Appendum

for

HM2007 datasheet

Version 1.0

Index

1. Revisions

Date	Site	Description	Initials
27-06-2006	All	First version	KJ
04-07-2006	5	Section 3.1 WLEN = low else the HM2007 will lock in some cases	KJ
04-07-2006	7,8,9	Flow chart updated, in better quality	KJ

2. Scope

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2.1   Purpose

The purpose of this document is to describe and clarify the correct use of HM2007 speech recognition chip in CPU-Mode.

2.2   Introduktion

This document is based on using the Speech recognition kit SR-07 from Images SI Inc in CPU-mode with an ATMega 128 as host controller.
Troubles were identified when using the SR-07 in CPU-mode. Also the HM-2007 booklet (DS-HM2007) has missing/incorrect description of using the HM2007 in CPU-mode.

This appendum is giving our experience in solving the problems when operating the HM2007 in CPU-Mode.

A generic implementation of a HM2007 driver is appended as reference.

3. Hardware

3.1 <u>Starup</u>

Following conditions must be performed before/when power-up of the HM2007:

- Pin CPUM must be logical high (PDIP pin 14, PLCC pin 15), this means select CPU-Mode.
- Pin WLEN must be logical low (PDIP pin 13, PLCC pin 14), this means select 0.92 sec word length. This is very important; else the HM2007 will lock, or give wrong command answer when result data is read.

4. Software

4.1   HM2007 Commands in generel

It seems that it is important to have a delay every time the state of the S-bus is changed. In the JKA-Electronic implementation, a 1 msec delay is used.

4.2   **HM2007 Recognize Command flow**

```
                    ┌──────────┐
                    │  S = 010 │◄──────────┐      S = S3 S2 S1
                    └──────────┘           │
                       │ Y                 │
                       ▼            N       │
                    ◄ ST = 10 ►─────────────┘
                                    ST = ST1 ST0 = K4 K3
                       │
                       ▼
                    ┌──────────┐
                    │  S = 000 │
                    └──────────┘
                       │
                       ▼
                    ┌──────────┐
                    │  S = 100 │
                    └──────────┘
                       │
                       ▼
                    ┌──────────┐
                    │   SEND   │
                    │  RECOG   │   Send 0001 means put data on the K-bus
                    │  (0001)  │
                    └──────────┘
                       │
                       ▼
                    ┌──────────┐
                    │  S = 010 │◄──────────┐
                    └──────────┘           │
                       │ Y                 │
                       ▼            N       │
                    ◄ ST = 01 ►─────────────┘
                       │
                       ▼
              Send another command
```
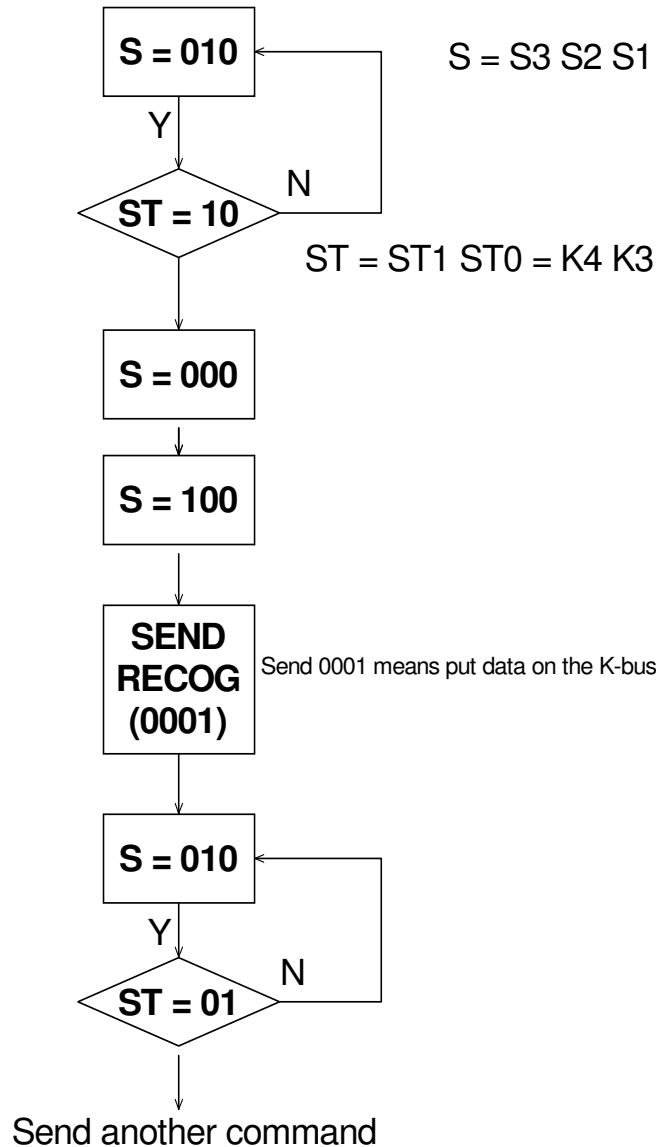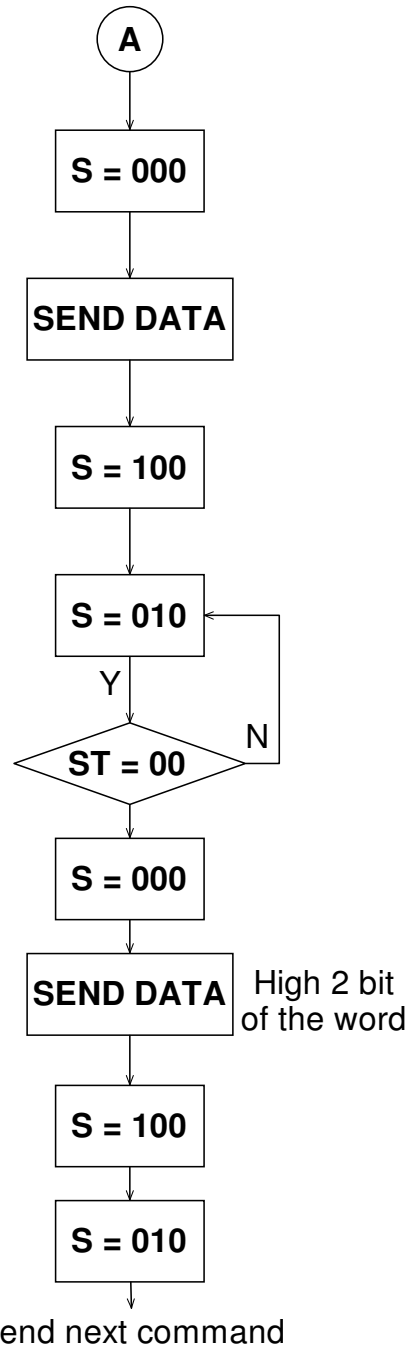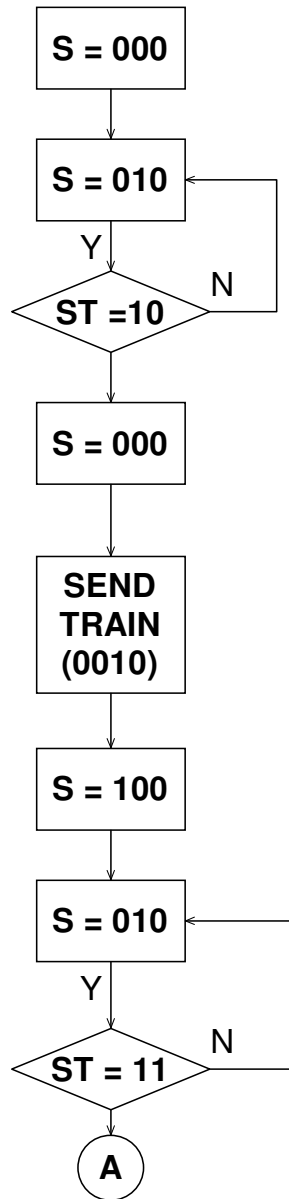
Fig 1. Control flow of the CPU mode for recognition

Above picture shows an updated flow description, of the one from the original HM2007 datasheet.

4.3   HM2007 Train Command flow

```
   ┌──────────┐                          ╭───╮
   │ S = 000  │                          │ A │
   └────┬─────┘                          ╰─┬─╯
        ↓                                  ↓
   ┌──────────┐                       ┌──────────┐
   │ S = 010  │←──┐                   │ S = 000  │
   └────┬─────┘   │                   └────┬─────┘
      Y ↓         │ N                      ↓
      ╱────────╲  │                   ┌──────────┐
     ╱ ST =10   ╲─┘                   │SEND DATA │
     ╲          ╱                     └────┬─────┘
      ╲────────╱                           ↓
        ↓                             ┌──────────┐
   ┌──────────┐                       │ S = 100  │
   │ S = 000  │                       └────┬─────┘
   └────┬─────┘                            ↓
        ↓                             ┌──────────┐
   ┌──────────┐                       │ S = 010  │←──┐
   │  SEND    │                       └────┬─────┘   │
   │  TRAIN   │                          Y ↓         │ N
   │  (0010)  │                          ╱────────╲  │
   └────┬─────┘                         ╱ ST = 00  ╲─┘
        ↓                               ╲          ╱
   ┌──────────┐                          ╲────────╱
   │ S = 100  │                              ↓
   └────┬─────┘                         ┌──────────┐
        ↓                               │ S = 000  │
   ┌──────────┐                         └────┬─────┘
   │ S = 010  │←──┐                          ↓
   └────┬─────┘   │                     ┌──────────┐  High 2 bit
      Y ↓         │ N                   │SEND DATA │  of the word
      ╱────────╲  │                     └────┬─────┘
     ╱ ST = 11  ╲─┘                          ↓
     ╲          ╱                       ┌──────────┐
      ╲────────╱                        │ S = 100  │
        ↓                               └────┬─────┘
      ╭───╮                                  ↓
      │ A │                             ┌──────────┐
      ╰───╯                             │ S = 010  │
                                        └────┬─────┘
                                             ↓
                                    Send next command
```

Above picture shows an updated flow description, of the one from the original HM2007 datasheet.

4.4 **HM2007 Result Command flow**
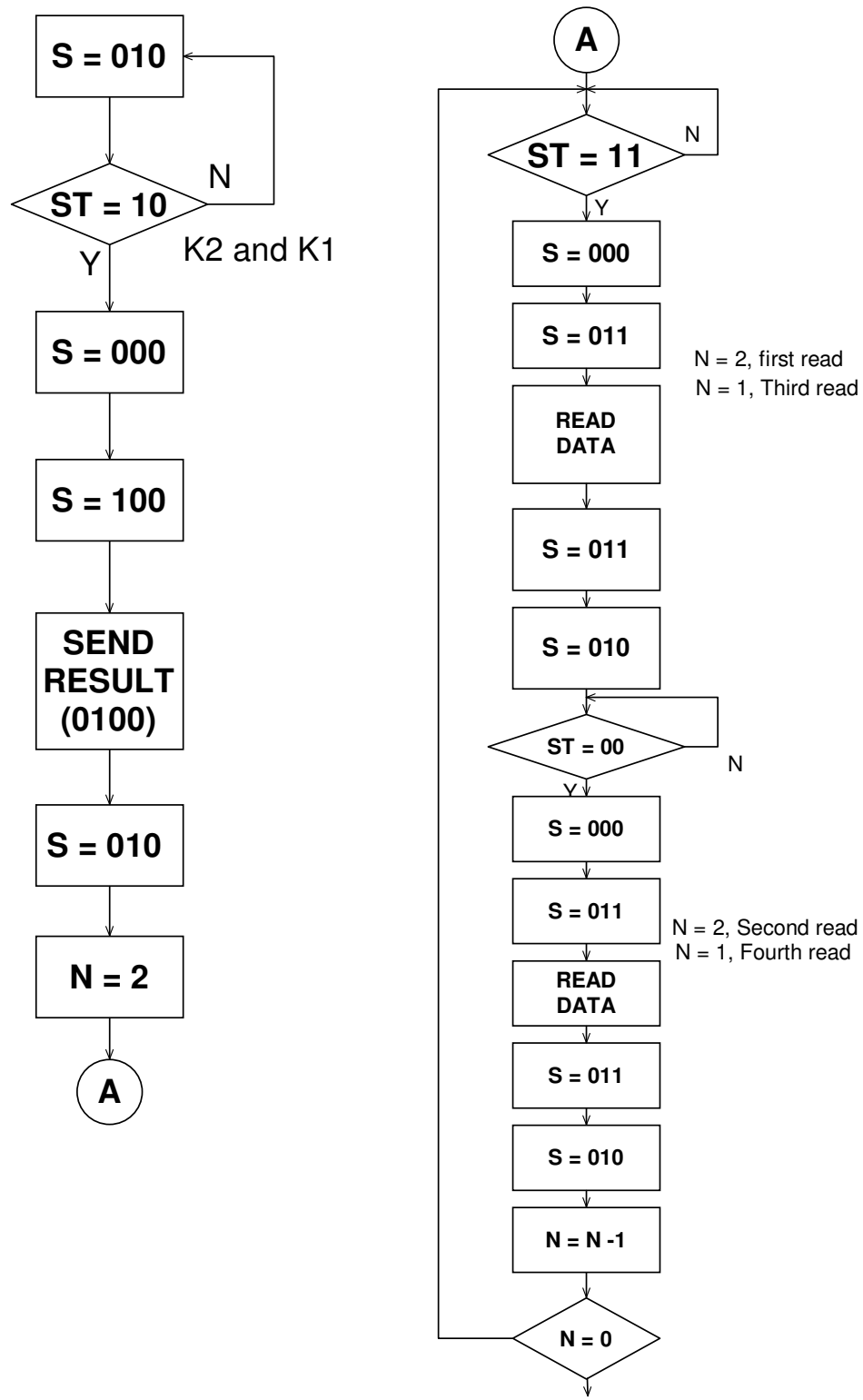
Updated flow chart

S = 010

ST = 10   N

Y   K2 and K1

S = 000

S = 100

SEND
RESULT
(0100)

S = 010

N = 2

A

A

ST = 11   N

Y

S = 000

S = 011

N = 2, first read
N = 1, Third read

READ
DATA

S = 011

S = 010

ST = 00   N

Y

S = 000

S = 011

N = 2, Second read
N = 1, Fourth read

READ
DATA

S = 011

S = 010

N = N -1

N = 0

Send another command

Fig 2. Control flow of the CPU mode for resulting

Above picture shows an updated flow description, of the one from the original HM2007 datasheet. It should be mentioned that when right column of the above shown flow chart is run through the first time, you will get position data, and the next time you run this part through you will get the score data. This information has not been described correctly anywhere in the original datasheet. If above is not followed exactly as described, the HM2007 will lock in the Result state.

4.5 HM2007 Upload Command

The flow for the Upload command is exactly as described in the datasheet, but care must be taken. Do not try to use the Upload command when no data is stored on a specific memory position in the HM2007, then it will lock, and the only way to get in contact with it again, is to recycle the power supply for the circuit.

4.6 HM2007 Download Command

The flow for the Download command is exactly as described in the datasheet.

4.7 HM2007 Reset Command

The flow for the Reset command is exactly as described in the datasheet.