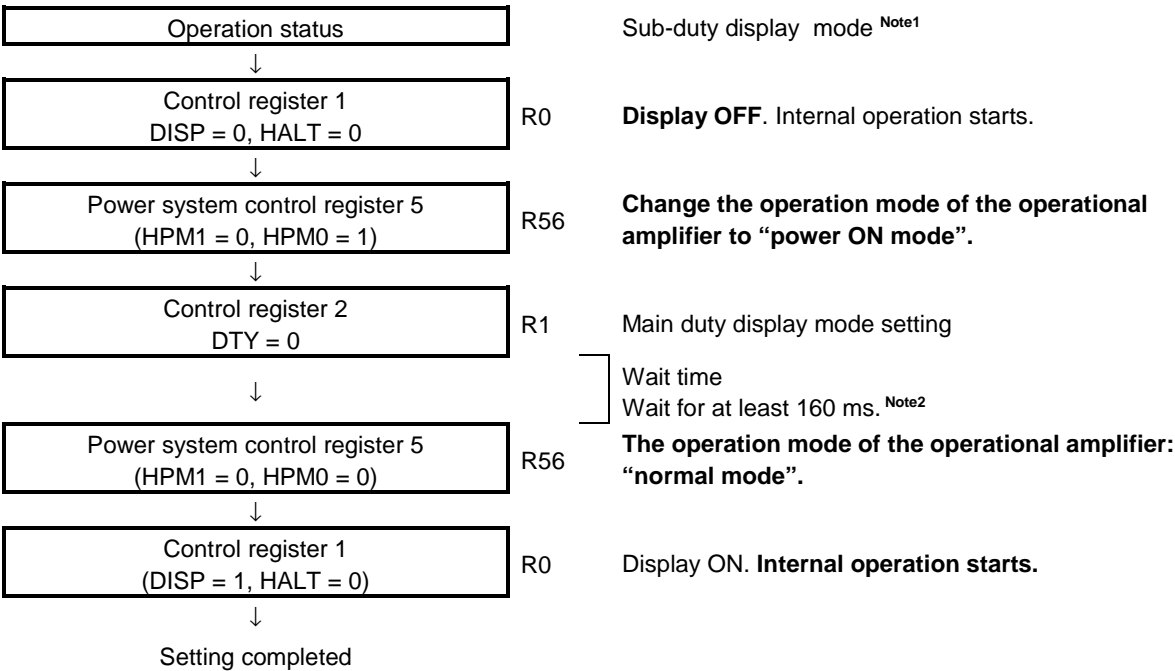


**Notes 1.** A scroll function cannot be used in sub-duty display mode. In the state where the scroll function is used by main duty display mode when it changes to sub-duty, a scroll function is disregarded. Then, when it changes to main duty display mode again, a scroll function returns to an effective state (state before changing to sub-duty).

**2.** The wait times 1, 2 vary depending on the characteristics of the LCD panel and the capacitance of the boosting or smoothing capacitor. It is recommended to determine these values after thorough evaluation with the actual system.



★ (2) Sub-duty display mode to main duty display mode



- Notes 1.** A scroll function cannot be used in sub-duty display mode. In the state where the scroll function is used by main duty display mode when it changes to sub-duty, a scroll function is disregarded. Then, when it changes to main duty display mode again, a scroll function returns to an effective state (state before changing to sub-duty).
- 2.** The wait time varies depending on the characteristics of the LCD panel and the capacitance of the boosting or smoothing capacitor. It is recommended to determine this value after thorough evaluation with the actual system.

## 5.8.2 Screen scrolling

The μPD161401 has a screen scroll function. This function is enabled during main duty display. The width of the area to be fixed is specified by the scroll fixed area width register (R27) and the number of scroll steps is set by the scroll step number register (R31). By these settings, other parts of screen can be scrolled with part of the screen fixed. To specify the position of the area to be fixed, set the FIXAHL flag of the scroll fixed area position register (R23) as shown in **Table 5–29**. Specify the fixed area position on the upper part of the LCD panel in master mode and on the bottom part of the panel in slave mode.

**Table 5–29. Scroll Fixed Area Width Register (R27)**

FIXAW1	FIXAW0	Fixed area width
0	0	0
0	1	16
1	0	24
1	1	32

**Table 5–30. Scroll Step Count Register (R31)**

MST6	MST5	MST4	MST3	MST2	MST1	MST0	Number of Scroll Steps
0	0	0	0	0	0	0	0
0	0	0	0	0	0	1	1
0	0	0	0	0	1	0	2
0	0	0	0	0	1	1	3
			⋮				⋮
1	0	0	1	1	1	0	78
1	0	0	1	1	1	1	79
1	0	1	0	0	0	0	Other settings prohibited

Note that the relationship between the number of scroll steps and the width of the scroll fixed area needs to be set so that the following condition is set.

$$\text{Number of scroll steps} \leq 79 - \text{Width of scroll fixed area}$$

**Caution** If values other than the above is set, the operation is not guaranteed.

**Table 5–31. Scroll Fixed Area Position Register (R23)**

FIXAHL	LCD Display Position
0	Bottom
1	Upper

### 5.8.3 Scroll setting examples

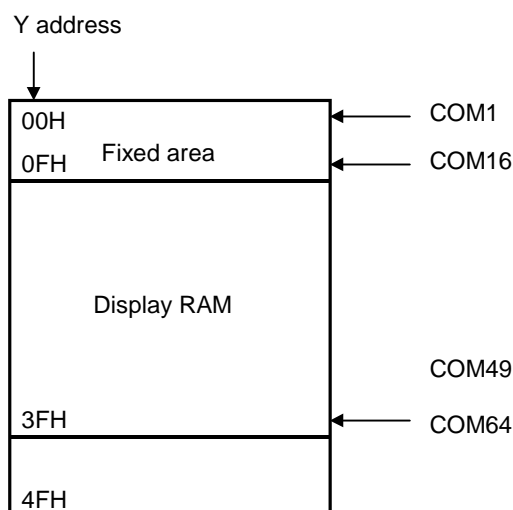
#### ★ (1) Setting example 1

Duty: 1/64 duty

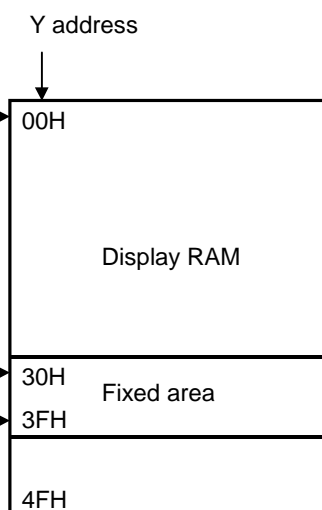
RAM read direction: normal (R0:COMR = 0)

Scroll fixed area width: 16 lines (R27: FIXAW1,0 = 0,1)

#### (a) Scroll fixed position: upper (R23: FIXAHL = 1)



#### (b) Scroll fixed position: bottom (R23: FIXAHL = 0)



The relationships between the numbers of scroll steps and RAM Y address scan order in cases of (a) and (b) are as follows.

#### (a)

Number of scroll steps: 0 (R31: MSTn = 00H)

Number of scroll steps: 1 (R31: MSTn = 01H)

Number of scroll steps: 10 (R31: MSTn = 0AH)

RAM Y address: 00H → 0FH, 10H → 3FH

RAM Y address: 00H → 0FH, 11H → 40H

RAM Y address: 00H → 0FH, 1AH → 49H

#### (b)

Number of scroll steps: 0 (R31: MSTn = 00H)

Number of scroll steps: 1 (R31: MSTn = 01H)

Number of scroll steps: 10 (R31: MSTn = 0AH)

RAM Y address: 00H → 2FH, 30H → 3FH

RAM Y address: 00H → 2FH, 40H, 30H → 3FH

RAM Y address: 0AH → 2FH, 40H → 49H, 30H → 3FH

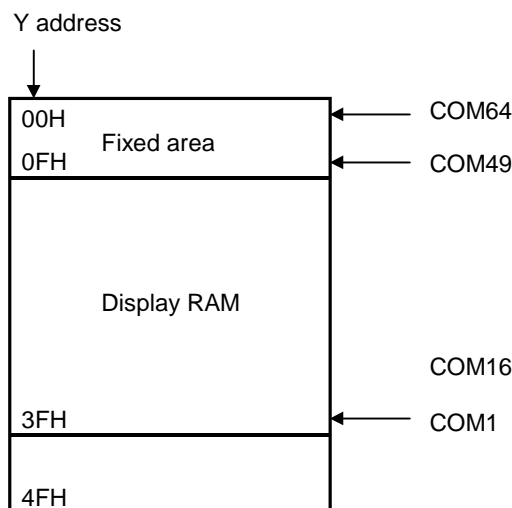
★ (2) Setting example 2

Duty: 1/64 duty

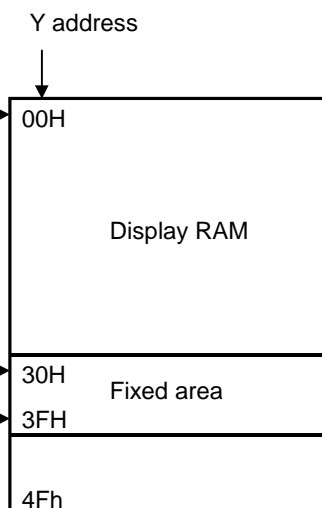
RAM read direction: reverse (R0: COMR = 1)

Scroll fixed area width: 16 lines (R27: FIXAW1,0 = 0,1)

(a) Scroll fixed position: upper (R23: FIXAHL = 1)



(b) Scroll fixed position: bottom (R23: FIXAHL = 0)



The relationships between the numbers of scroll steps and RAM Y address scan order in cases of (a) and (b) are as follows.

(a)

Number of scroll steps: 0 (R31: MSTn = 00H)

RAM Y address: 3FH → 10h, 0FH → 00H

Number of scroll steps: 1 (R31: MSTn = 01H)

RAM Y address: 40H → 11h, 0FH → 00H

Number of scroll steps: 10 (R31: MSTn = 0AH)

RAM Y address: 49H → 1Ah, 0FH → 00H

(b)

Number of scroll steps: 0 (R31: MSTn = 00H)

RAM Y address: 3Fh → 30H, 2FH → 00H

Number of scroll steps: 1 (R31: MSTn = 01H)

RAM Y address: 3Fh → 30H, 40h, 2FH → 01H

Number of scroll steps: 10 (R31: MSTn = 0AH)

RAM Y address: 3Fh → 30hH, 49H → 40H, 2FH → 0AH

## 5.9 Reset

When the reset command is input, the IC is initialized to the default status shown in the table below. Note that initialization by using the /DISP pin should be used only to prevent malfunctioning due to noise.

**Table 5–32. Default Values of Registers (1/2)**

Register		Reset Command	/DISP
Control register 1	R0	O	O (DISP, TRON flag only)
Control register 2	R1	O	×
X address register	R4	O	×
Y address register	R5	O	×
MIN.X address register	R7	O	×
MAX.X address register	R8	O	×
MIN.Y address register	R9	O	×
MIN.Y address register	R10	O	×
Display memory access register	R12	×	×
Main duty setting register	R14	O	×
Main duty N-line inversion register	R15	O	×
Main duty M-line shift register	R16	O	×
Sub-duty setting register	R17	O	×
Sub-duty N-line inversion register	R18	O	×
Sub-duty M-line shift register	R19	O	×
COM scanning address setting register	R21	O	×
Sub-duty start address register	R22	O	×
Scroll fixed area position register	R23	O	×
Scroll fixed area width register	R27	O	×
Scroll steps number register	R31	O	×
Blinking/reverse setting register	R37	O	×
Complementary color blink X address register	R38	O	×
Complementary color blink start line address register	R39	O	×
Complementary color blink end line address register	R40	O	×
Complementary color blink data memory register	R41	×	×
Specified color blink X address register	R42	O	×
Specified color blink start line address register	R43	O	×
Specified color blink end line address register	R44	O	×
Specified color blink data memory register	R45	×	×
Specified color setting register	R46	O	×
Reverse X address register	R47	O	×
Reverse start line address register	R48	O	×

**Remark** O: Default value is input. X: Default value is not input.

**Cautions 1.** When initialization is made using the /DISP pin, the contents of memory are not guaranteed.

In this case, use the initialized RAM. When initialization is made via the reset command, the contents of memory are retained.

2. If the device is initialized by the /DISP pin while the serial interface is being used, the serial clock counter is initialized.
3. Always input the reset command as the first command after power application.

Table 5–32. Default Values of Registers (2/2)

Register		Reset Command	/DISP
Reverse end line address register	R49	O	×
Reversed data memory access register	R50	×	×
Power system control register 1	R52	O	×
Power system control register 2	R53	O	×
Power system control register 3	R54	O	×
Power system control register 4	R55	O	×
Power system control register 5	R56	O	×
Main electronic volume register	R57	O	×
Sub-electronic volume register	R58	O	×
RAM test mode setting register	R61	O	×
Driving mode select register	R64	O	×
Main R grayscale data registers 1 to 8	R65 to R72	O	×
Main G grayscale data registers 1 to 8	R73 to R80	O	×
Main B grayscale data registers 1 to 4	R81 to R84	O	×
Sub R grayscale data registers 1 to 8	R85 to R92	O	×
Sub G grayscale data registers 1 to 8	R93 to R100	O	×
Sub B grayscale data registers 1 to 8	R101 to R104	O	×

**Remark** O: Default value is input. X: Default value is not input.

**Cautions 1.** When initialization is made using the /DISP pin, the contents of memory are not guaranteed.

In this case, use the initialized RAM. When initialization is made via the reset command, the contents of memory are retained.

2. If the device is initialized by the /DISP pin while the serial interface is being used, the serial clock counter is initialized.
3. Always input the reset command as the first command after power application.

## 6. COMMANDS

The  $\mu$ PD161401 identifies data bus signals by a combination of the RS, /RD (E), and /WR (R,/W) signals. It interprets and executes commands only in accordance with the internal timing, without being dependent upon the external clock. Therefore, the processing speed is extremely high and, usually, no busy check is necessary.

An i80 system CPU interface inputs a low pulse to the /RD pin when it reads data from the  $\mu$ PD161401 to issue a command. It inputs a low pulse to the /WR pin when it writes data to the  $\mu$ PD161401.

Data can be read from an M68 system CPU interface if a high-pulse signal is input to the R,/W pin, and written if a low-pulse signal is input to the R,/W pin. A command is executed if a high-pulse signal is input to the E pin in this status. Therefore, in the explanation of the commands and display commands in **6.1 Control Register 1 (R0)** and the sections that follow, the M68 system CPU interface uses H, instead of /RD (E), when reading status or display data. This is how it differs from the i80 system CPU interface.

The commands of the  $\mu$ PD161401 are explained below, taking an i80 system CPU interface as an example. When the serial interface is used, sequentially input data to the  $\mu$ PD161401, starting from D<sub>7</sub>.

The data bus length to input commands is as follows:

- Commands other than those that manipulate the display memory access register (R12) are input in byte units, regardless of the value of BMOD (control register 2 (R1), bus length setting).
- The commands that manipulate the display memory access register (R12) are input in 1-byte units when BMOD = 1, or in 2-byte units when BMOD = 0.

### A. Commands other than those that manipulate display memory access register (R12)

BMOD = 1 (8-bit data bus)

Pin	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
DATA	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>

BMOD = 0 (16-bit data bus)

Pin	D <sub>15</sub>	D <sub>14</sub>	D <sub>13</sub>	D <sub>12</sub>	D <sub>11</sub>	D <sub>10</sub>	D <sub>9</sub>	D <sub>8</sub>	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
DATA	Note	Note	Note	Note	Note	Note	Note	Note	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>

**Note** 0 or 1

### B. Display memory access register (R12)

BMOD = 1 (8-bit data bus)

Pin	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
DATA	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>

BMOD = 0 (16-bit data bus)

Pin	D <sub>15</sub>	D <sub>14</sub>	D <sub>13</sub>	D <sub>12</sub>	D <sub>11</sub>	D <sub>10</sub>	D <sub>9</sub>	D <sub>8</sub>	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
DATA	D <sub>15</sub>	D <sub>14</sub>	D <sub>13</sub>	D <sub>12</sub>	D <sub>11</sub>	D <sub>10</sub>	D <sub>9</sub>	D <sub>8</sub>	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>

## 6.1 Control Register 1 (R0)

This command specifies the general operation mode of the μPD161401.

RS	E /RD	R <sub>0</sub> /W /WR	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1	1	0	TRON	WAS	COMF	DISP	STBY	HALT	ADC	COMR

TRON	0: Normal mode (all values written to the test register are ignored) 1: Test register valid mode (values written to the test register are valid)
WAS	0: Normal data write mode 1: Window access mode (Refer to <b>5.2.7 Arbitrary address area access (window access mode (WAS))</b> .)
COMF	0: Normal display operation 1: All output from common pins is OFF (all the common pins output a non-selected waveform. At this time, the segment pins output OFF data (level 0)).
DISP	0: Display OFF (All the LCD output pins output a V <sub>SS</sub> level, and the oscillator and DC/DC converter operate.) 1: Display ON
STBY	0: Normal operation 1: Internal operation and oscillation stop. Display OFF
HALT	0: Internal operation starts. 1: Internal operation stops (all the LCD output pins output a V <sub>SS</sub> level, the oscillator operates, and the DC/DC converter stops, and the reference voltage generator operates).
ADC	Column addresses correspond to SEG outputs that are used to display the display data RAM (refer to <b>Table 6–1</b> ).
COMR	Selects the direction in which the lines of the graphic RAM are read (refer to <b>Table 6–2</b> ).

**Table 6–1. Relationship between Column Address of Display RAM and Segment Output**

SEG Output	SEG <sub>1</sub>	...	SEG <sub>303</sub>
ADC (D <sub>1</sub> )	0 1	→ ←	12EH 000H

**Table 6–2. Relationship between Common Scan Circuit and Scan Direction**

COMR (D <sub>0</sub> )	0 1	00H 4FH	→ →	4FH 00H
---------------------------	--------	------------	--------	------------

### Default (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
0	0	0	0	0	0	0	0



## 6.2 Control Register 2 (R1)

This command specifies the general operation mode of the μPD161401.

RS	E /RD	R <sub>7</sub> /W /WR	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1	1	0	FDM		BMOD		DTY	INC	XDIR	YDIR

FDM	Sets all screen display modes. 0: Normal operation 1: All screen display (Turns ON all screens [outputs grayscale level 16 to all screens].)
BMOD	Selects data length when parallel data is input. 0: 16-bit data bus 1: 8-bit data bus
DTY	0: Main duty display mode 1: Sub-duty display mode
INC <sup>Note</sup>	0: Increments/decrements X address each time it is accessed. 1: Increments/decrements Y address each time it is accessed.
XDIR <sup>Note</sup>	Specifies the direction in which the X address is to be accessed. 0: Increment (+1) 1: Decrement (-1)
YDIR <sup>Note</sup>	Specifies the direction in which the Y address is to be accessed. 0: Increment (+1) 1: Decrement (-1)

**Note** If the access direction is changed by INC, XDIR, or YDIR, be sure to set the X address register (R4) and Y address register (R5) before accessing the display RAM.

**Table 6–3. Relationship between Functions of μPD161401 and Display Mode**

Display Setting	Main Duty Display (DTY = 0)	Sub-duty Display (DTY = 1)
Duty	Main duty setting register (R14)	Sub-duty setting register (R17)
N-line inversion	Main duty N-line inversion register (R15)	Sub-duty N-line inversion register (R18)
M-line shift	Main duty M-line shift register (R16)	Sub-duty M-line shift register (R19)
V <sub>LCD</sub> adjustment	Power system control register 2 (R53) VRR3 to VRR0	Power system control register 2 (R53) SVR3 to SVR0
Bias value	Power system control register 3 (R54) BIS2 to BIS0	Power system control register 3 (R54) SBIS to SBIS0
Number of boosting steps	Power system control register 4 (R55) MBT2 to MBT0	Power system control register 4 (R55) SBT2 to SBT0
Electronic volume	Main electronic volume register (R57)	Sub-electronic volume register (R58)
Grayscale data setting	Main R grayscale data register (R65 to R72) Main G grayscale data register (R73 to R80) Main B grayscale data register (R81 to R84)	Sub R grayscale data register (R85 to R92) Sub G grayscale data register (R93 to R100) Sub B grayscale data register (R101 to R104)

### Default (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
0	<b>Note</b>	0	<b>Note</b>	0	0	0	0

**Note** 0 or 1

### 6.3 Reset Command Register (R3)

When this command is input, the registers of the  $\mu$ PD161401 (R0 to R104) are set to the default values.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1	0	0	0	0	0	0	0	1

**Caution** At power application, be sure to input the reset command as the first command.

### 6.4 X Address Register (R4)

The X address register specifies the X address of the display RAM the CPU accesses. This address is automatically incremented or decremented each time the display RAM has been accessed (INC = 0).

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1		XA6	XA5	XA4	XA3	XA2	XA1	XA0

**Caution** If the access direction is changed by control register 2 (R1: INC, XDIR, YDIR) or window access area is changed or set by MIN.X address register (R7, R9) and MAX.X address register (R8, R10), be sure to set the X address register (R4) and Y address register (R5) before accessing the display RAM.

Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	0	0	0	0	0	0	0

**Note** 0 or 1

### 6.5 Y Address Register (R5)

The Y address register specifies the Y address of the display RAM the CPU accesses. This address is automatically incremented or decremented each time the display RAM is accessed (INC = 1).

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1		YA6	YA5	YA4	YA3	YA2	YA1	YA0

YA6 to YA0	Sets line address
------------	-------------------

**Caution** If the access direction is changed by control register 2 (R1: INC, XDIR, YDIR), be sure to set the X address register (R4) and Y address register (R5) before accessing the display RAM.

Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	0	0	0	0	0	0	0

**Note** 0 or 1

### 6.6 MIN.-X Address Register (R7)

This register specifies the X address of the start point of the display RAM the CPU accesses when the window access mode is used.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1		XMN6	XMN5	XMN4	XMN3	XMN2	XMN1	XMN0

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	0	0	0	0	0	0	0

**Note** 0 or 1

### 6.7 MAX.-X Address Register (R8)

This register specifies the X address of the end point of the display RAM the CPU accesses when the window access mode is used.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1		XXM6	XXM5	XXM4	XXM3	XXM2	XXM1	XXM0

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	0	0	0	0	0	0	0

**Note** 0 or 1

### 6.8 MIN.-Y Address Register (R9)

This register specifies the Y address of the start point of the display RAM the CPU accesses when the window access mode is used.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1		YMN6	YMN5	YMN4	YMN3	YMN2	YMN1	YMN0

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	0	0	0	0	0	0	0

**Note** 0 or 1

### 6.9 MAX.-Y Address Register (R10)

This register specifies the Y address of the end point of the display RAM the CPU accesses when the window access mode is used.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1		YMX6	YMX5	YMX4	YMX3	YMX2	YMX1	YMX0

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	0	0	0	0	0	0	0

**Note** 0 or 1

### 6.10 Display Memory Access Register (R12)

The display memory access register is used to access the display RAM. When data is written to this register, it is directly written to the display RAM. In the  $\mu$ PD161401, the data of the display access memory register (R12) cannot be read.

BMOD = 1 (8-bit data bus)

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>

BMOD = 0 (16-bit data bus)

RS	D <sub>15</sub>	D <sub>14</sub>	D <sub>13</sub>	D <sub>12</sub>	D <sub>11</sub>	D <sub>10</sub>	D <sub>9</sub>	D <sub>8</sub>
1	D <sub>15</sub>	D <sub>14</sub>	D <sub>13</sub>	D <sub>12</sub>	D <sub>11</sub>	D <sub>10</sub>	D <sub>9</sub>	D <sub>8</sub>

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>

#### Default value (default value of reset command)

BMOD = 1 (8-bit data bus)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	Note	Note	Note	Note

**Note** 0 or 1

BMOD = 0 (16-bit data bus)

D <sub>15</sub>	D <sub>14</sub>	D <sub>13</sub>	D <sub>12</sub>	D <sub>11</sub>	D <sub>10</sub>	D <sub>9</sub>	D <sub>8</sub>
Note	Note	Note	Note	Note	Note	Note	Note

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	Note	Note	Note	Note

**Note** 0 or 1

### 6.11 Main Duty Setting Register (R14)

This register can set the display duty ratio in a range of 1/80, 1/72 and 1/64 duty as shown in **Table 6–5** in the main duty display mode.

Before changing the contents of this register, be sure to stop the internal operation by using the HALT command (control register 1 (R0)).

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1		MDT6	MDT5	MDT4	MDT3	MDT2	MDT1	MDT0

**Table 6–5. Main Duty Setting Register (R14)**

MDT6	MDT5	MDT4	MDT3	MDT2	MDT1	MDT0	Duty
1	0	0	1	1	1	1	1/80
1	0	0	0	1	1	1	1/72
0	1	1	1	1	1	1	1/64

**Default value (default value of reset command)**

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	1	0	0	1	1	1	1

**Note** 0 or 1

### 6.12 Main Duty N-line Inversion Register (R15)

This register can set the line position of AC driving in the main duty display mode as shown in **Table 6–6**.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1			MID5	MID4	MID3	MID2	MID1	MID0

**Table 6–6. Setting of Main Duty N-line Inversion Register (R15)**

MID5	MID4	MID3	MID2	MID1	MID0	Line to be reversed
0	0	0	0	0	0	1
0	0	0	0	0	1	2
0	0	0	0	1	0	3
		⋮				⋮
1	0	0	1	0	1	38
1	0	0	1	1	0	39
1	0	0	1	1	1	40

**Default value (default value of reset command)**

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	<b>Note</b>	1	0	0	1	1	1

**Note** 0 or 1

### 6.13 Main Duty M-line Shift Register (R16)

This register shifts the reverse position of each frame in the main duty display mode by the shift amount shown in Table 6–7.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1			MSD5	MSD4	MSD3	MSD2	MSD1	MSD0

**Table 6–7. Main Duty M-line Shift Register (R16)**

MSD5	MSD4	MSD3	MSD2	MSD1	MSD0	Shift amount of position to be reversed
0	0	0	0	0	0	0
0	0	0	0	0	1	1
0	0	0	0	1	0	2
0	0	0	0	1	1	3
		⋮				⋮
1	0	0	1	1	0	38
1	0	0	1	1	1	39
1	0	1	0	0	0	40

Make sure that the relationship between the display size, reverse cycle, and reverse position is established as follows.

**Display size (Duty)  $\geq$  reverse cycle  $\geq$  reverse shift amount**

**Default value (default value of reset command)**

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	0	0	0	0	0	0

**Note** 0 or 1

#### 6.14 Sub-duty Setting Register (R17)

This register can set the display duty ratio in a range of 1/48, 1/40, 1/32, 1/24 and 1/16 as shown in **Table 6–8** in the sub-duty display mode by setting SDT6 to SDT0.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1		SDT6	SDT5	SDT4	SDT3	SDT2	SDT1	SDT0

**Table 6–8. Main Duty Setting Register (R17)**

SDT6	SDT5	SDT4	SDT3	SDT2	SDT1	SDT0	Duty
0	1	0	1	1	1	1	1/48
0	1	0	0	1	1	1	1/40
0	0	1	1	1	1	1	1/32
0	0	1	0	1	1	1	1/24
0	0	0	1	1	1	1	1/16

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	0	1	0	1	1	1	1

**Note** 0 or 1

### 6.15 Sub-duty N-line Inversion Register (R18)

This register can set the line position of driving in the sub-duty display mode as shown in **Table 6–9**.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1			SID5	SID4	SID3	SID2	SID1	SID0

**Table 6–9. Sub-duty N-line Inversion Register (R18)**

SID5	SID4	SID3	SID2	SID1	SID0	Line to be reversed
0	0	0	0	0	0	1
0	0	0	0	0	1	2
0	0	0	0	1	0	3
0	0	0	0	1	1	4
		⋮				⋮
1	0	0	1	0	1	38
1	0	0	1	1	0	39
1	0	0	1	1	1	40

**Caution** Please protect the following relations.

**Sub-duty display size (duty) ≥ sub-duty reversed line**

If this relation is not protected, the operation is not guaranteed.

However, when the above-mentioned relation is not protected, inside μPD161401, processing which makes reversed line equal to display size is carried out. In addition, the value of a register is not rewritten automatically.

**Default value (default value of reset command)**

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	1	0	0	1	1	1

**Note** 0 or 1



# 6.16 Sub-duty M-line Shift Register (R19)

This register shifts the reverse position of each frame in the sub-duty display mode by the shift amount shown in Table 6–10.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1			SSD5	SSD4	SSD3	SSD2	SSD1	SSD0

Table 6–10. Sub-duty M-line Shift Register (R19)

SSD5	SSD4	SSD3	SSD2	SSD1	SSD0	Shift amount of position to be reversed
0	0	0	0	0	0	0
0	0	0	0	0	1	1
0	0	0	0	1	0	2
0	0	0	0	1	1	3
		⋮				⋮
1	0	0	1	1	0	38
1	0	0	1	1	1	39
1	0	1	0	0	0	40

Make sure that the relationship between the display size, reverse cycle, and reverse position is established as follows.

**Display size (duty) ≥ reverse cycle ≥ reverse shift amount**

Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	0	0	0	0	0	0

**Note** 0 or 1

### 6.17 COM Scanning Address Setting Register (R21)

This command specifies that scanning of the common outputs can be started from any of the On ( $n = 1$  to 80) output pins. Set the CSA4 to CSA0 bits as shown in **Table 6–11 (1/2)**. The scan start pin can be specified by the value  $n$  obtained from this table and the selected duty shown in **Table 6–11 (2/2)**. The common wiring on the LCD panel can be optimized according to the selected duty.

**Tables 6–12, 6–13, and 6–14** indicate examples of the COM scan address settings for 1/64 duty, 1/72 duty, and 1/80 duty.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1				CSA4	CSA3	CSA2	CSA1	CSA0

**Table 6–11. COM Scanning Address Setting Register (1/2)**

CSA4	CSA3	CSA2	CSA1	CSA0	n
0	0	0	0	0	1
0	0	0	0	1	2
0	0	0	1	0	3
		⋮			⋮
0	1	1	1	0	15
0	1	1	1	1	16
1	0	0	0	0	17
1	0	0	0	1	Other settings prohibited

**Table 6–11. COM Scanning Address Setting Register (2/2)**

COMR = 0			COMR = 1		
Scanning start (COM1) pin	→	Scanning end (COMa) <sup>Note</sup> pin	Scanning start (COM1) pin	→	Scanning end (COMa) <sup>Note</sup> pin
On	→	O(n+a–1) <sup>Note</sup>	O(82–a–n)	→	O(80–n+1) <sup>Note</sup>

**Note** a = 64: 1/64 duty  
a = 72: 1/72 duty  
a = 80: 1/80 duty

**Caution** Set the COM scan address setting register so that the scan start pin and scan end pin satisfy the equation below. If a value that exceeds this condition is set, the μPD161401 operation is not guaranteed.

$$O_1 \leq \text{Scan start pin and scan end pin} \leq O_{80}$$

Table 6–12. Example of COM Scanning Address Setting (1/64 duty)

CSA4	CSA3	CSA2	CSA1	CSA0	n	COMR = 0			COMR = 1		
						Scanning start (COM1) pin	→	Scanning end (COMa) <sup>Note</sup> pin	Scanning start (COM1) pin	→	Scanning end (COMa) <sup>Note</sup> pin
						On	→	O(n+a–1) <sup>Note</sup>	O(82–a–n)	→	O(80–n+1) <sup>Note</sup>
0	0	0	0	0	1	O <sub>1</sub>	→	O <sub>64</sub>	O <sub>17</sub>	→	O <sub>80</sub>
0	0	0	0	1	2	O <sub>2</sub>	→	O <sub>65</sub>	O <sub>16</sub>	→	O <sub>79</sub>
0	0	0	1	0	3	O <sub>3</sub>	→	O <sub>66</sub>	O <sub>15</sub>	→	O <sub>78</sub>
0	0	0	1	1	4	O <sub>4</sub>	→	O <sub>67</sub>	O <sub>14</sub>	→	O <sub>77</sub>
0	0	1	0	0	5	O <sub>5</sub>	→	O <sub>68</sub>	O <sub>13</sub>	→	O <sub>76</sub>
0	0	1	0	1	6	O <sub>6</sub>	→	O <sub>69</sub>	O <sub>12</sub>	→	O <sub>75</sub>
0	0	1	1	0	7	O <sub>7</sub>	→	O <sub>70</sub>	O <sub>11</sub>	→	O <sub>74</sub>
0	0	1	1	1	8	O <sub>8</sub>	→	O <sub>71</sub>	O <sub>10</sub>	→	O <sub>73</sub>
0	1	0	0	0	9	O <sub>9</sub>	→	O <sub>72</sub>	O <sub>9</sub>	→	O <sub>72</sub>
0	1	0	0	1	10	O <sub>10</sub>	→	O <sub>73</sub>	O <sub>8</sub>	→	O <sub>71</sub>
0	1	0	1	0	11	O <sub>11</sub>	→	O <sub>74</sub>	O <sub>7</sub>	→	O <sub>70</sub>
0	1	0	1	1	12	O <sub>12</sub>	→	O <sub>75</sub>	O <sub>6</sub>	→	O <sub>69</sub>
0	1	1	0	0	13	O <sub>13</sub>	→	O <sub>76</sub>	O <sub>5</sub>	→	O <sub>68</sub>
0	1	1	0	1	14	O <sub>14</sub>	→	O <sub>77</sub>	O <sub>4</sub>	→	O <sub>67</sub>
0	1	1	1	0	15	O <sub>15</sub>	→	O <sub>78</sub>	O <sub>3</sub>	→	O <sub>66</sub>
0	1	1	1	1	16	O <sub>16</sub>	→	O <sub>79</sub>	O <sub>2</sub>	→	O <sub>65</sub>
1	0	0	0	0	17	O <sub>17</sub>	→	O <sub>80</sub>	O <sub>1</sub>	→	O <sub>64</sub>

**Note** a = 64 at 1/64 duty

Table 6-13. Example of COM Scanning Address Setting (1/72 duty)

CSA4	CSA3	CSA2	CSA1	CSA0	n	COMR = 0		COMR = 1		Remark
						Scanning start (COM1) pin	Scanning end (COMa) <sup>Note</sup> pin	Scanning start (COM1) pin	Scanning end (COMa) <sup>Note</sup> pin	
						On	O(n+a-1) <sup>Note</sup>	O(82-a-n)	O(80-n+1) <sup>Note</sup>	
0	0	0	0	0	1	O <sub>1</sub>	→ O <sub>72</sub>	O <sub>9</sub>	→ O <sub>80</sub>	Other settings prohibited
0	0	0	0	1	2	O <sub>2</sub>	→ O <sub>73</sub>	O <sub>8</sub>	→ O <sub>79</sub>	
0	0	0	1	0	3	O <sub>3</sub>	→ O <sub>74</sub>	O <sub>7</sub>	→ O <sub>78</sub>	
0	0	0	1	1	4	O <sub>4</sub>	→ O <sub>75</sub>	O <sub>6</sub>	→ O <sub>77</sub>	
0	0	1	0	0	5	O <sub>5</sub>	→ O <sub>76</sub>	O <sub>5</sub>	→ O <sub>76</sub>	
0	0	1	0	1	6	O <sub>6</sub>	→ O <sub>77</sub>	O <sub>4</sub>	→ O <sub>75</sub>	
0	0	1	1	0	7	O <sub>7</sub>	→ O <sub>78</sub>	O <sub>3</sub>	→ O <sub>74</sub>	
0	0	1	1	1	8	O <sub>8</sub>	→ O <sub>79</sub>	O <sub>2</sub>	→ O <sub>73</sub>	
0	1	0	0	0	9	O <sub>9</sub>	→ O <sub>80</sub>	O <sub>1</sub>	→ O <sub>72</sub>	
0	1	0	0	1	10					

**Note** a = 72 at 1/72 duty

**Caution** Set the COM scan address setting register (R21) so that  $O_1 \leq \text{scan start pin}$  and  $\text{scan end pin} \leq O_{80}$ . If a value that exceeds this condition is set, the μPD161401 operation is not guaranteed

Table 6-14. Example of COM Scanning Address Setting (1/80 duty)

CSA4	CSA3	CSA2	CSA1	CSA0	n	COMR = 0		COMR = 1		Remark
						Scanning start (COM1) pin	Scanning end (COMa) <sup>Note</sup> pin	Scanning start (COM1) pin	Scanning end (COMa) <sup>Note</sup> pin	
						On	O(n+a-1) <sup>Note</sup>	O(82-a-n)	O(80-n+1) <sup>Note</sup>	
0	0	0	0	0	1	O <sub>1</sub>	→ O <sub>80</sub>	O <sub>1</sub>	→ O <sub>80</sub>	Other settings prohibited
0	0	0	0	1	2					

**Note** a = 80 at 1/80 duty

**Caution** When the μPD161401 is used in 1/80 duty, set the COM scan address setting register (R21) to CSA4, CSA3, CSA2, CSA1, CSA0 = 0, 0, 0, 0, 0. If any other settings are made, the μPD161401 operation is not guaranteed.

**Default value (default value of reset command)**

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	<b>Note</b>	<b>Note</b>	0	0	0	0	0

**Note** 0 or 1

### 6.18 Sub-duty Start Address Register (R22)

The sub-duty start address register specifies the start address of the display RAM the CPU accesses to use the sub-duty display mode. The sub-duty display area starts from this start line address and consists of the number of lines specified by the sub-duty setting register (R17).

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1		SSA6	SSA5	SSA4	SSA3	SSA2	SSA1	SSA0

Table 6–15. Sub-duty Start Address Register

SSA6	SSA5	SSA4	SSA3	SSA2	SSA1	SSA0	Common
0	0	0	0	0	0	0	COM <sub>1</sub>
0	0	0	0	0	0	1	COM <sub>2</sub>
0	0	0	0	0	1	0	COM <sub>3</sub>
0	0	0	0	0	1	1	COM <sub>4</sub>
			⋮				⋮
1	0	0	1	1	0	1	COM <sub>78</sub>
1	0	0	1	1	1	0	COM <sub>79</sub>
1	0	0	1	1	1	1	COM <sub>80</sub>

Make sure that SSA (R22) and SDT (R17) have in the following relationship.

$$SSA_n + SDT_n \leq MDT \leq 4FH$$

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	0	0	0	0	0	0	0

**Note** 0 or 1

### 6.19 Scroll Fixed Area Position Register (R23)

This command specifies the display position of the scroll fixed area to upper or bottom of side in LCD panel.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1								FIXAHL

**Table 6–16. Scroll Fixed Position Register (R23)**

FIXAHL	Display Position
0	bottom
1	upper

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	Note	Note	Note	1

**Note** 0 or 1

### 6.20 Scroll Fixed Area Width Register (R27)

This register selects the width of the area to be fixed from 0, 16, 24, and 32 lines.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1							FIXAW1	FIXAW0

**Table 4–16. Scroll Fixed Area Width Register (R27)**

FIXAW1	FIXAW0	Fixed Area Width
0	0	0
0	1	16
1	0	24
1	1	32

Even if the screen display size is changed by the duty setting register (R14 and R17), FIXAW1 and FIXAW0 are not overwritten.

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	Note	Note	0	0

**Note** 0 or 1

## 6.21 Scroll Step Number Register (R31)

This register sets the number of scroll steps when the scroll function is used.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1		MST6	MST5	MST4	MST3	MST2	MST1	MST0

**Table 6–18. Scroll Step Number Register (R31)**

MST6	MST5	MST4	MST3	MST2	MST1	MST0	Number of Scroll Steps
0	0	0	0	0	0	0	0
0	0	0	0	0	0	1	1
0	0	0	0	0	1	0	2
0	0	0	0	0	1	1	3
			⋮				⋮
1	0	0	1	1	0	1	77
1	0	0	1	1	1	0	78
1	0	0	1	1	1	1	79
1	0	1	0	0	0	0	Other settings prohibited

**Caution** The relationship between the number of scroll steps and scroll fixed area width should be as follows.

**Number of scroll steps ≤ 79 – Scroll fixed area width**

If values exceeding the above condition are set, the operation is not guaranteed.

### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	0	0	0	0	0	0	0

**Note** 0 or 1

## 6.22 Blink/Reverse Setting Register (R37)

This register controls blink display or reverse display. Blink display is controlled by the BLD1 and BLD0 flags of this register, and reverse display is controlled by the INV flag, as shown in the table below.

The condition of each of the blink and reverse display areas is individually set by R38 to R50.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1					INV		BLD1	BLD0

**Table 6–19. Blink/Reverse Display Control**

INV	Display
0	Reverse display OFF
1	Reverse display ON

BLD1	Display
0	Specified-color blink display OFF
1	Specified-color blink display ON

BLD0	Display
0	Complementary-color blink display OFF
1	Complementary-color blink display ON

### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	0	Note	0	0

**Note** 0 or 1

## 6.23 Complementary Color Blink X Address Register (R38)

The complementary color blink X address register specifies the X address of the complementary color blink RAM the CPU accesses. This address is automatically incremented each time the complementary color blink data RAM is accessed.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1					CBX3	CBX2	CBX1	CBX0

### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	0	0	0	0

**Note** 0 or 1



## 6.24 Complementary Color Blink Start Line Address Register (R39)

The complementary color blink start line address register specifies the start line address the CPU accesses to use complementary color blinking display. The range of the complementary color blink lines is determined by this register and the complementary color blink end line address register.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1		CBS6	CBS5	CBS4	CBS3	CBS2	CBS1	CBS0	

CBS6 to CBS0	Sets a start line address
--------------	---------------------------

**Caution** Make sure that CBS [6:0] ≤ 4FH. If 4FH is exceeded, operation is not guaranteed.

### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	0	0	0	0	0	0	0

**Note** 0 or 1

## 6.25 Complementary Color Blink End Line Address Register (R40)

The complementary color blink end line address register specifies the end line address the CPU accesses to use complementary color blink display. The range of the complementary color blink lines is determined by this register and the complementary color blink start line address register.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1		CBE6	CBE5	CBE4	CBE3	CBE2	CBE1	CBE0	

CBE6 to CBE0	Sets an end line address
--------------	--------------------------

**Caution** Make sure that CBE [6:0] ≤ 4FH. If 4FH is exceeded, operation is not guaranteed.

### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	0	0	0	0	0	0	0

**Note** 0 or 1

### 6.26 Complementary Color Blink Data Memory Register (R41)

The complementary color blink data memory register is used to access the complementary color blink data RAM. If this register is accessed for write, data is directly written to the complementary color blink data RAM.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>

Data	Status
0	Normal
1	Complementary color blinking

#### Default value (default value of reset command, all data)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	Note	Note	Note	Note

**Note** 0 or 1

### 6.27 Specified Color Blink X Address Register (R42)

The specified color blink X address register specifies the X address of the specified color blinking RAM the CPU accesses. This address is automatically incremented each time the specified color blink data RAM is accessed.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1					SBX3	SBX2	SBX1	SBX0

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	0	0	0	0

**Note** 0 or 1

### 6.28 Specified Color Blink Start Line Address Register (R43)

The specified color blink start line address register specifies the start line address the CPU accesses to use specified color blinking display. The range of the specified color blink lines is determined by this register and the specified color blinking end line address register.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1		SBS6	SBS5	SBS4	SBS3	SBS2	SBS1	SBS0	

SBS6 to SBS0	Sets a start line address.
--------------	----------------------------

**Caution** Make sure that SBS [6:0] ≤ 4FH. If 4FH is exceeded, operation is not guaranteed.

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	0	0	0	0	0	0	0

**Note** 0 or 1

### 6.29 Specified Color Blink End Line Address Register (R44)

The specified color blink end line address register specifies the end line address the CPU accesses to use specified color blink display. The range of the specified color blink lines is determined by this register and the specified color blink start line address register.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1		SBE6	SBE5	SBE4	SBE3	SBE2	SBE1	SBE0	

SBE6 to SBE0	Sets an end line address.
--------------	---------------------------

**Caution** Make sure that SBE [6:0] ≤ 4FH. If 4FH is exceeded, operation is not guaranteed.

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
0	0	0	0	0	0	0	0

### 6.30 Specified Color Blink Data Memory Register (R45)

The specified color blink data memory register is used to access the specified color blink data RAM. If this register is accessed for write, data is directly written to the specified color blink data RAM.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>

Data	Status
0	Normal
1	Specified color blinking

#### Default value (default value of reset command, all data)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	Note	Note	Note	Note

**Note** 0 or 1

### 6.31 Specified Color Setting Register (R46)

This register sets specified color data when the specified color blink function is used. The data between this data and the display RAM data blinks in a specified color.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Remark
1	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	
	R			G			B		In 256-color mode

#### Default value (default value of reset command, all data)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
0	0	0	0	0	0	0	0

### 6.32 Reverse X Address Register (R47)

The reverse X address register specifies the X address of the reverse data RAM the CPU accesses. This address is incremented each time the reverse RAM has been accessed.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1					IVX3	IVX2	IVX1	IVX0

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	0	0	0	0

**Note** 0 or 1

### 6.33 Reverse Start Line Address Register (R48)

The reverse start line address register specifies start line address of the display RAM the CPU accesses for reverse display. The range of the reverse lines is determined by this register and the reverse end line address register.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1		IVS6	IVS5	IVS4	IVS3	IVS2	IVS1	IVS0

IVS6 to IVS0	Sets a start line address.
--------------	----------------------------

**Caution** Make sure that IVS [6:0] ≤ 4FH. If 4FH is exceeded, operation is not guaranteed.

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	0	0	0	0	0	0	0

**Note** 0 or 1

### 6.34 Reverse End Line Address Register (R49)

The reverse end line address register specifies the end line address of the display RAM the CPU accesses for reverse display. The range of the reverse lines is determined by this register and the reverse start line address register.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1		IVE6	IVE5	IVE4	IVE3	IVE2	IVE1	IVE0	

IVE6 to IVE0	Sets an end line address.
--------------	---------------------------

**Caution** Make sure that IVE [6:0] ≤ 4FH. If 4FH is exceeded, operation is not guaranteed.

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	0	0	0	0	0	0	0

**Note** 0 or 1

6.35 Reverse Data Memory Access Register (R50)

The reverse data memory access register is used to access the reverse data RAM. When this register is accessed for write, data is directly written to the reverse data RAM.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	

Data	Status
0	Normal
1	Reverse

Default value (default value of reset command, all data)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	Note	Note	Note	Note

Note 0 or 1

### 6.36 Power System Control Register 1 (R52)

This command sets the power system mode of the μPD161401.

RS	E /RD	R,W /WR	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1	1	0		TCS2	TCS1	TCS0	OP3	OP2	OP1	OP0

TCS2 to TCS0	These bits set the value that selects the temperature curve of the V <sub>REG</sub> voltage to a value shown in <b>Table 6–20</b> .
OP3 to OP0	These bits turn ON/OFF the booster circuit, reference voltage generator, control the voltage regulator circuit (V regulator circuit) and voltage follower circuit (V/F circuit). The functions controlled by these four-power control set command controlled by these 4 bits are listed in <b>Table 6–21</b> .

**Table 6–20. V<sub>REG</sub> Voltage Temperature Curve Value**

TCS2	TCS1	TCS0	Status	Temperature Gradient (unit: %/°C)	V <sub>REG</sub> (TYP.) (unit: V)
0	0	0	Internal power supply	–0.12	1.77
0	0	1		–0.13	1.69
0	1	0		–0.15	1.63
0	1	1		–0.17	1.59
1	X	X	When external reference power supply is used	–	–

**Table 6–21. Details of Control by Each Bit of Power System Control Register**

Item	Status	
	1	0
OP3 : Booster circuit control bit	ON	OFF
OP2 : Reference voltage generator control bit	ON	OFF
OP1 : Voltage regulator circuit (V regulator circuit) control bit	ON	OFF
OP0 : Voltage follower circuit (V/F circuit) control bit	ON	OFF

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	0	0	0	0	0	0	0

Note 0 or 1

### 6.37 Power System Control Register 2 (R53)

This command sets the power system mode of the μPD161401.

RS	E /RD	R,W /WR	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1	1	0	VRR3	VRR2	VRR1	VRR0	SVR3	SVR2	SVR1	SVR0	

VRR3 to VRR0	When the main duty display mode is used, the resistance ratio can be changed in 16 steps by the V <sub>LCD</sub> internal resistance ratio adjustment command. Four bits of the V <sub>LCD</sub> internal resistance ratio adjustment register set the reference value of (1 + R <sub>b</sub> /R <sub>a</sub> ) to the value shown in <b>Table 6-22</b> .
SVR3 to SVR0	When the sub-duty display mode is used, the resistance ratio can be changed in 16 steps by the V <sub>LCD</sub> internal resistance ratio adjustment command. Four bits of the V <sub>LCD</sub> internal resistance ratio adjustment register set the reference value of (1 + R <sub>b</sub> /R <sub>a</sub> ) to the value shown in <b>Table 6-22</b> .

**Table 6-22. VLCD Internal Resistance Ratio Adjustment Register**

Register				1 + R <sub>b</sub> /R <sub>a</sub>
VRR3	VRR2	VRR1	VRR0	
SVR3	SVR2	SVR1	SVR0	
0	0	0	0	3
0	0	0	1	4
0	0	1	0	5
0	0	1	1	6
0	1	0	0	7
0	1	0	1	8
0	1	1	0	9
0	1	1	1	10
1	0	0	0	11
1	0	0	1	12
1	0	1	0	13
1	0	1	1	14
1	1	0	0	15
1	1	0	1	16
1	1	1	0	17
1	1	1	1	18

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
0	0	0	0	0	0	0	0



### 6.38 Power System Control Register 3 (R54)

This command sets the bias value for main duty display and sub-duty display by the μPD161401.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1		BIS2	BIS1	BIS0		SBIS2	SBIS1	SBIS0	

BIS2 to BIS0 <sup>Note</sup>	These flags select the bias ratio in the main duty display mode as follows:			
	BIS2	BIS1	BIS0	Bias Ratio
	0	0	0	1/9 bias
	0	0	1	1/8 bias
	0	1	0	1/7 bias
	0	1	1	1/6 bias
	1	0	0	1/5 bias
	1	0	1	Prohibited
	1	1	0	Prohibited
	1	1	1	Prohibited
SBIS2 to SBIS0 <sup>Note</sup>	These flags select the bias ratio in the sub-duty display mode as follows:			
	SBIS2	SBIS1	SBIS0	Bias Ratio
	0	0	0	1/9 bias
	0	0	1	1/8 bias
	0	1	0	1/7 bias
	0	1	1	1/6 bias
	1	0	0	1/5 bias
	1	0	1	Prohibited
	1	1	0	Prohibited
	1	1	1	Prohibited

**Note** Before changing these flags, execute the HALT command.

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	0	0	0	<b>Note</b>	0	0	0

**Note** 0 or 1

### 6.39 Power System Control Register 4 (R55)

This command sets the number of boosting steps for main duty display and sub-duty display of μPD161401 as shown in Table 6–23.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1		MBT2	MBT1	MBT0		SBT2	SBT1	SBT0	

**Table 6–23. Number of Boosting Steps for Main/Sub-duty Display of Booster Circuit**

MBT2	MBT1	MBT0	Number of Boosting Steps (unit: fold)
SBT2	SBT1	SBT0	
0	0	0	Two
0	0	1	Three
0	1	0	Four
0	1	1	Five
1	0	0	Six
1	0	1	Seven
1	1	0	Prohibited
1	1	1	Prohibited

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	0	0	0	Note	0	0	0

**Note** 0 or 1

#### 6.40 Power System Control Register 5 (R56)

This command sets the status of the voltage follower circuit of the μPD161401 that drives the LCD, as follows:

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1	LCS1	LCS0	LCC1	LCC0	HPM1	HPM0	PSM1	PSM0	

**Table 6–24. Setting of Segment Output Driving Capability (LCS1, LCS0 = 0, 0)**

LCS1	LCS0	Segment Output Driving Capability (unit: fold)
0	0	One
0	1	Two
1	0	Four
1	1	Eight

**Table 6–25. Setting of Common Output Driving Capability (LCS1, LCS0 = 0, 0)**

LCC1	LCC0	Common Output Driving Capability (unit: fold)
0	0	Two
0	1	Four
1	0	Eight
1	1	Sixteen

**Table 6–26. Setting of Operational Amplifier Operation Mode**

HPM1	HPM0	Mode Setting
0	0	Normal mode
0	1	Power ON mode1
1	0	Power OFF mode
1	1	Power ON mode2

**Table 6–27. Setting of Two-fold Supply Voltage (V<sub>LC3</sub>, V<sub>LC4</sub> Level Voltage Follower Power Supply)**

PSM1	Mode Setting
0	Not used
1	used

**Table 6–28. Setting of Voltage Follower Bias Current**

PSM0	Bias Current Setting (unit: fold)
0	One
1	Two

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
0	0	0	1	0	0	1	0

**6.41 Main Electronic Volume Register (R57)**

The main electronic volume register specifies the electronic volume value for adjusting the contrast in the main duty display mode, in 128 steps.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1		MEV6	MEV5	MEV4	MEV3	MEV2	MEV1	MEV0	

**Default value (default value of reset command)**

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	0	0	0	0	0	0	0

**Note** 0 or 1

**6.42 Sub-electronic Volume Register (R58)**

The sub-electronic volume register specifies an electronic volume value for adjusting the contrast in the sub-duty display mode, in 128 steps.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
1		SEV6	SEV5	SEV4	SEV3	SEV2	SEV1	SEV0	

**Default value (default value of reset command)**

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	0	0	0	0	0	0	0

**Note** 0 or 1

### 6.43 RAM Test Mode Setting Register (R61)

The RAM test mode setting register directly writes the data of each display status to the display RAM as shown in **Table 6–29**.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1						RTS2	RTS1	RTS0

**Table 6–29. RAM Test Mode**

RTS2	RTS1	RTS0	Write Data
0	0	0	Normal operation
0	0	1	all [00000000] / pixel display
0	1	0	all [11111111] / pixel display
0	1	1	Checker pattern display of [00000000] / [11111111]
1	0	0	Vertical grayscale bar display
1	0	1	Horizontal grayscale bar display
1	1	0	Each color grayscale display
1	1	1	256-color display

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	Note	0	0	0

**Note** 0 or 1

### 6.44 Driving Mode Select Register (R64)

The FXOR flag of the drive mode select register controls the reversal of the LCD drive waveform between frames as shown in **Table 6–30**. Note that the reverse function is executed between frames regardless of the FXOR flag during sub-duty display.

RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
1					FXOR			

**Table 6–30. Driving Mode Select Register (R64)**

FXOR	Reversing Between Frames
0	OFF
1	ON

#### Default value (default value of reset command)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	Note	0	Note	Note	Note

**Note** 0 or 1

### 6.45 Main R Grayscale Data Registers (R65 to R72)

The main R grayscale data registers specify the grayscale level of the R output in the main duty display mode. By using these registers, grayscale display can be optimized.

Rx	Data	RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
R65	0, 0, 0	1				MRG4	MRG3	MRG2	MRG1	MRG0	
R66	0, 0, 1	1				MRG4	MRG3	MRG2	MRG1	MRG0	
R67	0, 1, 0	1				MRG4	MRG3	MRG2	MRG1	MRG0	
R68	0, 1, 1	1				MRG4	MRG3	MRG2	MRG1	MRG0	
R69	1, 0, 0	1				MRG4	MRG3	MRG2	MRG1	MRG0	
R70	1, 0, 1	1				MRG4	MRG3	MRG2	MRG1	MRG0	
R71	1, 1, 0	1				MRG4	MRG3	MRG2	MRG1	MRG0	
R72	1, 1, 1	1				MRG4	MRG3	MRG2	MRG1	MRG0	

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Grayscale Level
×	×	×	0	0	0	0	0	Level 0
×	×	×	0	0	0	0	1	Level 1
×	×	×	0	0	0	1	0	Level 2
×	×	×	0	0	0	1	1	Level 3
			⋮					⋮
×	×	×	0	1	1	1	1	Level 15
×	×	×	1	0	0	0	0	Level 16

**Default value (default value of reset command, common to all grayscale data registers)**

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
<b>Note</b>	<b>Note</b>	<b>Note</b>	0	0	0	0	0

**Note** 0 or 1

#### 6.46 Main G Grayscale Data Registers (R73 to R80)

The main G grayscale data registers specify the grayscale level of the G output in the main duty display mode. By using these registers, grayscale display can be optimized.

Rx	Data	RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
R73	0, 0, 0	1				MGG4	MGG3	MGG2	MGG1	MGG0	
R74	0, 0, 1	1				MGG4	MGG3	MGG2	MGG1	MGG0	
R75	0, 1, 0	1				MGG4	MGG3	MGG2	MGG1	MGG0	
R76	0, 1, 1	1				MGG4	MGG3	MGG2	MGG1	MGG0	
R77	1, 0, 0	1				MGG4	MGG3	MGG2	MGG1	MGG0	
R78	1, 0, 1	1				MGG4	MGG3	MGG2	MGG1	MGG0	
R79	1, 1, 0	1				MGG4	MGG3	MGG2	MGG1	MGG0	
R80	1, 1, 1	1				MGG4	MGG3	MGG2	MGG1	MGG0	

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Grayscale Level
×	×	×	0	0	0	0	0	Level 0
×	×	×	0	0	0	0	1	Level 1
×	×	×	0	0	0	1	0	Level 2
×	×	×	0	0	0	1	1	Level 3
			⋮					⋮
×	×	×	0	1	1	1	1	Level 15
×	×	×	1	0	0	0	0	Level 16

**Default value (default value of reset command, common to all grayscale data registers)**

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	0	0	0	0	0

**Note** 0 or 1

### 6.47 Main B Grayscale Data Registers (R81 to R84)

The main B grayscale data registers specify the grayscale level of the B output in the main duty display mode. By using these registers, grayscale display can be optimized.

Rx	Data	RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
R81	0, 0	1				MBG4	MBG3	MBG2	MBG1	MBG0	
R82	0, 1	1				MBG4	MBG3	MBG2	MBG1	MBG0	
R83	1, 0	1				MBG4	MBG3	MBG2	MBG1	MBG0	
R84	1, 1	1				MBG4	MBG3	MBG2	MBG1	MBG0	

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Grayscale Level
×	×	×	0	0	0	0	0	Level 0
×	×	×	0	0	0	0	1	Level 1
×	×	×	0	0	0	1	0	Level 2
×	×	×	0	0	0	1	1	Level 3
			⋮					⋮
×	×	×	0	1	1	1	1	Level 15
×	×	×	1	0	0	0	0	Level 16

**Default value (default value of reset command, common to all grayscale data registers)**

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	0	0	0	0	0

**Note** 0 or 1



#### 6.48 Sub R Grayscale Data Registers (R85 to R92)

The sub R grayscale data registers specify the grayscale level of the R output in the sub-duty display mode. By using these registers, grayscale display can be optimized.

Rx	Data	RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
R85	0, 0, 0	1				SRG4	SRG3	SRG2	SRG1	SRG0	
R86	0, 0, 1	1				SRG4	SRG3	SRG2	SRG1	SRG0	
R87	0, 1, 0	1				SRG4	SRG3	SRG2	SRG1	SRG0	
R88	0, 1, 1	1				SRG4	SRG3	SRG2	SRG1	SRG0	
R89	1, 0, 0	1				SRG4	SRG3	SRG2	SRG1	SRG0	
R90	1, 0, 1	1				SRG4	SRG3	SRG2	SRG1	SRG0	
R91	1, 1, 0	1				SRG4	SRG3	SRG2	SRG1	SRG0	
R92	1, 1, 1	1				SRG4	SRG3	SRG2	SRG1	SRG0	

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Grayscale Level
×	×	×	0	0	0	0	0	Level 0
×	×	×	0	0	0	0	1	Level 1
×	×	×	0	0	0	1	0	Level 2
×	×	×	0	0	0	1	1	Level 3
			⋮					⋮
×	×	×	0	1	1	1	1	Level 15
×	×	×	1	0	0	0	0	Level 16

Default value (default value of reset command, common to all grayscale data registers)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	0	0	0	0	0

**Note** 0 or 1

#### 6.49 Sub G Grayscale Data Registers (R93 to R100)

The sub G grayscale data registers specify the grayscale level of the G output in the sub-duty display mode. By using these registers, grayscale display can be optimized.

Rx	Data	RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
R93	0, 0, 0	1				SGG4	SGG3	SGG2	SGG1	SGG0	
R94	0, 0, 1	1				SGG4	SGG3	SGG2	SGG1	SGG0	
R95	0, 1, 0	1				SGG4	SGG3	SGG2	SGG1	SGG0	
R96	0, 1, 1	1				SGG4	SGG3	SGG2	SGG1	SGG0	
R97	1, 0, 0	1				SGG4	SGG3	SGG2	SGG1	SGG0	
R98	1, 0, 1	1				SGG4	SGG3	SGG2	SGG1	SGG0	
R99	1, 1, 0	1				SGG4	SGG3	SGG2	SGG1	SGG0	
R100	1, 1, 1	1				SGG4	SGG3	SGG2	SGG1	SGG0	

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Grayscale Level
×	×	×	0	0	0	0	0	Level 0
×	×	×	0	0	0	0	1	Level 1
×	×	×	0	0	0	1	0	Level 2
×	×	×	0	0	0	1	1	Level 3
			⋮					⋮
×	×	×	0	1	1	1	1	Level 15
×	×	×	1	0	0	0	0	Level 16

Default value (default value of reset command, common to all grayscale data registers)

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	0	0	0	0	0

**Note** 0 or 1

### 6.50 Sub B Grayscale Data Registers (R101 to R104)

The sub B grayscale data registers specify the grayscale level of the B output in the sub-duty display mode. By using these registers, grayscale display can be optimized.

Rx	Data	RS	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Setting
R101	0, 0	1				SBG4	SBG3	SBG2	SBG1	SBG0	
R102	0, 1	1				SBG4	SBG3	SBG2	SBG1	SBG0	
R103	1, 0	1				SBG4	SBG3	SBG2	SBG1	SBG0	
R104	1, 1	1				SBG4	SBG3	SBG2	SBG1	SBG0	

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	Grayscale Level
×	×	×	0	0	0	0	0	Level 0
×	×	×	0	0	0	0	1	Level 1
×	×	×	0	0	0	1	0	Level 2
×	×	×	0	0	0	1	1	Level 3
			⋮					⋮
×	×	×	0	1	1	1	1	Level 15
×	×	×	1	0	0	0	0	Level 16

**Default value (default value of reset command, common to all grayscale data registers)**

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
Note	Note	Note	0	0	0	0	0

**Note** 0 or 1

# 7. μPD161401 REGISTER LIST

(1/2)

CS	RS	Index Register								Register Name	R/W	Data Bit							
		6	5	4	3	2	1	0				7	6	5	4	3	2	1	0
1																			
0	0								IR	Index Register	W		IR6	IR5	IR4	IR3	IR2	IR1	IR0
0	1	0	0	0	0	0	0	0	R0	Control Register 1	R/W	TRON	WAS	COMF	DISP	STBY	HALT	ADC	COMR
0	1	0	0	0	0	0	0	1	R1	Control Register 2	R/W	FDM		BMOD		DTY	INC	XDIR	YDIR
0	1	0	0	0	0	0	1	0	R2										
0	1	0	0	0	0	0	1	1	R3	Reset Command	W								RES
0	1	0	0	0	0	1	0	0	R4	X Address Register	R/W		XA6	XA5	XA4	XA3	XA2	XA1	XA0
0	1	0	0	0	0	1	0	1	R5	Y Address Register	R/W		YA6	YA5	YA4	YA3	YA2	YA1	YA0
0	1	0	0	0	0	1	1	0	R6										
0	1	0	0	0	0	1	1	1	R7	MIN. X Address Register	R/W		XMN6	XMN5	XMN4	XMN3	XMN2	XMN1	XMN0
0	1	0	0	0	1	0	0	0	R8	MAX. X Address Register	R/W		XMx6	XMx5	XMx4	XMx3	XMx2	XMx1	XMx0
0	1	0	0	0	1	0	0	1	R9	MIN. Y Address Register	R/W		YMN6	YMN5	YMN4	YMN3	YMN2	YMN1	YMN0
0	1	0	0	0	1	0	1	0	R10	MAX. Y Address Register	R/W		YMX6	YMX5	YMX4	YMX3	YMX2	YMX1	YMX0
0	1	0	0	0	1	0	1	1	R11										
0	1	0	0	0	1	1	0	0	R12	Display Memory Access Register	W	D15 D7	D14 D6	D13 D5	D15 D4	D11 D3	D10 D2	D9 D1	D8 D0
0	1	0	0	0	1	1	0	1	R13										
0	1	0	0	0	1	1	1	0	R14	Main Duty Setting Register	R/W		MDT6	MDT5	MDT4	MDT3	MDT2	MDT1	MDT0
0	1	0	0	0	1	1	1	1	R15	Main Duty N-line Inversion Register	R/W		MID5	MID4	MID3	MID2	MID1	MID0	
0	1	0	0	1	0	0	0	0	R16	Main Duty M-line Shift Register	R/W		MSD5	MSD4	MSD3	MSD2	MSD1	MSD0	
0	1	0	0	1	0	0	0	1	R17	Sub-duty Setting Register	R/W		SDT6	SDT5	SDT4	SDT3	SDT2	SDT1	SDT0
0	1	0	0	1	0	0	1	0	R18	Sub-duty N-line Inversion Register	R/W		SID5	SID4	SID3	SID2	SID1	SID0	
0	1	0	0	1	0	0	1	1	R19	Sub-duty M-line Shift Register	R/W		SSD5	SSD4	SSD3	SSD2	SSD1	SSD0	
0	1	0	0	1	0	1	0	0	R20										
0	1	0	0	1	0	1	0	1	R21	COM Scanning Address Setting Register	R/W				CSA4	CSA3	CSA2	CSA1	CSA0
0	1	0	0	1	0	1	1	0	R22	Sub-duty Start Address Register	R/W		SSA6	SSA5	SSA4	SSA3	SSA2	SSA1	SSA0
0	1	0	0	1	0	1	1	1	R23	Scroll Fixed Area Position Register	R/W								FIXAHL
0	1	0	0	1	1	0	0	0	R24										
0	1	0	0	1	1	0	0	1	R25										
0	1	0	0	1	1	0	1	0	R26										
0	1	0	0	1	1	0	1	1	R27	Scroll Fixed Area Width Register	R/W						FIXAW1	FIXAW0	
0	1	0	0	1	1	1	0	0	R28										
0	1	0	0	1	1	1	0	1	R29										
0	1	0	0	1	1	1	1	0	R30										
0	1	0	0	1	1	1	1	1	R31	Scroll Step Number Register	R/W		MST6	MST5	MST4	MST3	MST2	MST1	MST0
0	1	0	1	0	0	0	0	0	R32										
0	1	0	1	0	0	0	0	1	R33										
0	1	0	1	0	0	0	1	0	R34										
0	1	0	1	0	0	0	1	1	R35										
0	1	0	1	0	0	1	0	0	R36										
0	1	0	1	0	0	1	0	1	R37	Blink/Reverse Setting Register	R/W					INV		BLD1	BLD0
0	1	0	1	0	0	1	1	0	R38	Complementary Color Blink X Address Register	R/W					CBX3	CBX2	CBX1	CBX0
0	1	0	1	0	0	1	1	1	R39	Complementary Color Blink Start Line Address Register	R/W		CBS6	CBS5	CBS4	CBS3	CBS2	CBS1	CBS0
0	1	0	1	0	1	0	0	0	R40	Complementary Color Blink End Line Address Register	R/W		CBE6	CBE5	CBE4	CBE3	CBE2	CBE1	CBE0
0	1	0	1	0	1	0	0	1	R41	Complementary Color Blink Data Memory Register	W	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	0	1	0	1	0	R42	Specified Color Blinking X Address Register	R/W					SBX3	SBX2	SBX1	SBX0
0	1	0	1	0	1	0	1	1	R43	Specified Color Blink Start Line Address Register	R/W		SBS6	SBS5	SBS4	SBS3	SBS2	SBS1	SBS0
0	1	0	1	0	1	1	0	0	R44	Specified Color Blink End Line Address Register	R/W		SBE6	SBE5	SBE4	SBE3	SBE2	SBE1	SBE0
0	1	0	1	0	1	1	0	1	R45	Specified Color Blink Data Memory Register	W	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	0	1	1	1	0	R46	Specified Color Setting Register	R/W	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	0	1	1	1	1	R47	Reverse X Address Register	R/W					IVX3	IVX2	IVX1	IVX0
0	1	0	1	1	0	0	0	0	R48	Reverse Start Line Address Register	R/W		IVS6	IVS5	IVS4	IVS3	IVS2	IVS1	IVS0
0	1	0	1	1	0	0	0	1	R49	Reverse End Line Address Register	R/W		IVE6	IVE5	IVE4	IVE3	IVE2	IVE1	IVE0
0	1	0	1	1	0	0	1	0	R50	Reverse Data Memory Access Register	W	D7	D6	D5	D4	D3	D2	D1	D0
0	1	0	1	1	0	0	1	1	R51										
0	1	0	1	1	0	1	0	0	R52	Power System Control Register 1	R/W		TCS2	TCS1	TCS0	OP3	OP2	OP1	OP0
0	1	0	1	1	0	1	0	1	R53	Power System Control Register 2	R/W	VRR3	VRR2	VRR1	VRR0	SVR3	SVR2	SVR1	SVR0
0	1	0	1	1	0	1	1	0	R54	Power System Control Register 3	R/W		BIS2	BIS1	BIS0		SBS2	SBS1	SBS0
0	1	0	1	1	0	1	1	1	R55	Power System Control Register 4	R/W		MBT2	MBT1	MBT0		SBT2	SBT1	SBT0
0	1	0	1	1	1	0	0	0	R56	Power System Control Register 5	R/W	LCS1	LCS0	LCC1	LCC0	HPM1	HPM0	PSM1	PSM0
0	1	0	1	1	1	0	0	1	R57	Main Electronic Volume Register	R/W		MEV6	MEV5	MEV4	MEV3	MEV2	MEV1	MEV0
0	1	0	1	1	1	0	1	0	R58	Sub-electronic Volume Register	R/W		SEV6	SEV5	SEV4	SEV3	SEV2	SEV1	SEV0
0	1	0	1	1	1	0	1	1	R59										
0	1	0	1	1	1	1	0	0	R60										
0	1	0	1	1	1	1	0	1	R61	RAM Test Mode Setting Register	R/W						RTS2	RST1	RST0
0	1	0	1	1	1	1	1	0	R62										
0	1	0	1	1	1	1	1	1	R63										

(2/2)

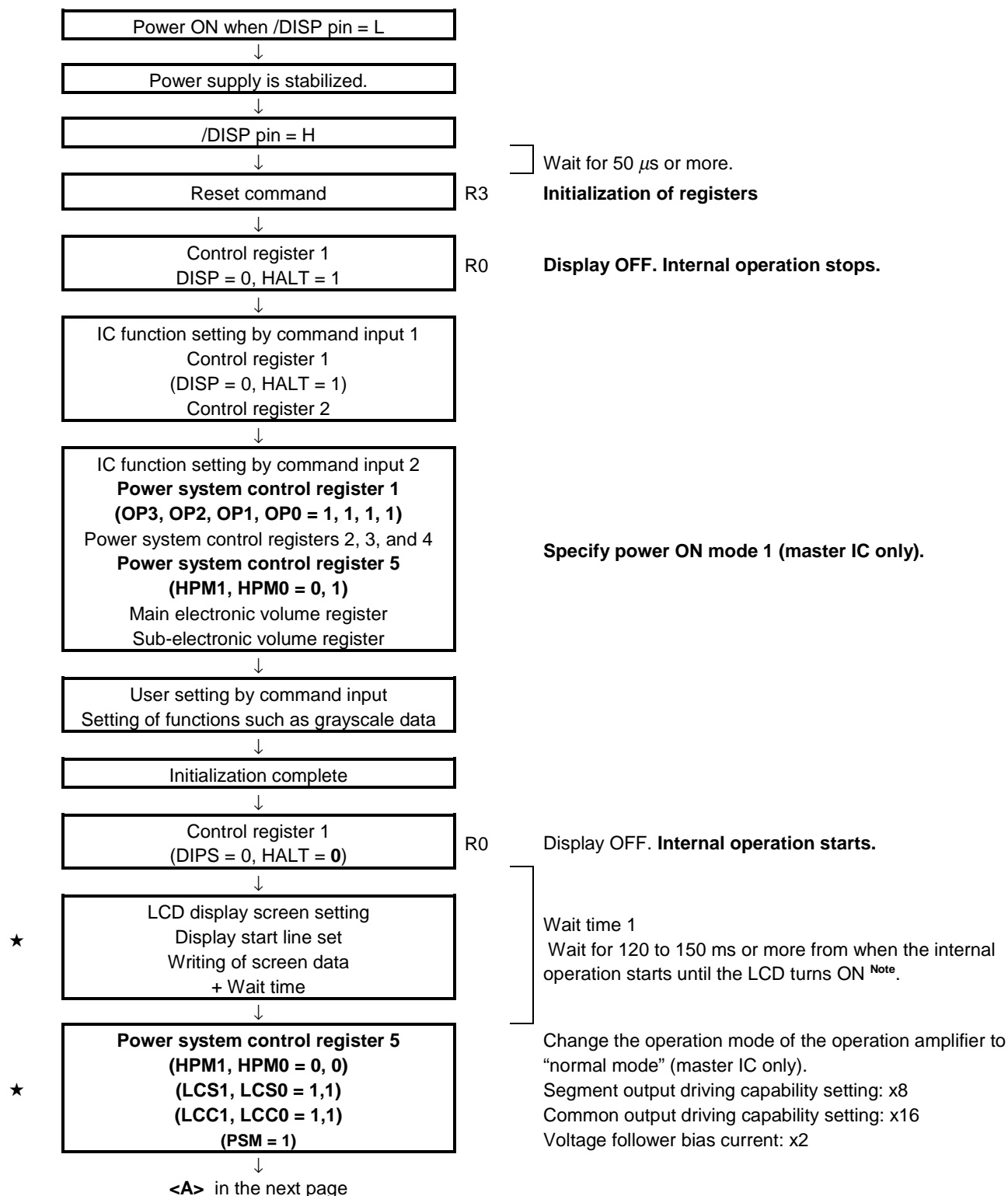
CS	RS	Index Register							Register Name	R/W	Data Bit							
		6	5	4	3	2	1	0			7	6	5	4	3	2	1	0
1																		
0	0								IR									
0	1	1	0	0	0	0	0	0	R64	Driving Mode Select Register					FXOR			
0	1	1	0	0	0	0	0	1	R65	Main R Grayscale Data Register 1 (0, 0, 0)				MRG4	MRG3	MRG2	MRG1	MRG0
0	1	1	0	0	0	0	1	0	R66	Main R Grayscale Data Register 2 (0, 0, 1)				MRG4	MRG3	MRG2	MRG1	MRG0
0	1	1	0	0	0	0	1	1	R67	Main R Grayscale Data Register 3 (0, 1, 0)				MRG4	MRG3	MRG2	MRG1	MRG0
0	1	1	0	0	0	1	0	0	R68	Main R Grayscale Data Register 4 (0, 1, 1)				MRG4	MRG3	MRG2	MRG1	MRG0
0	1	1	0	0	0	1	0	1	R69	Main R Grayscale Data Register 5 (1, 0, 0)				MRG4	MRG3	MRG2	MRG1	MRG0
0	1	1	0	0	0	1	1	0	R70	Main R Grayscale Data Register 6 (1, 0, 1)				MRG4	MRG3	MRG2	MRG1	MRG0
0	1	1	0	0	0	1	1	1	R71	Main R Grayscale Data Register 7 (1, 1, 0)				MRG4	MRG3	MRG2	MRG1	MRG0
0	1	1	0	0	1	0	0	0	R72	Main R Grayscale Data Register 8 (1, 1, 1)				MRG4	MRG3	MRG2	MRG1	MRG0
0	1	1	0	0	1	0	0	1	R73	Main G Grayscale Data Register 1 (0, 0, 0)				MGG4	MGG3	MGG2	MGG1	MGG0
0	1	1	0	0	1	0	1	0	R74	Main G Grayscale Data Register 2 (0, 0, 1)				MGG4	MGG3	MGG2	MGG1	MGG0
0	1	1	0	0	1	0	1	1	R75	Main G Grayscale Data Register 3 (0, 1, 0)				MGG4	MGG3	MGG2	MGG1	MGG0
0	1	1	0	0	1	1	0	0	R76	Main G Grayscale Data Register 4 (0, 1, 1)				MGG4	MGG3	MGG2	MGG1	MGG0
0	1	1	0	0	1	1	0	1	R77	Main G Grayscale Data Register 5 (1, 0, 0)				MGG4	MGG3	MGG2	MGG1	MGG0
0	1	1	0	0	1	1	1	0	R78	Main G Grayscale Data Register 6 (1, 0, 1)				MGG4	MGG3	MGG2	MGG1	MGG0
0	1	1	0	0	1	1	1	1	R79	Main G Grayscale Data Register 7 (1, 1, 0)				MGG4	MGG3	MGG2	MGG1	MGG0
0	1	1	0	1	0	0	0	0	R80	Main G Grayscale Data Register 8 (1, 1, 1)				MGG4	MGG3	MGG2	MGG1	MGG0
0	1	1	0	1	0	0	0	1	R81	Main B Grayscale Data Register 1 (0, 0)				MBG4	MBG3	MBG2	MBG1	MBG0
0	1	1	0	1	0	0	1	0	R82	Main B Grayscale Data Register 2 (0, 1)				MBG4	MBG3	MBG2	MBG1	MBG0
0	1	1	0	1	0	0	1	1	R83	Main B Grayscale Data Register 3 (1, 0)				MBG4	MBG3	MBG2	MBG1	MBG0
0	1	1	0	1	0	1	0	0	R84	Main B Grayscale Data Register 4 (1, 1)				MBG4	MBG3	MBG2	MBG1	MBG0
0	1	1	0	1	0	1	0	1	R85	Sub R Grayscale Data Register 1 (0, 0, 0)				SRG4	SRG3	SRG2	SRG1	SRG0
0	1	1	0	1	0	1	1	0	R86	Sub R Grayscale Data Register 2 (0, 0, 1)				SRG4	SRG3	SRG2	SRG1	SRG0
0	1	1	0	1	0	1	1	1	R87	Sub R Grayscale Data Register 3 (0, 1, 0)				SRG4	SRG3	SRG2	SRG1	SRG0
0	1	1	0	1	1	0	0	0	R88	Sub R Grayscale Data Register 4 (0, 1, 1)				SRG4	SRG3	SRG2	SRG1	SRG0
0	1	1	0	1	1	0	0	1	R89	Sub R Grayscale Data Register 5 (1, 0, 0)				SRG4	SRG3	SRG2	SRG1	SRG0
0	1	1	0	1	1	0	1	0	R90	Sub R Grayscale Data Register 6 (1, 0, 1)				SRG4	SRG3	SRG2	SRG1	SRG0
0	1	1	0	1	1	0	1	1	R91	Sub R Grayscale Data Register 7 (1, 1, 0)				SRG4	SRG3	SRG2	SRG1	SRG0
0	1	1	0	1	1	1	0	0	R92	Sub R Grayscale Data Register 8 (1, 1, 1)				SRG4	SRG3	SRG2	SRG1	SRG0
0	1	1	0	1	1	1	0	1	R93	Sub G Grayscale Data Register 1 (0, 0, 0)				SGG4	SGG3	SGG2	SGG1	SGG0
0	1	1	0	1	1	1	1	0	R94	Sub G Grayscale Data Register 2 (0, 0, 1)				SGG4	SGG3	SGG2	SGG1	SGG0
0	1	1	0	1	1	1	1	1	R95	Sub G Grayscale Data Register 3 (0, 1, 0)				SGG4	SGG3	SGG2	SGG1	SGG0
0	1	1	1	0	0	0	0	0	R96	Sub G Grayscale Data Register 4 (0, 1, 1)				SGG4	SGG3	SGG2	SGG1	SGG0
0	1	1	1	0	0	0	0	1	R97	Sub G Grayscale Data Register 5 (1, 0, 0)				SGG4	SGG3	SGG2	SGG1	SGG0
0	1	1	1	0	0	0	1	0	R98	Sub G Grayscale Data Register 6 (1, 0, 1)				SGG4	SGG3	SGG2	SGG1	SGG0
0	1	1	1	0	0	0	1	1	R99	Sub G Grayscale Data Register 7 (1, 1, 0)				SGG4	SGG3	SGG2	SGG1	SGG0
0	1	1	1	0	0	1	0	0	R100	Sub G Grayscale Data Register 8 (1, 1, 1)				SGG4	SGG3	SGG2	SGG1	SGG0
0	1	1	1	0	0	1	0	1	R101	Sub B Grayscale Data Register 1 (0, 0)				SBG4	SBG3	SBG2	SBG1	SBG0
0	1	1	1	0	0	1	1	0	R102	Sub B Grayscale Data Register 2 (0, 1)				SBG4	SBG3	SBG2	SBG1	SBG0
0	1	1	1	0	0	1	1	1	R103	Sub B Grayscale Data Register 3 (1, 0)				SBG4	SBG3	SBG2	SBG1	SBG0
0	1	1	1	0	1	0	0	0	R104	Sub B Grayscale Data Register 4 (1, 1)				SBG4	SBG3	SBG2	SBG1	SBG0
0	1	1	1	0	1	0	0	1	R105									
0	1	1	1	0	1	0	1	0	R106									
0	1	1	1	0	1	0	1	1	R107									
0	1	1	1	0	1	1	0	0	R108									
0	1	1	1	0	1	1	0	1	R109									
0	1	1	1	0	1	1	1	0	R110									
0	1	1	1	0	1	1	1	1	R111									
0	1	1	1	1	0	0	0	0	R112									
0	1	1	1	1	0	0	0	1	R113									
0	1	1	1	1	0	0	1	0	R114									
0	1	1	1	1	0	0	1	1	R115									
0	1	1	1	1	0	1	0	0	R116									
0	1	1	1	1	0	1	0	1	R117									
0	1	1	1	1	0	1	1	0	R118									
0	1	1	1	1	0	1	1	1	R119									
0	1	1	1	1	1	0	0	0	R120									
0	1	1	1	1	1	0	0	1	R121									
0	1	1	1	1	1	0	1	0	R122									
0	1	1	1	1	1	0	1	1	R123									
0	1	1	1	1	1	1	0	0	R124									
0	1	1	1	1	1	1	0	1	R125									
0	1	1	1	1	1	1	1	0	R126									
0	1	1	1	1	1	1	1	1	R127									

## 8. POWER SEQUENCE

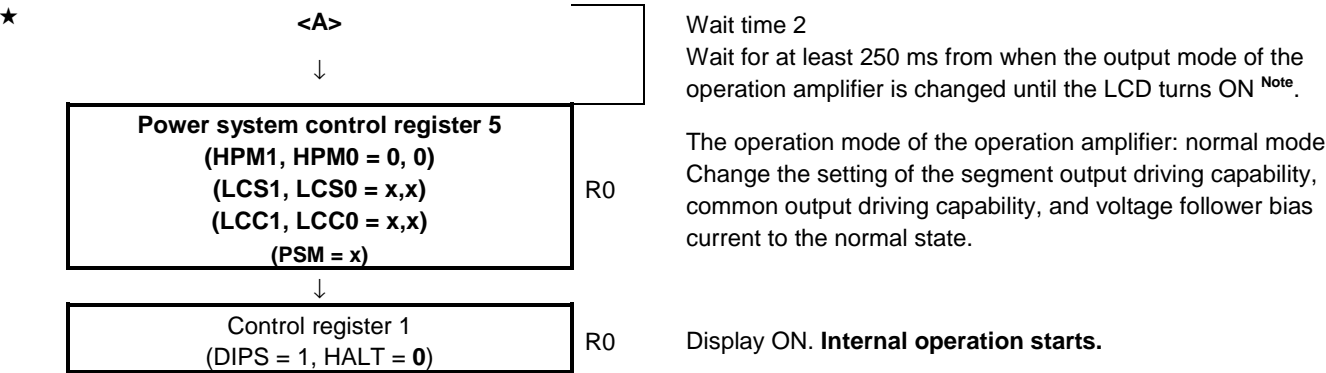
The  $\mu$ PD161401 has on-chip power circuits such as a booster circuit and a voltage follower circuit. Resetting by the /DISP pin should only be used to prevent malfunctioning due to noise.

If charge remains in the smoothing capacitor connected between the LCD drive pins ( $V_{LCD}$ ,  $V_{LC1}$  to  $V_{LC4}$ ) and  $V_{SS}$ , the display screen may momentarily blackout when power is turned ON or OFF. It is therefore recommended to turn ON/OFF power in the following sequence to avoid any trouble.

# 8.1 Power ON Sequence (with Internal Power Supply, Power ON → Display ON)

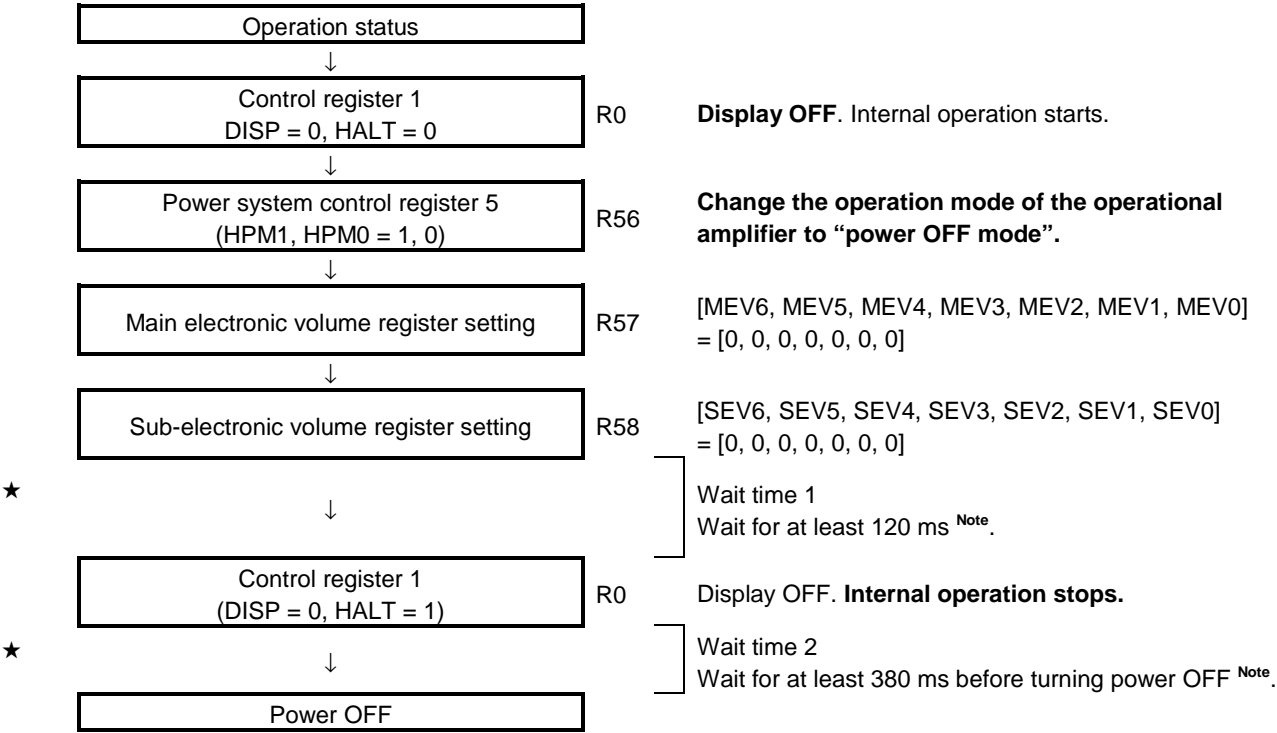


**Note** The wait times1, 2 vary depending on the characteristics of the LCD panel and the capacitance of the boosting or smoothing capacitor. It is recommended to determine this value after thorough evaluation with the actual system (refer to 8.5 Flow of V<sub>OUT</sub> and V<sub>LCD</sub> Voltages from Power ON to Power OFF).





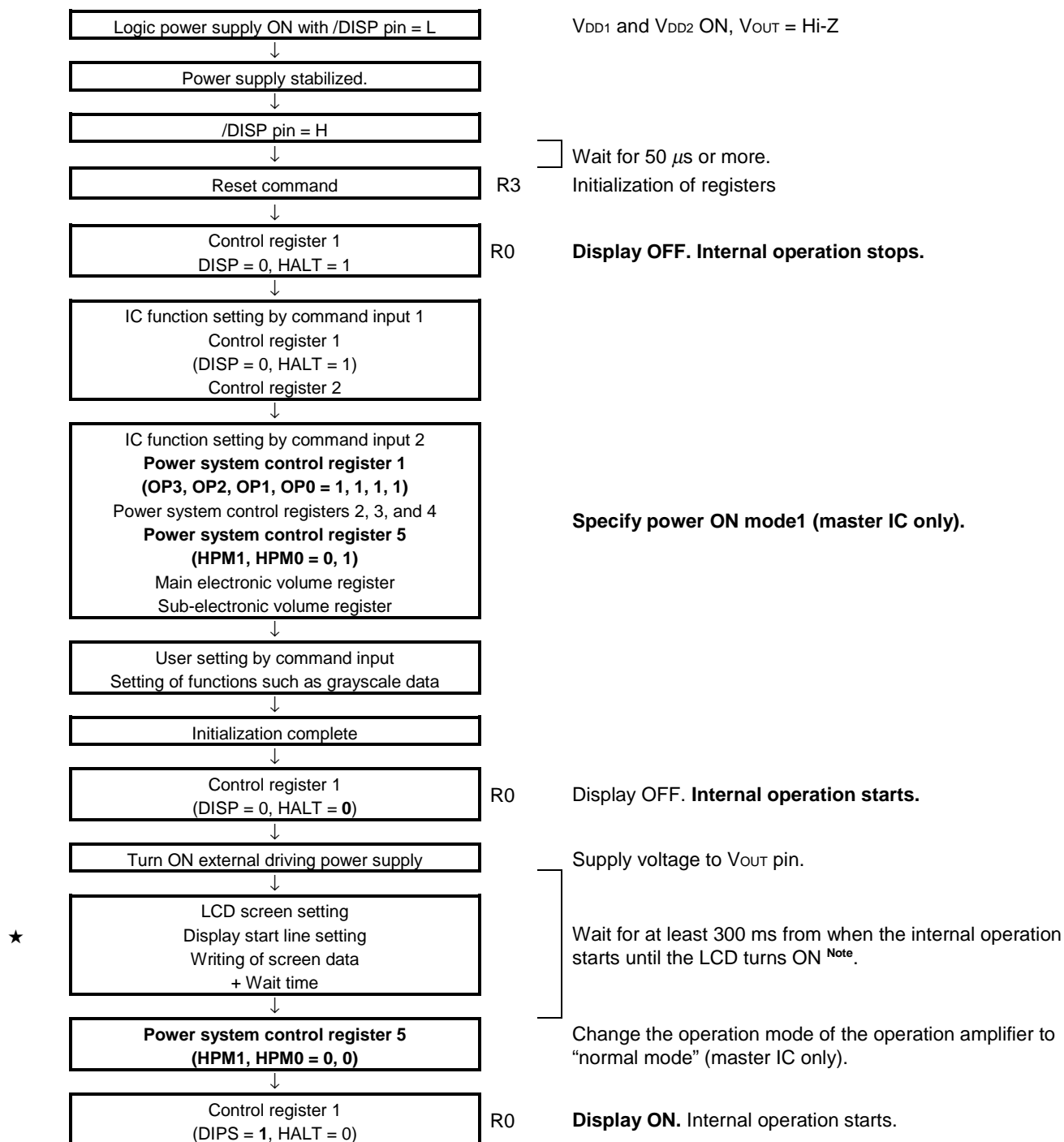
8.2 Power OFF Sequence (with Internal Power Supply)



**Note** The wait times 1, 2 vary depending on the characteristics of the LCD panel and the capacitance of the boosting or smoothing capacitor. It is recommended to determine this value after thorough evaluation with the actual system (refer to **8.5 Flow of V<sub>OUT</sub> and V<sub>LCD</sub> Voltages from Power ON to Power OFF**).

### 8.3 Power ON Sequence (with External Driving Power Supply, Power ON → Display ON)

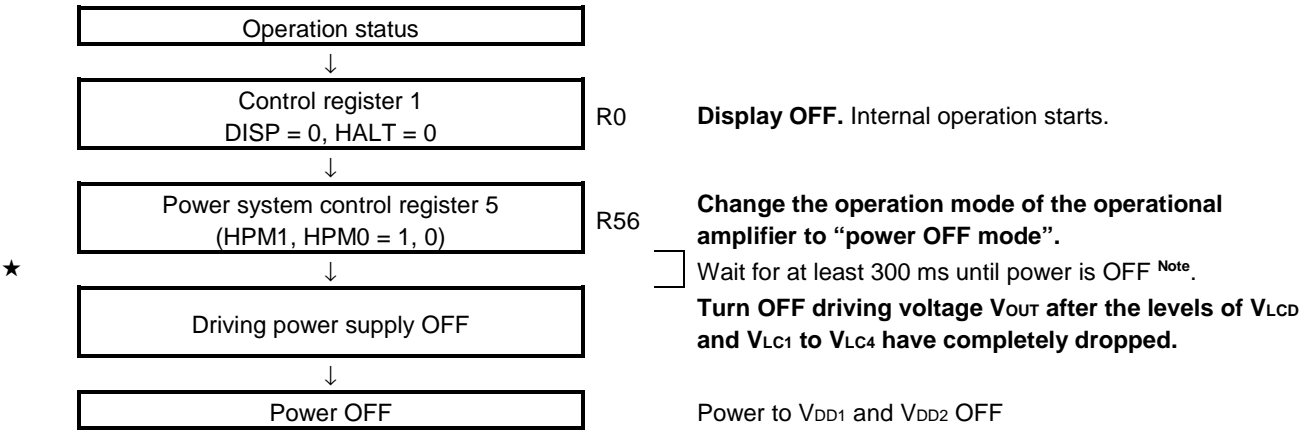
This is an example of inputting a reference voltage to the  $V_{RS}$  pin and a driving voltage to the  $V_{OUT}$  pin from an external power supply.



**Note** The time of 300 ms varies depending on the characteristics of the LCD panel and the capacitance of the smoothing capacitor. It is recommended to determine this value after thorough evaluation with the actual system (refer to **8.5 Flow of V<sub>OUT</sub> and V<sub>LCD</sub> Voltages from Power ON to Power OFF**).

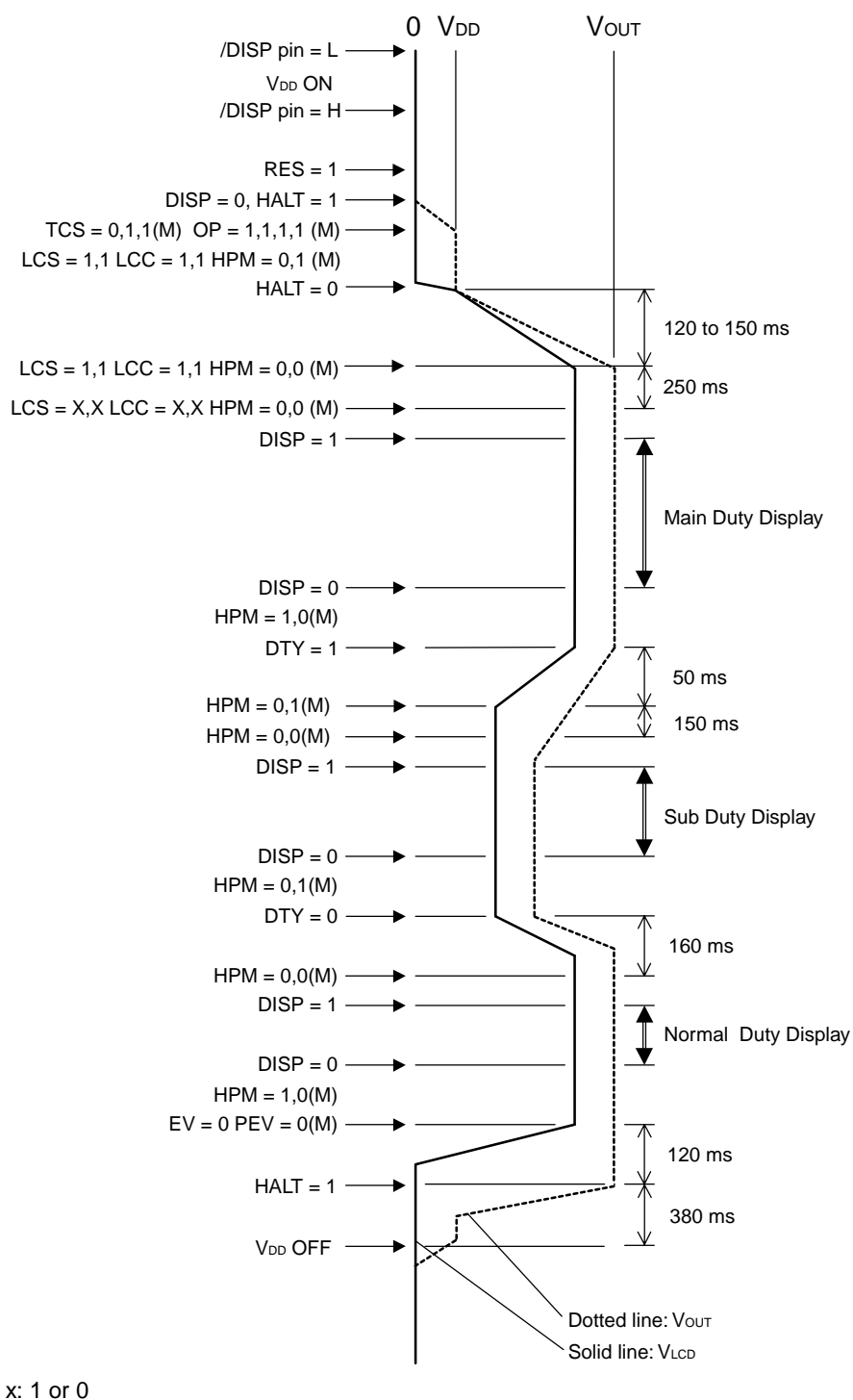
8.4 Power OFF Sequence (with External Driving Power Supply)

This is an example of inputting a reference voltage to the V<sub>RS</sub> pin and a driving voltage to the V<sub>OUT</sub> pin from an external power supply.



**Note** The time of 300 ms varies depending on the characteristics of the LCD panel and the capacitance of the smoothing capacitor. It is recommended to determine this value after thorough evaluation with the actual system (refer to 8.5 Flow of V<sub>OUT</sub> and V<sub>LCD</sub> Voltages from Power ON to Power OFF).

★ 8.5 Flow of  $V_{OUT}$  and  $V_{LCD}$  Voltages from Power ON to Power OFF



x: 1 or 0

**Test conditions:**

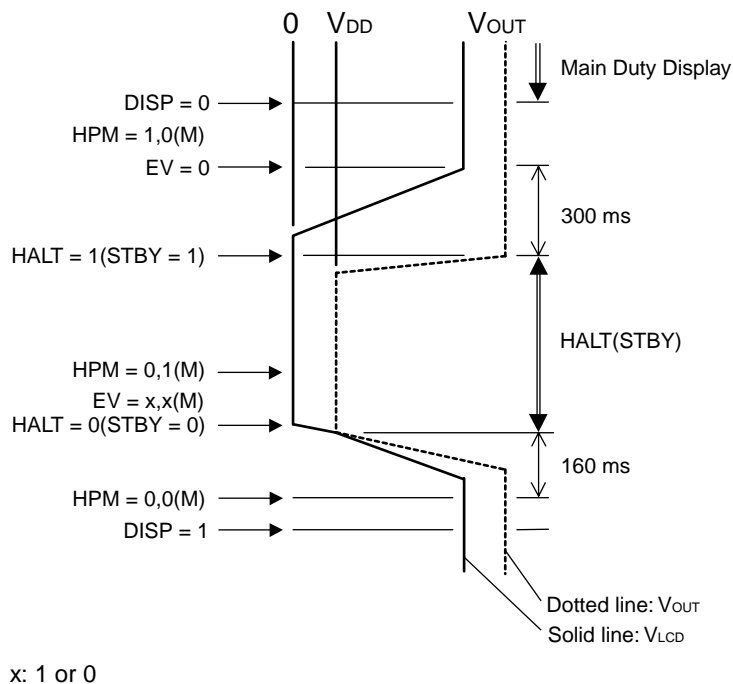
Supply voltage:  $V_{DD1} = V_{DD2} = 3.0 \text{ V}$

Number of boosting stages: x5 (in normal display mode), x3 (in partial display mode)

Capacitance: Between  $V_{LCh}$  pin and  $C_n^{+/-}$  pins =  $1.0 \mu\text{F}$

**Caution** Connect a capacitor of  $0.1 \mu\text{F}$  or less to the AMP<sub>OUTM</sub> and AMP<sub>OUTS</sub> pins.

★ 8.6 Flow of  $V_{OUT}$  and  $V_{LCD}$  Voltages in Display Output and HALT/Standby Modes



**Test conditions:**

Supply voltage:  $V_{DD1} = V_{DD2} = 3.0\text{ V}$ .

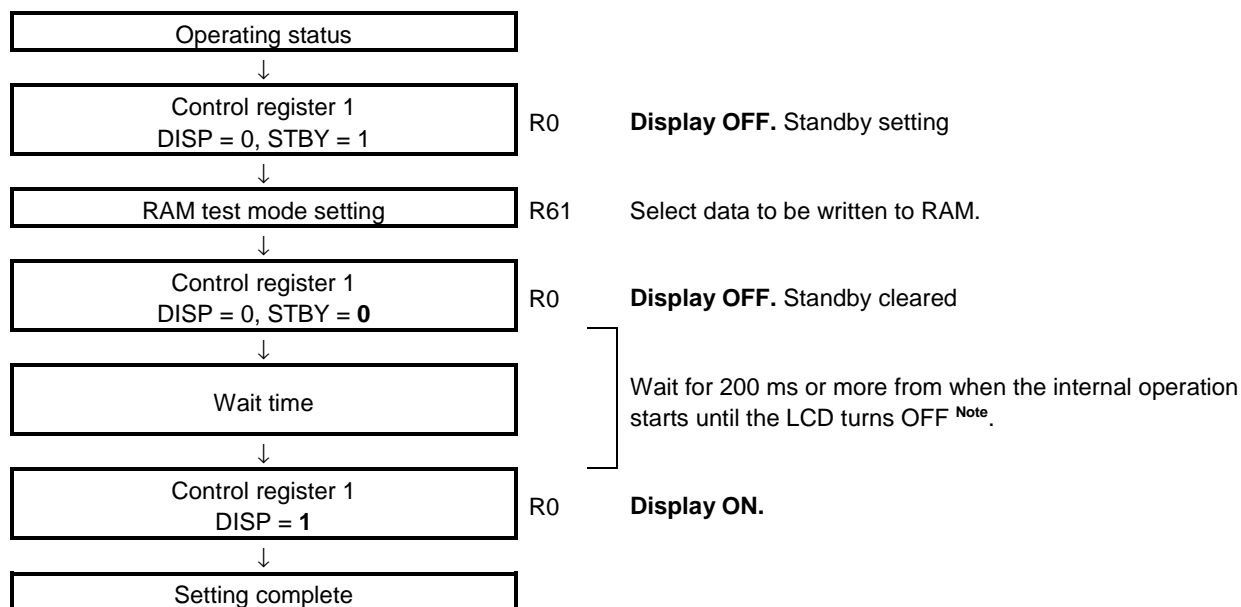
Number of boosting stages: x5 (in normal display mode), x3 (in partial display mode)

Capacitance: Between  $V_{LCn}$  pin and  $C_n^{+/-}$  pins =  $1.0\text{ }\mu\text{F}$

**Caution** Connect a capacitor of  $0.1\text{ }\mu\text{F}$  or less to the  $AMP_{OUTM}$  and  $AMP_{OUTS}$  pins.

## 9. USING RAM TEST MODE

The μPD161401 has a test mode in which seven types of screen data are written to the display RAM. When using this test mode, be sure to execute the following sequence. If the RAM test mode is executed in any other sequence, erroneous data may be displayed.



**Note** The time of 200 ms varies depending on the characteristics of the LCD panel and the capacitance of the boosting or smoothing capacitor. It is recommended to determine this value after thorough evaluation with the actual system.

**Remark** The set display data is always written to the display RAM in the RAM test mode.

## 10. ELECTRICAL SPECIFICATIONS

### Absolute Maximum Ratings ( $T_A = 25^\circ\text{C}$ , $V_{SS} = 0\text{ V}$ )

Parameter	Symbol	Ratings	Unit
Logic supply voltage	$V_{DD1}$	-0.3 to +4.0	V
Booster circuit supply voltage	$V_{DD2}$	-0.3 to +4.0	V
Driver supply voltage	$V_{OUT}$	-0.3 to +20.0	V
Driver reference power input voltage	$V_{LCD}, V_{LC1}$ to $V_{LC4}$	-0.3 to $V_{OUT} + 0.3$	V
Logic input voltage	$V_{IN1}$	-0.3 to $V_{DD1} + 0.3$	V
Logic output voltage	$V_{O1}$	-0.3 to $V_{DD1} + 0.3$	V
Logic I/O voltage	$V_{I/O1}$	-0.3 to $V_{DD1} + 0.3$	V
Driver input voltage	$V_{IN2}$	-0.3 to $V_{OUT} + 0.3$	V
Driver output voltage	$V_{O2}$	-0.3 to $V_{OUT} + 0.3$	V
Operating ambient temperature	$T_A$	-40 to +85	°C
Storage temperature	$T_{stg}$	-55 to +125	°C

**Caution** Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

### Recommended Operating Range

Parameter	Symbol	MIN.	TYP.	MAX.	Unit
Logic supply voltage	$V_{DD1}$	1.8		3.6	V
Booster circuit supply voltage	$V_{DD2}$ <sup>Note1</sup>	2.4		3.6	V
Driver supply voltage	$V_{OUT}$ <sup>Note2</sup>	5.5		18.0	V
Logic supply voltage	$V_{IN}$	0		$V_{DD1}$	V
Driver supply voltage	$V_{LCD},$ $V_{LC1}$ to $V_{LC4}$ <sup>Note2</sup>	0		$V_{OUT}$	V
Maximum LCD voltage setting range	$V_{LCD}$ <sup>Note3</sup>			$V_{OUT} - 0.5$	V

**Notes** 1. It is essential that  $V_{DD1} \leq V_{DD2}$ .

2. These conditions are recommended when the LCD is driven by an external power supply.
3. This condition is recommended when the LCD is driven by the internal power supply circuit.

**Cautions** 1. Make sure that the relationship of  $V_{SS} < V_{LC4} < V_{LC3} < V_{LC2} < V_{LC1} < V_{LCD} \leq V_{OUT}$  is satisfied when the LCD is driven by an external power supply.

2. Make sure that the condition described in 8. POWER SEQUENCE are satisfied when turning power ON or OFF.
3. Keep the voltage at the  $V_R$  and  $V_{RS}$  pins to between 1.0 V and  $V_{DD1}$  when an external resistor is used (when the internal resistor is not used to adjust  $V_{LCD}$ ).

**Electrical Specifications (Unless otherwise specified, T<sub>A</sub> = −40 to +85°C, V<sub>DD1</sub> = 1.8 to 3.6 V, V<sub>DD2</sub> = 2.4 to 3.6 V.)**

Parameter	Symbol	Conditions	MIN.	TYP. <sup>Notes1</sup>	MAX.	Unit
Input voltage, high	V <sub>IH</sub>		0.8 V <sub>DD1</sub>			V
Input voltage, low	V <sub>IL</sub>				0.2 V <sub>DD1</sub>	V
Input current, high	I <sub>IH1</sub>	Other than D <sub>15</sub> to D <sub>0</sub>			1	μA
Input current, low	I <sub>IL1</sub>	Other than D <sub>15</sub> to D <sub>0</sub>			−1	μA
Output voltage, high	V <sub>OH</sub>	I <sub>OUT</sub> = −1 mA. Other than OCS <sub>OUT</sub>	V <sub>DD1</sub> − 0.5			V
Output voltage, low	V <sub>OL</sub>	I <sub>OUT</sub> = 1 mA. Other than OCS <sub>OUT</sub>			0.5	V
Leakage current, high	I <sub>LOH</sub>	D <sub>15</sub> to D <sub>8</sub> , D <sub>7</sub> (SI), D <sub>6</sub> (SCL), D <sub>5</sub> to D <sub>0</sub> , V <sub>IN/OUT</sub> = V <sub>DD1</sub>			10	μA
Leakage current, low	I <sub>LOL</sub>	D <sub>15</sub> to D <sub>8</sub> , D <sub>7</sub> (SI), D <sub>6</sub> (SCL), D <sub>5</sub> to D <sub>0</sub> , V <sub>IN/OUT</sub> = V <sub>SS</sub>			−10	μA
Common output ON resistance	R <sub>COM</sub>	V <sub>LCn</sub> → COM <sub>n</sub> , V <sub>OUT</sub> = 15 V, V <sub>LCD</sub> = 13 V, 1/9 bias,  I <sub>O</sub>   = 50 μA			4	kΩ
Segment output ON resistance	R <sub>SEG</sub>	V <sub>LCn</sub> → SEG <sub>n</sub> , V <sub>OUT</sub> = 15 V, V <sub>LCD</sub> = 13 V, 1/9 bias,  I <sub>O</sub>   = 50 μA			4	kΩ
Driver voltage (booster voltage)	V <sub>OUT</sub>	In 5-fold mode, V <sub>DD2</sub> = 3.0 V, diced display	13.8			V
		In 6-fold mode, V <sub>DD2</sub> = 3.0 V, diced display	16.6			V
Regulated voltage <sup>Notes2</sup>	V <sub>REG</sub>	T <sub>A</sub> = 85°C. (TCS2, TCS1, TCS0) = (0, 1, 0) Temperature curve −0.15 %/°C	1.430	1.485	1.540	V
Output voltage deflection	ΔV <sub>LCn</sub>	V <sub>LCn</sub> : V <sub>LCD</sub> , V <sub>LC1</sub> to V <sub>LC4</sub> , (OP3, OP2, OP1, OP0) = (0, 0, 0, 1) V <sub>DD1</sub> = 2.5 V, V <sub>OUT</sub> = 15 V, AMP <sub>OUTM</sub> = 14 V, bias = 1/5 to 1/9, IRS pin = L, display OFF, no load	−50		50	mV
	ΔAMP <sub>OUT</sub>	IRS pin = H, 1+R <sub>b</sub> /R <sub>a</sub> = 10-fold	−100		100	mV
Oscillation frequency <sup>Notes3</sup>	f <sub>OSC</sub>	V <sub>DD1</sub> = 3.0 V, T <sub>A</sub> = 25°C, 1/80 duty, R = 360 kΩ (OSC <sub>IN1</sub> –OSC <sub>OUT</sub> )	72	85	97	kHz
		V <sub>DD1</sub> = 3.0 V, T <sub>A</sub> = 25°C, 1/38 duty, R = 770 kΩ (OSC <sub>IN2</sub> –OSC <sub>OUT</sub> )	33	40	46	kHz
Current consumption	I <sub>DD11</sub>	Frame frequency = 70 Hz, all PWM display output, 1/80 duty, V <sub>DD1</sub> = V <sub>DD2</sub> = 3.0 V, V <sub>LCD</sub> = 13 V, in 5-fold mode, driving mode (segment x 1, common x 4)		175	280	μA
		Frame frequency = 70 Hz, all PWM display output, 1/32 duty, V <sub>DD1</sub> = V <sub>DD2</sub> = 3.0 V, V <sub>LCD</sub> = 7.0 V, in 3-fold mode, driving mode (segment x 1, common x 4)		72	120	μA
Current consumption (standby mode)	I <sub>DD22</sub>	V <sub>DD1</sub> = V <sub>DD2</sub> = 3.0 V			10	μA

**Notes1** The TYP. values are reference values at T<sub>A</sub> = 25°C (except for regulated voltage (V<sub>REG</sub>)).

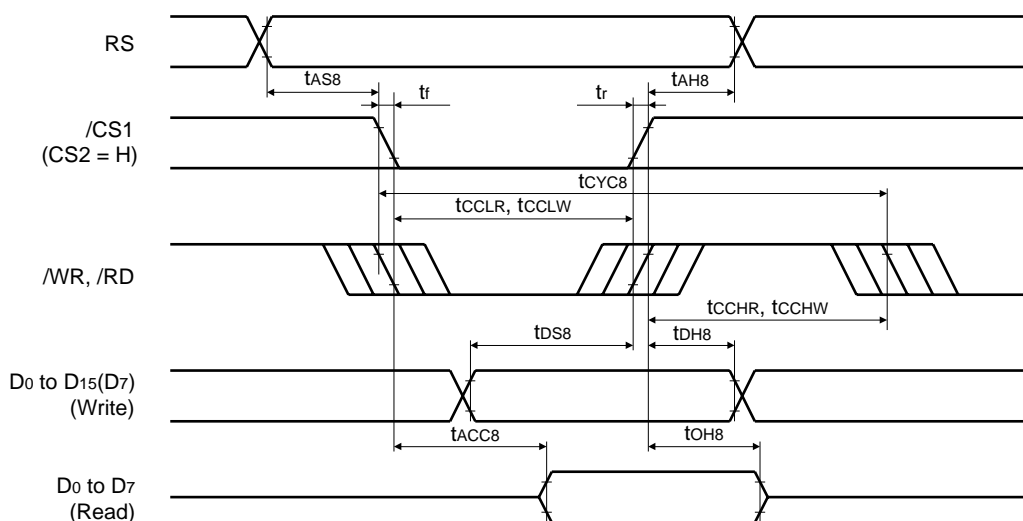
**2** The TYP. values of Regulated voltage (V<sub>REG</sub>) at T<sub>A</sub> = 25°C are MIN. 1.580 V, TYP. 1.635 V, MAX. 1.690 V

**3** Oscillation frequency is changed under the influence of the wiring capacity to the external resistor for oscillation.



Timing Requirements (Unless otherwise specified,  $T_A = -30$  to  $+85^\circ\text{C}$ .)

## (1) i80 CPU interface

(V<sub>DD1</sub> = 1.8 to 2.0 V)

Parameter	Symbol	Conditions	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
Address hold time	t <sub>AH8</sub>	RS	0			ns
Address setup time	t <sub>AS8</sub>	RS	0			ns
System cycle time	t <sub>CYC8</sub>		1000			ns
Control L pulse width (/WR)	t <sub>CCLW</sub>	/WR	160			ns
Control L pulse width (/RD)	t <sub>CCLR</sub>	/RD	430			ns
Control H pulse width (/WR)	t <sub>CCHW</sub>	/WR	160			ns
Control H pulse width (/RD)	t <sub>CCHR</sub>	/RD	160			ns
Data setup time	t <sub>DS8</sub>	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	160			ns
Data hold time	t <sub>DH8</sub>	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	0			ns
/RD access time	t <sub>ACC8</sub>	D <sub>0</sub> to D <sub>7</sub> , C <sub>L</sub> = 100 pF	0		470	ns
Output disable time	t <sub>OH8</sub>	D <sub>0</sub> to D <sub>7</sub> , C <sub>L</sub> = 5 pF, R <sub>L</sub> = 3 k $\Omega$	0		170	ns

**Note** The TYP. values are reference values at  $T_A = 25^\circ\text{C}$ .(V<sub>DD1</sub> = 2.0 to 2.5 V)

Parameter	Symbol	Conditions	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
Address hold time	t <sub>AH8</sub>	RS	0			ns
Address setup time	t <sub>AS8</sub>	RS	0			ns
System cycle time	t <sub>CYC8</sub>		600			ns
Control L pulse width (/WR)	t <sub>CCLW</sub>	/WR	120			ns
Control L pulse width (/RD)	t <sub>CCLR</sub>	/RD	240			ns
Control H pulse width (/WR)	t <sub>CCHW</sub>	/WR	120			ns
Control H pulse width (/RD)	t <sub>CCHR</sub>	/RD	120			ns
Data setup time	t <sub>DS8</sub>	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	120			ns
Data hold time	t <sub>DH8</sub>	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	0			ns
/RD access time	t <sub>ACC8</sub>	D <sub>0</sub> to D <sub>7</sub> , C <sub>L</sub> = 100 pF	0		280	ns
Output disable time	t <sub>OH8</sub>	D <sub>0</sub> to D <sub>7</sub> , C <sub>L</sub> = 5 pF, R <sub>L</sub> = 3 k $\Omega$	0		170	ns

**Note** The TYP. values are reference values at  $T_A = 25^\circ\text{C}$ .

(V<sub>DD1</sub> = 2.5 to 3.6 V)

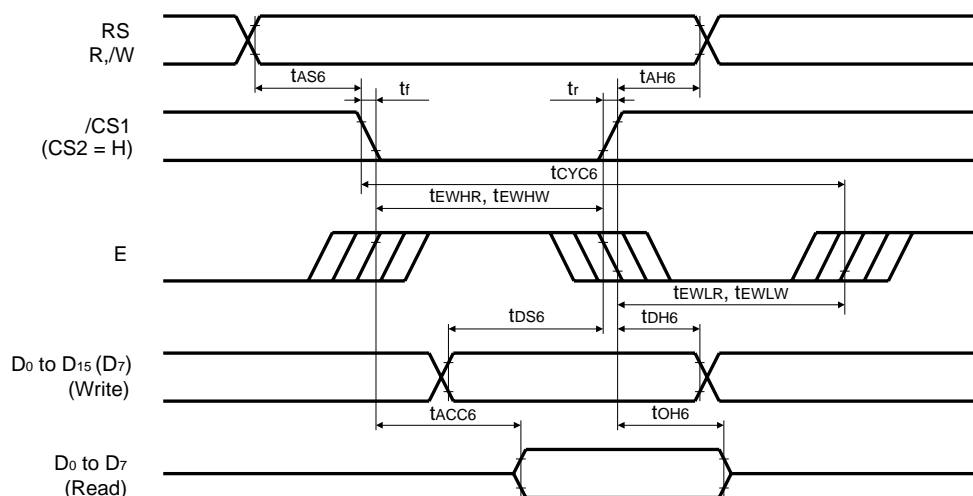
Parameter	Symbol	Conditions	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
Address hold time	t <sub>AH8</sub>	RS	0			ns
Address setup time	t <sub>AS8</sub>	RS	0			ns
System cycle time	t <sub>CYC8</sub>		100			ns
Control L pulse width (/WR)	t <sub>CCLW</sub>	/WR	40			ns
Control L pulse width (/RD)	t <sub>CCLR</sub>	/RD	40			ns
Control H pulse width (/WR)	t <sub>CCHW</sub>	/WR	40			ns
Control H pulse width (/RD)	t <sub>CCHR</sub>	/RD	40			ns
Data setup time	t <sub>DS8</sub>	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	40			ns
Data hold time	t <sub>DH8</sub>	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	0			ns
/RD access time	t <sub>ACC8</sub>	D <sub>0</sub> to D <sub>7</sub> , C <sub>L</sub> = 100 pF	0		50	ns
Output disable time	t <sub>OH8</sub>	D <sub>0</sub> to D <sub>7</sub> , C <sub>L</sub> = 5 pF, R <sub>L</sub> = 3 kΩ	0		50	ns

**Note** The TYP. values are reference values at T<sub>A</sub> = 25°C.

**Cautions 1. The rise and fall times (t<sub>r</sub> and t<sub>f</sub>) of an input signal are 10 ns or less.**

**2. All timing data is specified at 20% and 80% of V<sub>DD1</sub>.**

(2) M68 CPU interface



( $V_{DD1} = 1.8$  to  $2.0$  V)

Parameter	Symbol	Conditions	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
Address hold time	$t_{AH6}$	RS	0			ns
Address setup time	$t_{AS6}$	RS	0			ns
System cycle time	$t_{CYC6}$		1000			ns
Data setup time	$t_{DS6}$	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	160			ns
Data hold time	$t_{DH6}$	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	0			ns
Access time	$t_{ACC6}$	D <sub>0</sub> to D <sub>7</sub> , $C_L = 100$ pF	0		470	ns
Output disable time	$t_{OH6}$	D <sub>0</sub> to D <sub>7</sub> , $C_L = 5$ pF, $R = 3$ kΩ	0		170	ns
Enable H pulse width	Read	$t_{EWHR}$	430			ns
	Write	$t_{EWHW}$	160			ns
Enable L pulse width	Read	$t_{EWLR}$	160			ns
	Write	$t_{EWLW}$	160			ns

**Note** The TYP. values are reference values at  $T_A = 25^\circ\text{C}$ .

( $V_{DD1} = 2.0$  to  $2.5$  V)

Parameter	Symbol	Conditions	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
Address hold time	$t_{AH6}$	RS	0			ns
Address setup time	$t_{AS6}$	RS	0			ns
System cycle time	$t_{CYC6}$		600			ns
Data setup time	$t_{DS6}$	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	120			ns
Data hold time	$t_{DH6}$	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	0			ns
Access time	$t_{ACC6}$	D <sub>0</sub> to D <sub>7</sub> , $C_L = 100$ pF	0		280	ns
Output disable time	$t_{OH6}$	D <sub>0</sub> to D <sub>7</sub> , $C_L = 5$ pF, $R = 3$ kΩ	0		170	ns
Enable H pulse width	Read	$t_{EWHR}$	240			ns
	Write	$t_{EWHW}$	120			ns
Enable L pulse width	Read	$t_{EWLR}$	120			ns
	Write	$t_{EWLW}$	120			ns

**Note** The TYP. values are reference values at  $T_A = 25^\circ\text{C}$ .

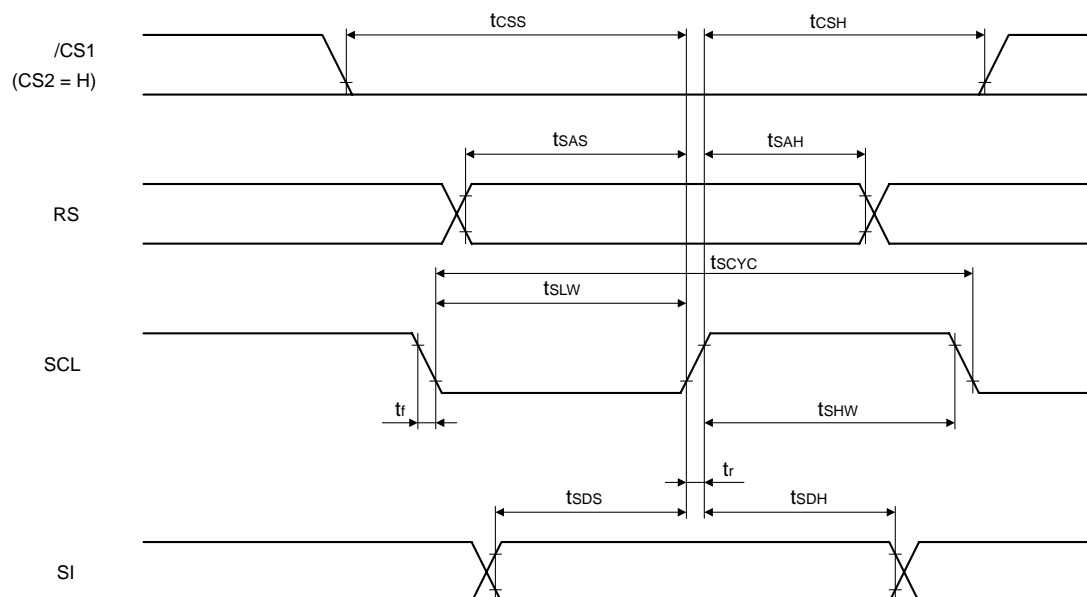
(V<sub>DD1</sub> = 2.5 to 3.6 V)

Parameter		Symbol	Conditions	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
Address hold time		t <sub>AH6</sub>	RS	0			ns
Address setup time		t <sub>AS6</sub>	RS	0			ns
System cycle time		t <sub>CYC6</sub>		100			ns
Data setup time		t <sub>DS6</sub>	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	50			ns
Data hold time		t <sub>DH6</sub>	D <sub>0</sub> to D <sub>15</sub> (D <sub>7</sub> )	0			ns
Access time		t <sub>ACC6</sub>	D <sub>0</sub> to D <sub>7</sub> , C <sub>L</sub> = 100 pF	0		50	ns
Output disable time		t <sub>OH6</sub>	D <sub>0</sub> to D <sub>7</sub> , C <sub>L</sub> = 5 pF, R = 3 kΩ	0		50	ns
Enable H pulse width	Read	t <sub>EWHR</sub>	E	40			ns
	Write	t <sub>EWHW</sub>	E	40			ns
Enable L pulse width	Read	t <sub>EWLR</sub>	E	40			ns
	Write	t <sub>EWLW</sub>	E	40			ns

**Note** The TYP. values are reference values at T<sub>A</sub> = 25°C.

- Cautions**
1. The rise and fall times (t<sub>r</sub> and t<sub>f</sub>) of an input signal are 10 ns or less. If the system cycle time is short, (t<sub>r</sub> + t<sub>f</sub>) ≤ (t<sub>CYC6</sub> – t<sub>EWLW</sub> – t<sub>EWHW</sub>) or (t<sub>r</sub> + t<sub>f</sub>) ≤ (t<sub>CYC6</sub> – t<sub>EWLR</sub> – t<sub>EWHR</sub>).
  2. All timing data is specified at 20% and 80% of V<sub>DD1</sub>.

### (3) Serial interface



( $V_{DD1} = 1.8$  to  $2.5$  V)

Parameter	Symbol	Condition	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
Serial clock cycle	$t_{sCYC}$	SCL	250			ns
SCL high-level pulse width	$t_{sHW}$	SCL	100			ns
SCL low-level pulse width	$t_{sLW}$	SCL	100			ns
Address hold time	$t_{sAH}$	RS	150			ns
Address setup time	$t_{sAS}$	RS	150			ns
Data setup time	$t_{sDS}$	SI	100			ns
Data hold time	$t_{sDH}$	SI	100			ns
CS - SCL time	$t_{cSS}$	/CS1 (CS2 = H)	150			ns
	$t_{cSH}$	/CS1 (CS2 = H)	150			ns

**Note** TYP. values are reference values when  $T_A = 25^\circ\text{C}$ .

( $V_{DD1} = 2.5$  to  $3.6$  V)

Parameter	Symbol	Condition	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
Serial clock cycle	$t_{sCYC}$	SCL	150			ns
SCL high-level pulse width	$t_{sHW}$	SCL	60			ns
SCL low-level pulse width	$t_{sLW}$	SCL	60			ns
Address hold time	$t_{sAH}$	RS	90			ns
Address setup time	$t_{sAS}$	RS	90			ns
Data setup time	$t_{sDS}$	SI	60			ns
Data hold time	$t_{sDH}$	SI	60			ns
CS - SCL time	$t_{cSS}$	/CS1 (CS2 = H)	90			ns
	$t_{cSH}$	/CS1 (CS2 = H)	90			ns

**Note** TYP. values are reference values when  $T_A = 25^\circ\text{C}$ .

**Cautions** 1. The rise and fall times of input signal ( $t_r$  and  $t_f$ ) are rated as 15 ns or less.

2. All timing is rated based on 20% and 80% of  $V_{DD1}$ .

(4) Common

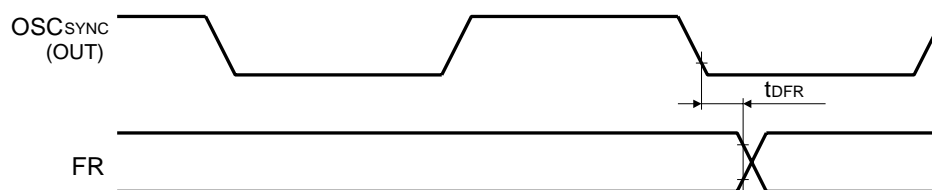
Parameter	Symbol	Conditions	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
Clock input 1	f <sub>M</sub>	OSC <sub>IN1</sub> . External clock is used in main duty display mode, 1/80 duty		85		kHz
Clock input 2	f <sub>S</sub>	OSC <sub>IN2</sub> . External clock is used in sub-duty display mode, 1/40 duty		40		kHz

**Note** The TYP. values are reference value at a frame frequency = 70 Hz.

**Cautions 1.** The rise time and fall time (t<sub>r</sub> and t<sub>f</sub>) of an input signal is 15 ns or less.

**2.** All timing data is specified at 20% and 80% of V<sub>DD1</sub>.

(a) Timing of display control output



(V<sub>DD1</sub> = 1.8 to 2.5 V)

Parameter	Symbol	Conditions	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
FR delay time	t <sub>DFR</sub>	FR, C <sub>L</sub> = 50 pF		50	200	ns

**Note** The TYP. values are reference values at T<sub>A</sub> = 25°C.

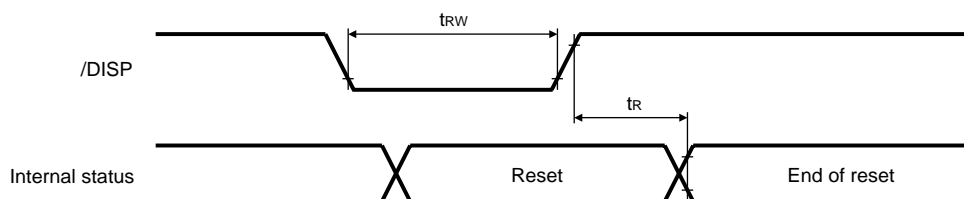
(V<sub>DD1</sub> = 2.5 to 3.6 V)

Parameter	Symbol	Conditions	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
FR delay time	t <sub>DFR</sub>	FR, C <sub>L</sub> = 50 pF		20	80	ns

**Note** The TYP. values are reference values at T<sub>A</sub> = 25°C.

**Caution** All timing data is specified at 20% and 80% of V<sub>DD1</sub>.

(b) Reset timing



( $V_{DD1} = 1.8$  to  $2.5$  V)

Parameter	Symbol	Conditions	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
Reset time	$t_R$				50	$\mu s$
Reset L pulse width	$t_{RW}$	/DISP	50			$\mu s$

**Note** The TYP. values are reference values at  $T_A = 25^\circ C$ .

( $V_{DD1} = 2.5$  to  $3.6$  V)

Parameter	Symbol	Conditions	MIN.	TYP. <sup>Note</sup>	MAX.	Unit
Reset time	$t_R$				50	$\mu s$
Reset L pulse width	$t_{RW}$	/DISP	50			$\mu s$

**Note** The TYP. values are reference values at  $T_A = 25^\circ C$ .

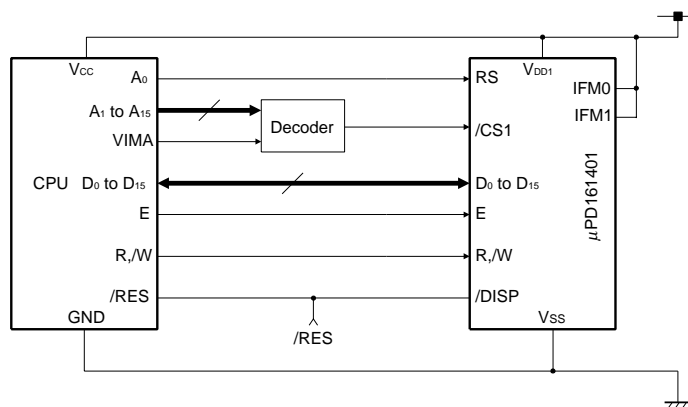
**Caution** All timing data is specified at 20% and 80% of  $V_{DD1}$ .

## 11. CPU INTERFACE (Reference Example)

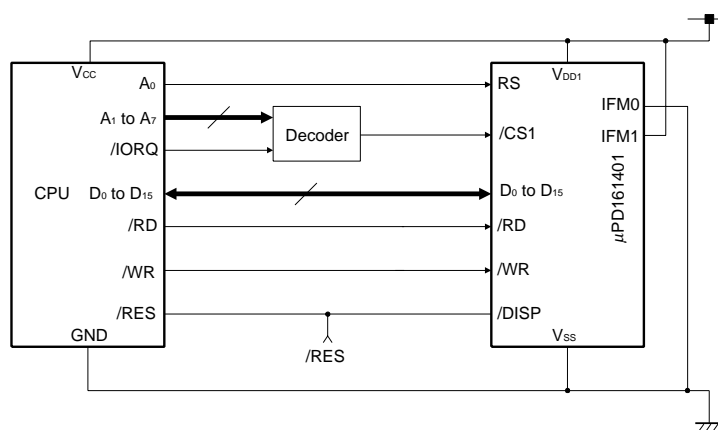
The μPD161401 can be connected to both an i80 system CPU and a M68 system CPU. In addition, the number of signal lines can be reduced by using the serial interface.

The display area can be expanded by using two or more μPD161401 chips. In this case, each IC is selected and accessed by a chip select signal.

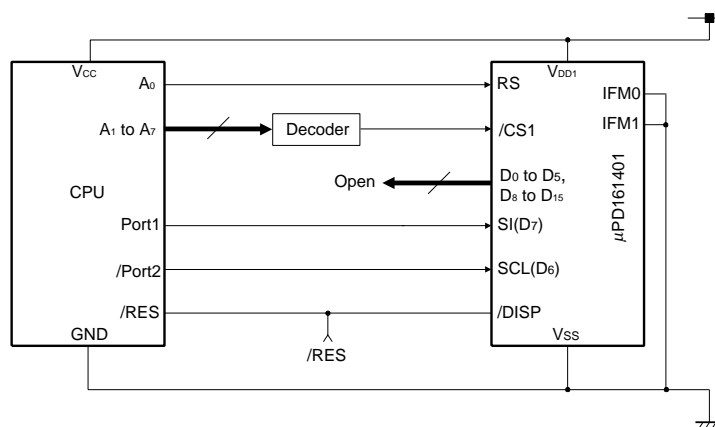
(1) M68 series CPU



(2) i80 series CPU



(3) Serial interface in used





[MEMO]

[MEMO]

**NOTES FOR CMOS DEVICES****① PRECAUTION AGAINST ESD FOR SEMICONDUCTORS**

Note:

Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

**② HANDLING OF UNUSED INPUT PINS FOR CMOS**

Note:

No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to  $V_{DD}$  or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

**③ STATUS BEFORE INITIALIZATION OF MOS DEVICES**

Note:

Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.

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