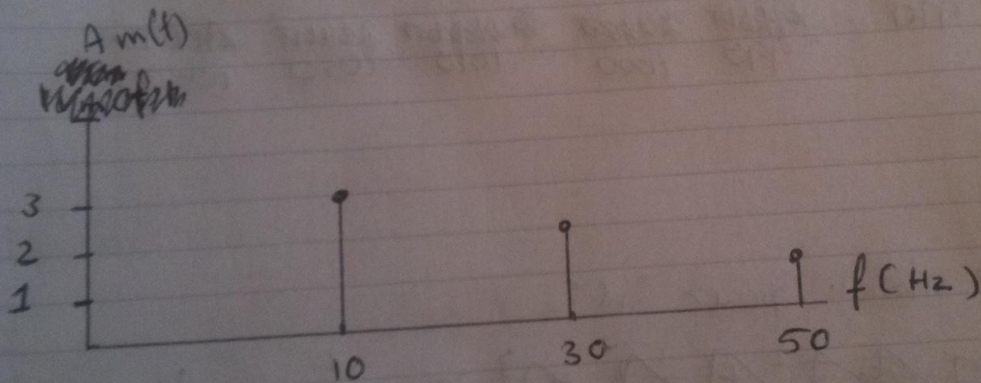


L3)

1)

$$V_m(t) = 3 \cos(20\pi t + \frac{\pi}{4}) + 2 \sin(60\pi t) - \cos(100\pi t)$$

$$V_m(t) = 3 \cos(20\pi t + \frac{\pi}{4}) + 2 \cos(60\pi t - \frac{\pi}{2}) - \cos(100\pi t)$$



2)

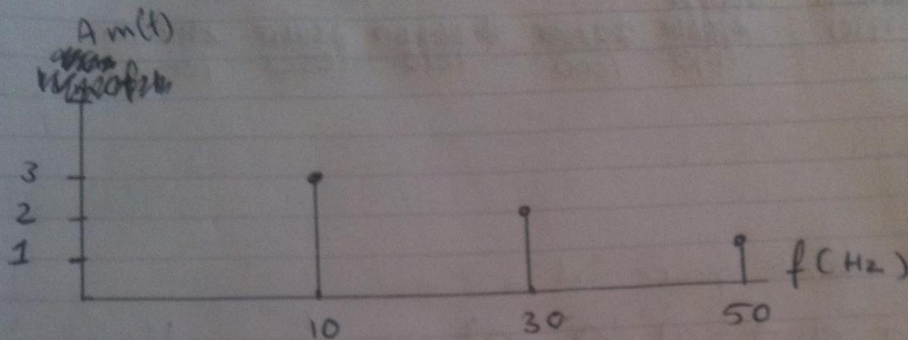
$$V_{am}(t) = (V_c + K_{am} \cdot V_m(t)) \cos(2\pi f_c t)$$

$$V_{am}(t) = \cos(2 \times 10^3 \pi t) + 0.5 \cos(2 \times 10^3 \pi t) V_m(t)$$

$$V_{am}(t) = \cos(2 \times 10^3 \pi t) + \frac{3}{4} \cos(1980 \pi t - \frac{\pi}{4}) + 3 \cos(2020 \pi t + \frac{\pi}{4})$$

*[Handwritten signature]*

$$V_m(t) = 3\cos(20\pi t + \frac{\pi}{4}) + 2\cos(60\pi t - \frac{\pi}{2}) - \cos(100\pi t)$$



2)

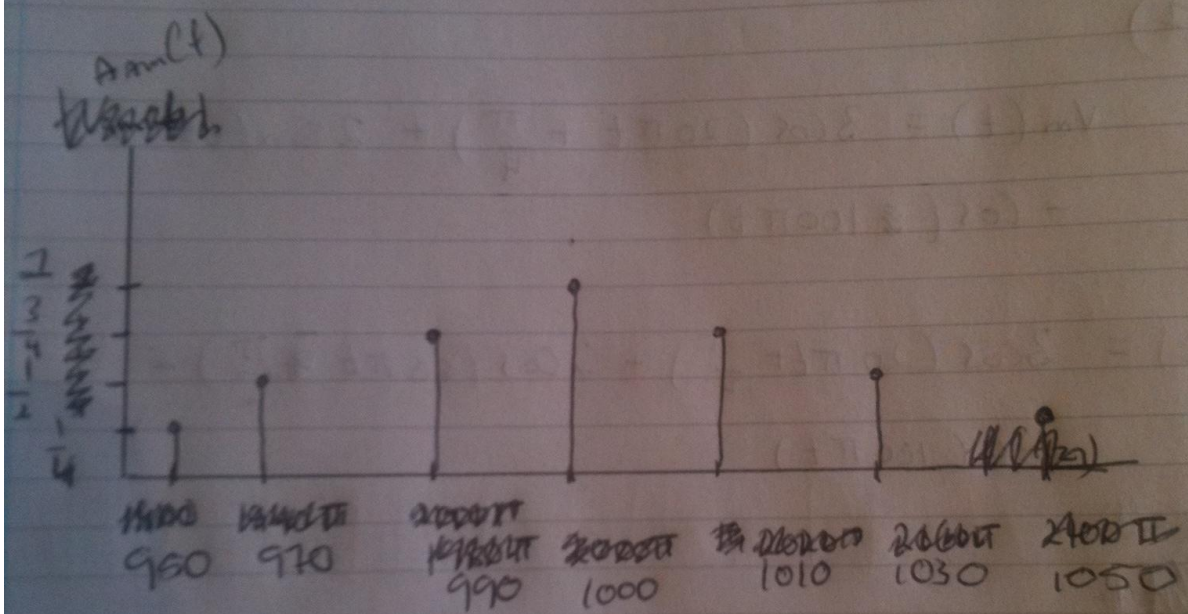
$$V_{am}(t) = (V_c + V_{am} \cdot V_m(t)) \cos(2\pi f_c t)$$

$$V_{am}(t) = \cos(2 \times 10^3 \pi t) + 0.5 \cos(2 \times 10^3 \pi t) V_m(t)$$

$$\begin{aligned} V_{am}(t) = & \cos(2 \times 10^3 \pi t) \\ & + \frac{3}{4} \cos(1980 \pi t - \frac{\pi}{4}) \\ & + \frac{3}{4} \cos(2020 \pi t + \frac{\pi}{4}) \\ & + \frac{1}{2} \cos(1940 \pi t + \frac{\pi}{2}) \\ & + \frac{1}{2} \cos(2060 \pi t - \frac{\pi}{2}) \\ & + -\frac{1}{4} \cos(1900 \pi t) \\ & - \frac{1}{4} \cos(2100 \pi t) \end{aligned}$$

~~scribbles~~



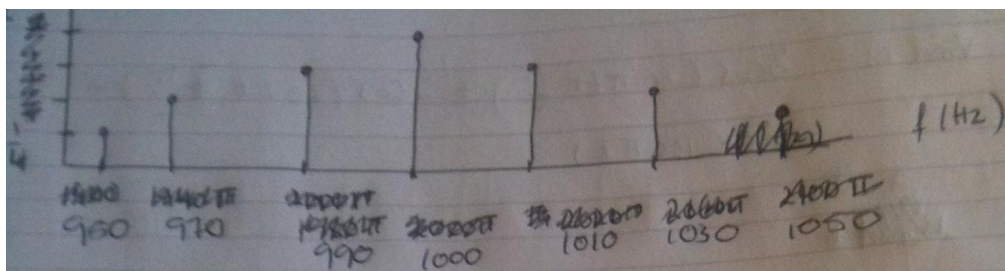


3)

The total power is:

$$P_t = \frac{0.25^2}{2} + \frac{0.5^2}{2} + \frac{0.75^2}{2} + \frac{1^2}{2} = \frac{11}{8}$$

0.75<sup>2</sup>      0.5<sup>2</sup>      0.25<sup>2</sup>



The total power is:

$$P_t = \frac{0.25^2}{2} + \frac{0.5^2}{2} + \frac{0.75^2}{2} + \frac{1^2}{2} + \frac{0.75^2}{2} + \frac{0.5^2}{2} + \frac{0.25^2}{2}$$

$$P_t = \frac{0.25^2}{2} + \frac{0.5^2}{2} + \frac{0.75^2}{2} + \frac{1^2}{2}$$

$$+ \frac{0.75^2}{2} + \frac{0.5^2}{2} + \frac{0.25^2}{2}$$

$$P_t = \frac{43}{32} + \frac{0.25^2}{2} = \frac{11}{8} = 1.375 \text{ Hz}$$

power in side frequencies:

$$P_{SF} = P_t - P_c = 1.375 - \frac{1^2}{2} = \underline{\underline{0.875 \text{ Hz}}}$$

- 4) Since the carrier has only 36.36% of the total power then we know that the message is overmodulated and thus needs coherent detection.



Continued . . .

$$4) \quad V_o(t) = V_{am}(t) - V_c(t)$$

$$V_o(t) = (V_c + V_{am} \cdot V_m(t)) \left[ \frac{1}{2} + \frac{1}{2} \cos(4\pi t_c t) \right]$$

$$V_o(t) = (1 + 0.5 V_m(t)) \left[ \frac{1}{2} + \frac{1}{2} \cos(4 \times 10^3 \pi t) \right]$$

$$V_o(t) = \frac{1}{2} + \frac{1}{2} \cos(4 \times 10^3 \pi t) + \frac{1}{4} V_m(t) \\ + \frac{1}{4} V_m(t) \cos(4 \times 10^3 \pi t)$$

$$V_o(t) =$$

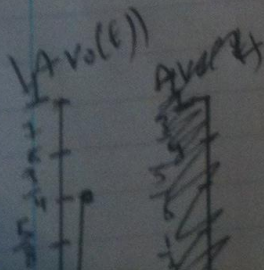
$$\frac{1}{2} + \frac{1}{2} \cos(4 \times 10^3 \pi t) + \frac{3}{4} \cos(20\pi t + \frac{\pi}{4})$$

$$+ \frac{1}{2} \cos(60\pi t - \frac{\pi}{2}) - \frac{1}{4} \cos(100\pi t)$$

$$+ \frac{3}{8} \cos(3980\pi t - \frac{\pi}{4}) + \frac{3}{8} \cos(4020\pi + \frac{\pi}{4})$$

$$+ \frac{1}{4} \cos(3940\pi t + \frac{\pi}{2}) + \frac{1}{4} \cos(4060\pi t - \frac{\pi}{2})$$

$$+ - \frac{1}{8} \cos(3900\pi) - \frac{1}{8} \cos(4100\pi)$$



$$V_o(t) =$$

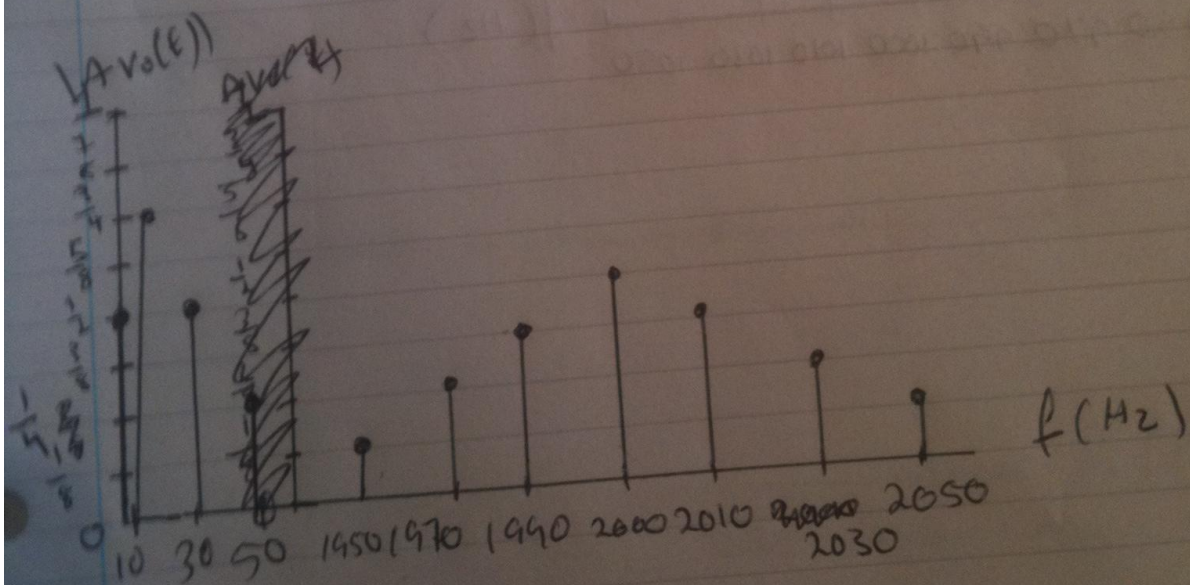
$$\frac{1}{2} + \frac{1}{2} \cos(4 \times 10^3 \pi t) + \frac{3}{4} \cos(20 \pi t + \frac{\pi}{4})$$

$$+ \frac{1}{2} \cos(60 \pi t - \frac{\pi}{2}) - \frac{1}{4} \cos(100 \pi t)$$

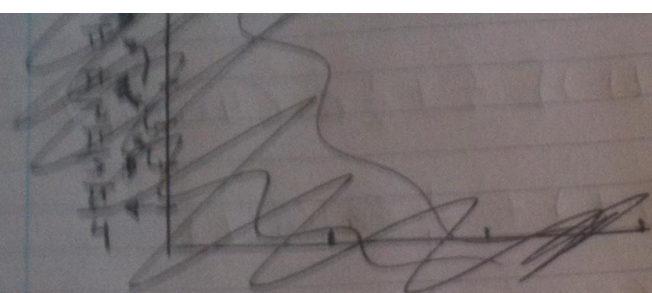
$$+ \frac{3}{8} \cos(3980 \pi t - \frac{\pi}{4}) + \frac{3}{8} \cos(4020 \pi t)$$

$$+ \frac{1}{4} \cos(3940 \pi t + \frac{\pi}{2}) + \frac{1}{4} \cos(4060 \pi t)$$

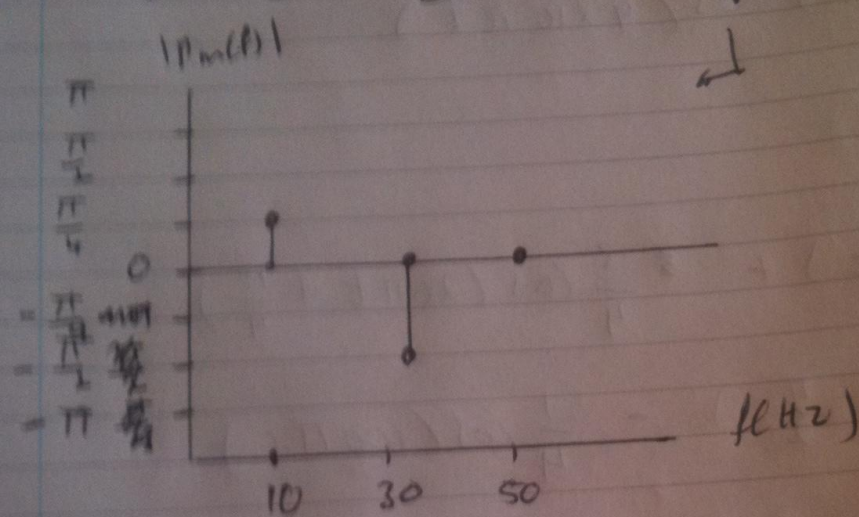
$$+ - \frac{1}{8} \cos(3900 \pi t) - \frac{1}{8} \cos(4100 \pi t)$$



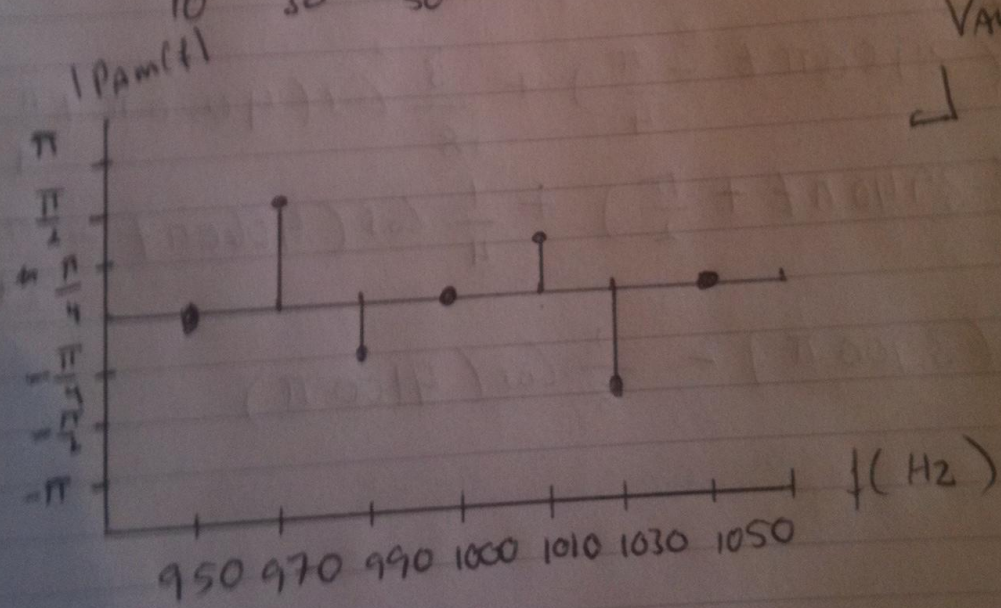




$V_m(t)$



$V_{Am}(t)$



L21)

$$1) \quad V_{m1}(t) = 2 + \sin(40\pi t) + 3 \cos(60\pi t)$$

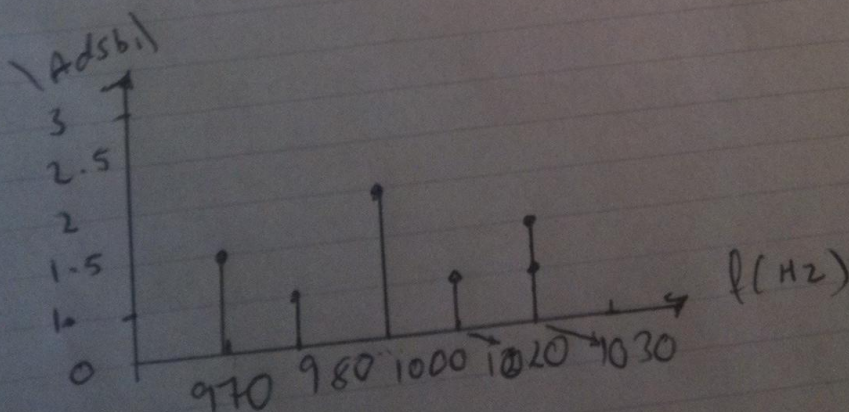
$$V_{m1}(t) = 2 + \cos(40\pi t + \frac{\pi}{2}) + 3 \cos(60\pi t)$$

$$V_{dsb1}(t) = V_{m1}(t) \cdot V_c \cos(2\pi f_c t)$$

$$V_{dsb1}(t) = 2 \cos(2 \times 10^3 \pi t) + \cos(40\pi - \frac{\pi}{2}) \cos(2 \times 10^3 \pi t) \\ + 3 \cos(60\pi t) \cos(2 \times 10^3 \pi t)$$

$$V_{dsb1}(t) = 2 \cos(2 \times 10^3 \pi t) + \cos(1960\pi t + \frac{\pi}{2}) \\ + \cos(2040\pi t - \frac{\pi}{2})$$

$$+ \frac{3}{2} \cos(1940\pi t) + \frac{3}{2} \cos(2060\pi t)$$





$$V_{dsb_1}(t) = 2 \cos(2 \times 10^3 \pi t) + \cos(2040 \pi t - \frac{\pi}{2}) + \frac{3}{2} \cos(1940 \pi t) + \frac{3}{2} \cos(2060 \pi t)$$

